

rydiqule Release 1.2.2

# Quantum Technology Center DEVCOM Army Research Laboratory Naval Air Warfare Center - Weapons Division

**Unclassified - Approved for Public Release** 

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# **GETTING STARTED**

| 1 | Installation                                     | 3    |  |  |
|---|--|------|--|--|
|   | 1.1 Conda installation                           | . 3  |  |  |
|   | 1.2 Pure pip installation                        | . 4  |  |  |
|   | 1.3 Confirm installation                         | . 4  |  |  |
|   | 1.4 Updating an existing installation            | . 4  |  |  |
|   | 1.5 Dependencies                                 | . 5  |  |  |
| 2 | Pydicula Overview                                | 7    |  |  |
| 4 | 2.1 Define the System                            | 8    |  |  |
|   | 2.1 Solve the System                             | . 0  |  |  |
|   | 2.2 Solve the System                             | . 0  |  |  |
|   |  | . 0  |  |  |
| 3 | Introduction to Rydiqule                         | 9    |  |  |
|   | 3.1 Design philosophy                            | . 9  |  |  |
|   | 3.2 Limitations                                  | . 9  |  |  |
|   | 3.3 1. Creating a Sensor object                  | . 10 |  |  |
|   | 3.4 2. Solving a Sensor in the steady-state case | . 13 |  |  |
|   | 3.5 3. Solving in the time domain                | . 1/ |  |  |
|   | 3.6 4. Simulating Doppler broadening             | . 22 |  |  |
|   | 3.7 5. Cell and real atoms                       | . 24 |  |  |
|   | 5.8 Acknowledgments                              | . 21 |  |  |
| 4 | Changelog  | 29   |  |  |
|   | 4.1 v1.2.2                                       | . 29 |  |  |
|   | 4.2 v1.2.1                                       | . 29 |  |  |
|   | 4.3 v1.2.0                                       | . 29 |  |  |
|   | 4.4 v1.1.0                                       | . 30 |  |  |
|   | 4.5 v1.0.0                                       | . 31 |  |  |
|   | 4.6 v1.0.0rc2                                    | . 32 |  |  |
|   | 4.7 v1.0.0rc1                                    | . 32 |  |  |
|   | 4.8 v0.5.0                                       | . 33 |  |  |
|   | 4.9 v0.4.0                                       | . 34 |  |  |
|   | 4.10 v0.3.0                                      | . 35 |  |  |
|   | 4.11 v0.2.0                                      | . 36 |  |  |
|   | 4.12 v0.1.0                                      | . 36 |  |  |
| 5 | Physics Documentation                            | 37   |  |  |
|   | 5.1 Equations of Motion Generation               | . 37 |  |  |
|   | 5.2 Stacking Conventions                         | . 40 |  |  |
|   | 5.3 Observables                                  | . 41 |  |  |
|   | 5.4 Doppler Averaging                            | . 42 |  |  |
|   | 5.5 Time-Dependence                              | . 45 |  |  |
| 6 | API Documenation 51                              |      |  |  |
| - | 6.1 rydiqule                                     | . 51 |  |  |

| 7    | <b>Deve</b><br>7.1<br>7.2<br>7.3<br>7.4                     | loper Documentation         Unit Tests         Type Hinting         Linting         Building the Documentation                                     | <b>147</b><br>147<br>148<br>149<br>149        |  |  |  |  |
|------|---|--|---|--|--|--|--|
| 8    | <b>3-pho</b><br>8.1<br>8.2<br>8.3                           | oton Rydberg EIT         Doppler-free, 3 photon excitation         Colinear 3-photon Excitation with Doppler Averaging         Doppler-Free Angles | <b>151</b><br>151<br>152<br>154               |  |  |  |  |
| 9    | <b>Calcu</b><br>9.1<br>9.2                                  | ulating SNR1D Optimum2D Optimum - Fnd Optimized $\Omega_p$ and $\Omega_c$ for best SNR   | <b>157</b><br>158<br>160                      |  |  |  |  |
| 10   | <b>RF h</b><br>10.1<br>10.2<br>10.3                         | eterodyne with Doppler Example         Imports         Define the Sensors         Observe a heterodyne beat between the Signal and LO.             | <b>163</b><br>163<br>163<br>164               |  |  |  |  |
| 11   | <b>RF h</b><br>11.1<br>11.2<br>11.3<br>11.4<br>11.5<br>11.6 | Imports  | <b>171</b><br>171<br>175<br>176<br>178<br>179 |  |  |  |  |
| Py   | Python Module Index   |  |   |  |  |  |  |
| 1110 | uCX   |  | 102   |  |  |  |  |



A python library for calculating Rydberg electrometer response to arbitrary RF fields in steady-state or time domains. It is a general density matrix-based master equation solver, optimized for speed to solve problems with large parameter spaces while maintaining flexibility to define novel problems. It leverages a graph-based system definition, computationally-efficient equation "stacking" in the form of tensors, and external computational libraries such as numpy, scipy, and ARC.

For more details, see the Rydiqule Overview.

For detailed usage examples, see the Introduction to Rydiqule Jupyter notebook.

If you use rydiqule in your work, please cite as

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# INSTALLATION

Installation is done via pip or conda. See below for detailed instructions.

In all cases, it is highly recommended to install rydiqule in a virtual environment.

## 1.1 Conda installation

Installation via conda is recommended for rydiqule. It handles dependency installation as well as a virtual environment to ensure packages do not conflict with other usages on the same system. Finally, the numpy provided by anaconda has been compiled against optimized BLAS/LAPACK implementations, which results in much better performance in rydiqule itself.

Assuming you have not already created a separate environment for RydIQule (recommended), run the following to create a new environment:

```
(base) ~/> conda create -n rydiqule python=3.11
(base) ~/> conda activate rydiqule
```

RydIQule currently requires python >3.8. For a new installation, it is recommended to use the newest supported python.

Now install via rydiqule's anaconda channel. This channel provides rydiqule as well as its dependencies that are not available in the default anaconda channel. If one of these dependencies is outdated, please raise an issue with the vendoring repository.

(rydiqule) ~/> conda install -c rydiqule rydiqule

If you would like to install rydiqule in editable mode to locally modify its source, this must be done using pip. Follow the above to install rydiqule and its dependencies, then run the following to uninstall rydiqule as provided by conda and install the editable local repository.

```
(rydiqule) ~/> conda remove rydiqule --force
# following must be run from root of local repository
(rydiqule) ~/> pip install -e .
```

Note that editable installations require git. This can be provided by a system-wide installation or via conda in the virtual environment (conda install git).

**Note:** While rydiqule is a pure python package (ie it is platform independent), its core dependency ARC is not. If a pre-built package of ARC is not available for your platform in our anaconda channel, you will need to install ARC via pip to build it locally before installing rydiqule. To see what architectures are supported, please see the vendoring repository.

## 1.2 Pure pip installation

To install normally, run:

pip install rydiqule

This command will use pip to install all necessary dependencies.

To install in an editable way (which allows edits of the source code), run the following from the root directory of the cloned repository:

pip install -e .

Editable installtion requires git to be installed.

# **1.3 Confirm installation**

Proper installation can be confirmed by executing the following commands in a python terminal.

```
>>> import rydiqule as rq
>>> rq.about()
       Rydiqule
    _____
Rydiqule Version:
                    1.1.0
Installation Path: ~\Miniconda3\envs\rydiqule\lib\site-packages\rydiqule
     Dependencies
    _____
NumPy Version: 1.24.3
SciPy Version: 1.10.1
Matplotlib Version: 3.7.1
ARC Version: 3.3.0
Python Version: 3.9.1
                    3.9.16
Python Install Path: ~\Miniconda3\envs\rydiqule
Platform Info: Windows (AMD64)
CPU Count:
                     12
Total System Memory: 128 GB
```

# 1.4 Updating an existing installation

Upgrading an existing installation is simple. Simply run the appropriate upgrade command for the installation method used.

For conda installations, run the following command to upgrade rydiqule

conda upgrad rydiqule

For pip, you can use the same installation command to upgrade. Optionally, include the update flag to greedily update dependencies as well.

pip install -U rydiqule

This command will also install any new dependencies that are required.

If using an editable install, simply replacing the files in the same directory is sufficient. Though it is recommended to also run the appropriate pip update command as well to capture updated depedencies.

pip install -U -e .

## **1.5 Dependencies**

This package requires installation of the excellent ARC package, which is used to get Rydberg atomic properties. It also requires other standard computation dependencies, such as numpy, scipy, matplotlib, etc. These will be automatically installed if not already present.

**Note:** Rydiqule's performance does depend on these depedencies. In particular, numpy can be compiled with a variety of backends that implements BLAS and LAPACK routines that can have different performance for different computer architectures. When using Windows, it is recommended to install numpy from conda, which is built against the IntelMKL and has generally shown the best performance for Intel-based PCs.

Optional timesolver backend dependencies include the numbakit-ode and CyRK packages. Both are available via pip. They can be installed automatically via the optional extras specification for the pip command.

pip install rydiqule[backends]

For conda installations, these dependencies must be installed manually

conda install -c rydiqule CyRK numbakit-ode

# **RYDIQULE OVERVIEW**

Rydiqule (RYDberg sensing Interactive Quantum ModULE) is a python module that can calculate response of a Rydberg sensor to RF fields. It uses a semi-classical approximation of the Schroedinger equation known as the Lindblad equation to create equations of motion that describe the interaction of the sensor with optical and RF fields.

In order to use rydiqule at its basic level, you need to understand a few core elements. These elements are shown in Fig. 2.1.



Fig. 2.1: The basic organizational structure for using Rydiqule.

A calculation needs three general components.

- 1. Define the system to be solved.
- 2. Solve the system.
- 3. Interpret the results to observable quantities.

# 2.1 Define the System

A system can be defined using one of two classes: *Sensor* or *Cell*. In either case, multiple values for a parameter can be set to produce parameter scans in the solve stage. The Sensor class defines the bare minimum of information necessary to produce a system of equations to solve. This class allows for arbitrary definitions of the system. The Cell class defines a physical gas of atoms for the system that in turn produces a Sensor for doing calculations. This class relies on ARC to provide physical parameters.

# 2.2 Solve the System

We currently have two solvers implemented.

- 1. A steady state solver (*solve\_steady\_state()*) that finds the steady state density matrix of the system. This can solve in a few different conditions:
  - 1. Optically-thin, cold ensemble
  - 2. Optically-thin, doppler-averaged ensemble
- 2. A time solver (*solve\_time()*) that allows for fields to be defined arbitrarily in time.

Each solver takes a Sensor or Cell object and solves the system. The output is the corresponding density matrix in the steady-state, spanning the defined parameter space, or a series of density matrices versus time in the case of the time solver.

# 2.3 Interpret the Results

Once the solutions are made, we need to interpret the density matrices into observable values, typically some change to the optical probing field. We implement a few functions to get the *susceptibility*, *probe absorption*, and *probe phase shift*. Note that getting these values generally requires more information about the system than the bare minimum required to solve them. *Raw density matrix elements* can also be obtained.



# INTRODUCTION TO RYDIQULE

**RydIQule**, the Rydberg Interactive Quantum Module, is a python library built to simulate the interaction of Rydberg atoms and light using a semi-classical approach. This notebook will illustrate some of its core functionality, and demonstrate how to use the tool to model simple systems. The intent here is not to demonstrate discoveries in physics. Rather it will use cartoonish but nontrivial examples to demonstrate how to use the module.

# 3.1 Design philosophy

Rydiqule was built with a few core principles in mind:

- 1. **Rydiqule is simple** Setting and solving an atomic system can be done with just a handful of lines of code while behaving in an intuitive way.
- 2. **Rydiqule is fast** Under the hood, the library makes broad use of fast numpy matrix braodcasting and compiled code in places that would be slowed down by native python. The result is a toolbox that can produce meaningful results in a few minutes or less.
- 3. **Rydiqule is flexible** Rydiqule can model a huge variety of semiclassical Rydberg atomic systems with no code modification. For users with more particular modelling needs who wish to extend Rydiqule, the Sensor class provides a minimal physical system that can easily be inherited and overloaded for more involved experimental setups.

# 3.2 Limitations

While we have worked hard to make Rydiqule as good as possible, there are some areas that can cause issues:

- 1. **Memory** For systems with many laser parameter values, many levels, doppler averaging in several dimensions, or especially a combination of these, the equations of motion generated by rydiqule simply have to be very large, often requiring more memory than is in a typical laptop or simple desktop. For very large systems, the memory footprint may even outpace a powerful workstation. Rydiqule has built-in functionality to handle some of these cases, but it is far from perfect and will need to be iteratated upon to be as flexible as possible.
- 2. **Speed** While huge improvements have been made in the speed of rydiqule, there are certain situations that can still cause some slowdowns. For longer simulations, in particular for the poorly-conditioned equations produced with large doppler width, solving can still be slow.
- 3. **Quantum Back-action** We treat the optical fields as static, and do not include them explicitly in the semi-classical equations of motion. Rydiqule does not account for atom-field back-action effects. This approximation is valid for low optical depth samples, and is known to give valid results for SNR in moderate optical depth samples. However, for quantitative analysis of quantum noise in high optical depth samples, Rydiqule may not be accurate.
- 4. **Device Modelling** Rydiqule is a physics solver, and does not currently have user-friendly support for device-level modelling.

#### 3.2.1 Imports

Rydiqule is conventionally imported as rq. In addition, numpy and matplotlib are useful to have in notebooks, so we will import them as well. They are dependencies of rydiqule, so they should already be installed if you installed rydiqule.

```
#Auto-reload code for fast testing
%load_ext autoreload
%autoreload 2
%matplotlib inline
```

```
import rydiqule as rq
import numpy as np
import matplotlib.pyplot as plt
```

## 3.3 1. Creating a Sensor object

The Sensor is the core object of rydiqule. It defines an atomic system, and while you can create an solve a Hamiltonian manually, the Sensor takes care of the bookeeping to generate Hamiltonian and solve its associated equations of motion. The base Sensor class is constructed with a single required argument, the basis size. Here we create a 3-level system. On its own, a Sensor contains no information about atomic structure; it is an abstraction that allows for a high degree of manual configuration.

```
basis_size = 3
sensor = rq.Sensor(basis_size)
```

#### 3.3.1 Defining a simple Ladder system

This demonstrates how a minimal ladder system would be defined in rydiqule. States are coupled by defining dictionaries which have one key-value pair describing the basis states which are coupled as a tuple with two integer elements. For applied laser fields under the rotating wave approximation, you must also specify a rabi frequency and detuning. They are then added using the add\_couplings() function with as many couplings as you'd like. All frequency values are in megarad/s.

### Notes on detunings and rotating wave transformation

For defining detunings, the states in a coupling are always defined to go from lower to higher energy. For example, (1, 2) means state 2 is higher than 1. Any coupling with a defined detuning will be treated in the rotating frame of the coupling.

```
laser_01 = {"states": (0,1), "detuning": 1, "rabi_frequency": 3}
laser_12 = {"states": (1,2), "detuning": 2, "rabi_frequency": 5}
sensor.add_couplings(laser_01, laser_12)
```

Once the system is defined, we can see the Hamiltonian matrix. You usually will not need to call this explicitly (it will be called internally by a solver), but it can be useful to make sure the system is defined as expected.

```
print(sensor.get_hamiltonian())
```

```
[[ 0. +0.j 1.5+0.j 0. +0.j]
[ 1.5-0.j -1. +0.j 2.5+0.j]
[ 0. +0.j 2.5-0.j -3. +0.j]]
```

### 3.3.2 Defining a simple V scheme

We can do something similar, but with a different arrangement of couplings. We can also pass fields in the constructor if we like

```
laser_01 = {"states": (0,1), "detuning": 1, "rabi_frequency": 3}
laser_02 = {"states": (0,2), "detuning": 2, "rabi_frequency": 5}
sensor_v = rq.Sensor(3, laser_01, laser_02)
print(sensor_v.get_hamiltonian())
```

```
[[ 0. +0.j 1.5+0.j 2.5+0.j]
[ 1.5-0.j -1. +0.j 0. +0.j]
[ 2.5-0.j 0. +0.j -2. +0.j]]
```

### 3.3.3 Defining a simple Lambda scheme

Here is another system, this time a lambda scheme.

```
laser_02 = {"states": (0,2), "detuning": 1, "rabi_frequency": 3}
laser_21 = {"states": (2,1), "detuning": 2, "rabi_frequency": 5}
sensor_lambda = rq.Sensor(3, laser_02, laser_21)
```

print(sensor\_lambda.get\_hamiltonian())

[[ 0. +0.j 0. +0.j 1.5+0.j] [ 0. +0.j -3. +0.j 2.5-0.j] [ 1.5-0.j 2.5+0.j -1. +0.j]]

Before we proceed further, we will make a quick note of what is happening under the hood. rydiqule is storing all of the information we specified when we added couplings on an object called a graph from the networkx library (https://networkx.org/). We treat the nodes of this graph as states and the edges as couplings. Internally, the graph is called couplings. It is not important to understand networkx to use rydiqule, but let's have a look at this Sensor. couplings attribute to hopefully help make it a little more transparent.

```
print(sensor_lambda.couplings.nodes)
print(sensor_lambda.couplings.edges(data=True))
```

The edges contain all of the data that we have added! Again, this is not crucial, but if you are interested in how data is stored, this is a useful demo.

### 3.3.4 Systems that are not fully coupled

We can also define a system in which not all states are connected explicitly by couplings. This allows us to solve systems which, for example, have states coupled only by decoherence. This exact use case will be demonstrated later, but we can set up the system and show the hamiltonian here.

The hamiltonaian works by treating an uncoupled states as a "second ground state", and calculates digonal hamiltonian elements from there. We show a 4-level system in which state 4 is coupled to state 5 via a steady state rf transition, but to no other states. It should be noted that calling an rf transition does not change the way the system is solved here.

Looking at the hamiltonian, we can see that the 4th term along the diagonal is 0, and the 5th term counts from there.

sensor\_uncoupled = rq.Sensor(5)
laser\_01 = {"states": (0,1), "detuning": 1, "rabi\_frequency": 3}
laser\_12 = {"states": (1,2), "detuning": 2, "rabi\_frequency": 5}
rf = {"states": (3,4), "detuning": 8, "rabi\_frequency": 1}
sensor\_uncoupled.add\_couplings(laser\_01, laser\_12, rf)

print(sensor\_uncoupled.get\_hamiltonian())

[[ 0. +0.j 1.5+0.j 0. +0.j 0. +0.j 0. +0.j] [ 1.5-0.j -1. +0.j 2.5+0.j 0. +0.j 0. +0.j] [ 0. +0.j 2.5-0.j -3. +0.j 0. +0.j 0. +0.j] [ 0. +0.j 0. +0.j 0. +0.j 0. +0.j 0.5+0.j] [ 0. +0.j 0. +0.j 0. +0.j 0.5-0.j -8. +0.j]]

In some more complicated cases, we may want a more concrete visual reassurance that everything is defined correctly. rydiqule makes use of the atomic\_energy\_diagram library to help draw visual representations of a Sensor. In the drawing below, we can see that the diagram indeed shows that states 2 and 3 are not coupled.



## 3.4 2. Solving a Sensor in the steady-state case

So far we have just created sensor objects and shown their corresponding Hamiltonians. The most important functionality of rydiqule, however, is solving their associated equations of motion automatically. Here we will demonstrate some of the ways to solve a simple system using rydiqule.

#### 3.4.1 Basic Solving in the steady state

If all we need steady state behavior of a particular system, it is straightforward and quick in rydiqule. By wrapping a simple matrix differential equation solver, we can quickly get the steady state frequencies of each element of the density matrix  $\rho$  of the system. We start by re-defining the same ladder system we had at the beginning of the notebook.

```
basis_size = 3
sensor = rq.Sensor(basis_size)
laser_01 = {"states": (0,1), "detuning": 1, "rabi_frequency": 3}
laser_12 = {"states": (1,2), "detuning": 2, "rabi_frequency": 5}
sensor.add_couplings(laser_01, laser_12)
```

#### Gamma matrix

However, before we solve the system, we must define the decoherence and dephasing rates of the system, which is defined by the gamma\_matrix. This is square matrix whose dimensionality matches that of the system Hamiltonian. Diagonal terms of this matrix represent represent dephasing rates for each state, while off-diagonal terms represent the rate of spontaneous population decay between states. Just like with the rest of rydiqule, the units are in Mrad/s.

This step is crucial. Without a gamma matrix (or with a matrix of all zeros), the equations of motion will be singular, and the system will not have a well-defined steady-state solution.

The gamma matrix is a matrix where each element  $\Gamma_{ij}$  defines the incoherent decay rate of atomic population from state *i* to state *j*. Diagonal elements  $\Gamma_{ii}$  represent incoherend dephasing from state *i*. More details may be found in Appendix A of https://arxiv.org/abs/2105.10494

```
gamma = np.zeros((basis_size, basis_size))
gamma[1,0] = 0.1
sensor.set_gamma_matrix(gamma)
```

Instead of creating the entire gamma matrix and adding all at once, you can also add individual decoherences using the add\_decoherence method of Sensor as well as the related, specialized helper methods add\_self\_broad-ening and add\_transit\_broadening.

Here is the equivalent method of defining the gamma matrix for the system using these methods.

```
sensor.add_decoherence((1,0), 0.1)
```

Now, instead of showing the Hamiltonian, we can just call rydiqule.solve\_steady\_state() function on sensor and get the result.

```
solution = rq.solve_steady_state(sensor)
print(type(solution))
```

```
<class 'rydiqule.sensor_solution.Solution'>
```

As you can see, the solution itself is not an array, but rather a rydiqule.Solution object. This is a bunch-type object that functions just like a python dictionary from which you access values as class variables instead of the usual d[key] syntax. This makes accessing elements a little cleaner. Here we can see that accessing with the usual dictionary key syntax or as a class variable. As you can see below, they are the same.

```
print(solution.rho)
print(solution["rho"])
```

```
[-0.17354416 -0.24474176 0.00800973 0.24029191 0.20024326 0.00667478

0. 0.22694236]

[-0.17354416 -0.24474176 0.00800973 0.24029191 0.20024326 0.00667478

0. 0.22694236]
```

#### Adjustments to the equations

So why does the solution have 8 elements? Why is it real? It represents a density matrix, which should have  $n^2$  complex-valued elements ( $3^2 = 9$  in this case).

For numerical stability, rydiqule removes the ground state population equations, so the  $\rho_{00}$  term is omitted from the solution (typically  $\rho_{00} >> \rho_{ij}$  for  $ij \neq 00$ , which is the source of the numerical problems). If needed, it can be inferred as  $\rho_{00} = 1 - \sum_{i=1}^{n} \rho_{ii}$ . Furthermore, rydiqule transforms the basis so that all values are real. Rather than an  $n \times n$  Hermitian matrix, rydiqule parameterizes the density matrix  $\rho$  as  $n \times n$  real values before removing the ground state. For more details, refer to the documentation of the get\_basis\_transformation() function in the sensor\_utils module.

So how do we know (ideally quickly) which element of the solution corresponds to which density matrix element? The Sensor class contains a function called basis() which does exactly this, returning a list of strings showing the info we want. Since the density matrix is hermitian and trace 1, this array does indeed contain all of the information of the density matrix. Note that basis() does not include  $\rho_{00}$  since the ground state is removed by the solver (see docs)

*Note*: there are technically arguments to disable this and solve the full complex equations, but they are intended for internal use only, and almost certainly will not work for a general system. We recommend keeping these values at their defaults.

#### 3.4.2 Solving for multiple values of a parameter

Getting a single result is nice, but really just a single data point. One of the simplest types of experiments you might want to simulate is to scan, for example, over a range of detuning values and see the behavior of the system at each value. Fortunately, rydiqule makes this type of experiment trivial. Suppose we wanted to sweep our probe laser detuning between -10 MHz and 10 MHz. Without rydiqule we might write an explicit loop over a set of values, modifying and solving the system at each iteration, and storing the results in a new list. In python especially, this sort of approach has a high computational overhead. With rydiqule, We can set up the system similarly to above, this time as a 4-level system. However, this time, instead of using a single float value for a coupling parameter, we will define the  $0 \leftrightarrow 1$  coupling detunuing value as a list-like object, in our case a 1-dimensional numpy array constructed with the linspace function.

```
basis_size = 4
sensor_sweep = rq.Sensor(basis_size)

detunings = 2*np.pi*np.linspace(-10,10,201) #201 values between -10 and 10 MHz
probe = {"states":(0,1), "detuning": detunings, "rabi_frequency": 3}
coupling = {"states":(1,2), "detuning": 0, "rabi_frequency": 5}
rf = {"states":(2,3), "detuning": 0, "rabi_frequency":7}
```

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```
sensor_sweep.add_couplings(probe, coupling, rf)
sensor_sweep.add_decoherence((1,0), 0.1)
sensor_sweep.add_decoherence((2,1), 0.1)
sensor_sweep.add_decoherence((3,0), 0.1)
```

From here, we solve exactly as before. Rydiqule will automagically solve the system for every detuning value (very quickly). We also show the utility function get\_rho\_ij() which extracts  $\rho_{ij}$  from the density matrix  $\rho$  of any solution (regardless of how many dimensions it is). We use it to get  $\rho_{01}$ .

```
solution = rq.solve_steady_state(sensor_sweep)
print(f"Solution shape: {solution.rho.shape}")
absorption = rq.get_rho_ij(solution.rho,0,1).imag
print(f"Absorption_shape: {absorption.shape}")
```

```
Solution shape: (201, 15)
Absorption_shape: (201,)
```

We can see that there is a 15-element solution for each one of the detuning values. After we get the absorption using get\_rho\_ij(), we can see that we are left with a single array with 201 elements, corresponding to to the absorption at each value of detuning. The function doesn't do anything special, it just is a quick way to get common info you might want out of a solution. We can now do a quick-and-dirty plot to see what it looks like:

```
plt.plot(detunings/2/np.pi, absorption);
```



#### 3.4.3 Solving for multiple values of multiple parameters

If you like the simplicity of scanning an single laser detuning in rydiqule you will be even more excited to learn that rydiqule can handle scans over multple different parameters simulataneously. We will set up the sensor as before, with a couple of changes. We will now also scan the dephasing rate and show how the absorption changes.

Once again, no extra steps are required, just call <code>solve\_steady\_state()</code> as normal, and look at the shape of the solution and the absorption and rydiqule will quickly find the solution for every combination of those 2 parameters.

```
solution_2 = rq.solve_steady_state(sensor_sweep_2)
print(f"Solution shape: {solution_2.rho.shape}")
absorption_2 = rq.get_rho_ij(solution_2.rho,0,1).imag
print(f"Absorption_shape: {absorption_2.shape}")
```

```
Solution shape: (201, 10, 15)
Absorption_shape: (201, 10)
```

How do we know which axis corresponds to the probe detuning and which is the coupling detuning? Sensor has a method called axis\_labels() which does just that, and this is where labeling our couplings comes in handy. Note that if couplings are not labeled, the axes will default to being labeled by the states they couple. For example  $["(0,1)_detuning", (1,2)_detuning"]$ .

This function will not label the axes for the density matrix, or the time or doppler axes (discussed later), since it is just a method of Sensor. The density matrix will always be last, time second to last (if solved in the time domain), and the axes for *n* dimensions of doppler solveing will be the first *n* axes.

```
print(sensor_sweep_2.axis_labels())
```

```
['probe_detuning', '(1,0)_gamma']
```

So the first axis corresponds to the probe laser detuning, and the second axis corresponds to  $\Gamma_{1,0}$ . Now calling a function like np.argmin() or np.argmax() could quickly be used to optimize some value over a large parameter space. rydiqule lets us add as many parameters as you like as a list, detunings, rabi frequencies, or dephasings. It's handy, but beware that the memory footprint can quickly balloon out of control when generating equations of motion if you get too ambitious, increasing by a factor of n when you add an axis with n elements, especially given that many values used in internal calculations are 128-bit complex arrays. Currently, rydiqule has internal functions to spot this before it happens and break it into more manageable chunks if it can, but it is certainly possible to make a system which even it cannot handle. If the solution does not fit in memory, no amount of splitting up the equations will allow the system to be solved, and you should reconsider the size of your parameter space. Even in the above example, rydiqule is solving  $201 \times 10 \times 15 \approx 30000$  equations simultaneously.

We can plot these probe sweeps at the same time fairly simply.





# 3.5 3. Solving in the time domain

Suppose you have defined a sensor, and we want to see the response of the sensor of some well-defined rf input function. In this case, the steady-state solution above is not enough. We will set up a sensor similar to the one above, but define the rf field differently. We will use the "time\_dependence" keyword in the dictionary, and supply with a function which takes a single argument of time in microseconds. First we will define a function below, which turns on a static field at  $t = 1 \mu s$ .

```
def turn_on_field(t):
    if t < 1:
        return 0.0
    else:
        return 1.0</pre>
```

rydiqule treats time dependent functions as a modulation of the rabi frequency at time t. So if we define the field we apply this function to as having a rabi frequency of 7 Mrad/s as above, the field will turn on with a rabi frequency of 7 Mrad/s at t = 1. Note that because we are still specifying a detuning, the field is still treated as being in the rotating frame.

Note: Specifying time dependence means you can no longer call <code>solve\_steady\_state()</code>

```
basis_size = 4
sensor_time = rq.Sensor(basis_size)
```

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```
probe = {"states":(0,1), "detuning": 2, "rabi_frequency": 3, "label":"probe"}
coupling = {"states":(1,2), "detuning": 2, "rabi_frequency": 5, "label": "coupling
or "}
rf = {"states":(2,3), "detuning": 0, "rabi_frequency":7, "label": "rf", "time_
or dependence":turn_on_field}
sensor_time.add_couplings(probe, coupling, rf)
gamma = np.zeros((basis_size, basis_size))
gamma[1:,0] = 0.1
sensor_time.set_gamma_matrix(gamma)
```

With everything set up, we now call the rq.solve\_time() function, which behaves as you might expect. The only difference is that you need a couple of extra arguments: - end\_time, specifying the length of the simulation time in microseconds. - num\_pts, which specifies the number of points on the time interval  $(0, t_{end})$  at which to sample the solution evenly.

In addition, the function can take the optional argument use\_nkode which is a bool that indicates whether to use the numbakit\_ode compiled differential equation solver as a backend. This can result in speedups in some situations, particularly very long time simulation ( $\approx > 100 \mu s$  or so). However, it introduces overhead with compiling input functions that means it is not guaranteed to provide a speedup so it defaults to False. Because its speed vs the default scipy.optimize.solve\_ivp() backend is highly dependent on the particular problem, and even version/platform to a certain extent, our recommendation is to experiment with both True and False to see what works best for the types of problems you need to solve.

```
end_time = 10 #microseconds
num_pts = 100
solution_time = rq.solve_time(sensor_time, end_time, num_pts)
print(type(solution_time))
```

```
<class 'rydiqule.sensor_solution.Solution'>
```

Once again we have a Solution object. However, for a time solve, this object contains two fields, rho as before, and now also t, which are the time values at which the solution was evaluated. Let's have a look at the shape of each one.

```
print(f"Solution shape: {solution_time.rho.shape}")
print(f"t shape: {solution_time.t.shape}")
```

```
Solution shape: (100, 15)
t shape: (100,)
```

So the density matrix solution is an array of shape (100, 15). The 15 is obviously the flattened real density matrix discussed above  $(4^2 - 1 = 15)$  and, as you might expect, the 100-element axis represents the time. So accessing solution\_time.rho[50,:] or just solution\_time.rho[50] would give the density matrix of the system at time given by the 50th element of solution\_time.t[50].

Now, we can look at what a particular density matrix element looks like as a function of time using matplotlib. This will be a minimal plot of  $\rho_{01}$  vs t just to show how you might do this for your own system. The get\_rho\_ij function makes it easy, since the axis for the density matrix is always the last one for any rydiqule solution.

```
absorption_time = rq.get_rho_ij(solution_time.rho,0,1).imag
print(f"Shape: {absorption_time.shape}")
```

plt.plot(solution\_time.t, absorption\_time);

Shape: (100,)



As we can see, the density matrix element is in a steady-state until the field is turned on at time  $t = 1\mu s$ , then we observe oscilitory behavior after the field is turned on. This is a toy model, so more detailed discussion of results will be saved for other notebooks, but you can see that viewing this behavior is very straightforward once the system has been solved.

### 3.5.1 Initial Conditions

You might reasonably ask where the steady-state that is on at t = 0 comes from in the above example. If the initial condition of the time solve is unspecified, rydiqule will solve the steady-state problem *without* any of the time-dependent fields active and use that as the initial condition for the solver. However, if you wish to start the system with a different initial density matrix, you can specify the optional init\_cond argument in solve\_time(). As a note, the shape of the initial condition must match what the shape of the steady-state solution is (if you wish to use different initial conditions for each set of parameters), or just the shape of the density matrix (to use the same initial condition for all cases). For this system, they are the same since there is only one value for each laser parameter, but in general they need to match.

Let us see what it looks like to set the initial condition to all the population staying in the ground state. This corresponds to  $\rho_{00} = 1$ , and  $\rho_{ij} = 0$  for  $i, j \neq 0, 0$ . Since we know rydiqule discards the ground state when it solves, this corresponds to an array of all zeros.

```
sol_dim = sensor_time.basis_size**2 - 1
ic = np.zeros(sol_dim)
print(f"Initial Condition Shape: {ic.shape}")
```

```
Initial Condition Shape: (15,)
```

Notice that we also accessed the size of the basis via Sensor.basis\_size. This is the expected size for a solution, so let's see what the solution looks like for the absorption element  $\rho_{01}$ .

solution\_time\_from\_0 = rq.solve\_time(sensor\_time, end\_time, num\_pts, init\_cond=ic)
absorption\_time\_from\_0 = rq.get\_rho\_ij(solution\_time\_from\_0.rho, 0, 1).imag

plt.plot(solution\_time\_from\_0.t, absorption\_time\_from\_0);



As you might expect, we see an abrupt transient from zero, which has a small jump at  $1\mu s$ , followed by some oscillitory behavior that is at least similar to the plot above.

#### 3.5.2 Multi-value Parameters in a time solve

Just like solve steady, solve\_time supports coupling parameter definitions that are list-like. It works more or less as you might expect based on the behavior of steady-state solving, but it is worth briefly discussing for the sake of demonstrating what the solution might look like.

We start by creating a sensor identical to the one above, but with detunings defined as lists:

Then, we solve with solve\_time just as above. We have reduced the number of detunings, but remember that rydiqule is still solving about 2,500 equations here, so we should expect it to be a little slow. We can use the %%time jupyter magic to see how slow.

%%time
end\_time = 10 #microseconds

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```
num_pts = 100
solution_time_sweep = rq.solve_time(time_sensor_sweep, end_time, num_pts)
```

```
CPU times: total: 39.9 s
Wall time: 20.4 s
```

On my machine it runs in about 7 seconds, but the time depends on several things, including how powerful your machine is and library version/build issues we are working on. If it takes you several times longer, consider trying with use\_nkode=True. We can now inspect and try and make sense of the shape of the solution.

print(f"Shape: {solution\_time\_sweep.rho.shape}")

```
Shape: (51, 51, 100, 15)
```

So what does this mean? As you likely can figure out, the last axis of the solution is still the elements of the density matrix with the expected 15 elements. Then, the second-to-last axis is the time axis. This holds true in general for time solutions regardless of how many other axes there are. The last is always density matrix elements and the second-to-last is always time. We can then get the other axes from a call to Sensor.axis\_labels(), which works just as above to help with the rest of the axes.

print(time\_sensor\_sweep.axis\_labels())

['probe\_detuning', 'coupling\_detuning']

get\_rho\_ij() also works as expected for stacked time solutions:

```
absorption = rq.get_rho_ij(solution_time_sweep.rho, 0, 1).imag
print(absorption.shape)
```

(51, 51, 100)

So suppose we wanted to plot  $\rho_{01}$  vs t for the on-resonance case. On-resonance (detuning zero) corresponds to the middle of the detuning list defined above, element 25. We can then plot that vs time.

absorption\_resonance = absorption[25, 25]
plt.plot(solution\_time\_sweep.t, absorption\_resonance);



# 3.6 4. Simulating Doppler broadening

One final key piece of functionality in rydiqule is the ability to simulate a doppler-broadened system. Internally, this is handled by breaking a doppler velocity profile into some number of slices, then applying the corresponding detunings for each class to the unshifted solution. This produces many sets of equations of motion, which are then solved, and then a weighted average performed to get the doppler-broadened solution.

To set up a system with doppler broadening, we use the "kvec" keyword the couplings definition. A kvec is a 3-element spatial vector in the propagation direction of the field, with magnitude equal to the standard deviation of the doppler velocity profile component in that direction.

Again, this is a cartoon example, but it illustrates how to set up doppler broadening. In this case, we apply identical 100 Mhz doppler broadening in the x direction on both the coupling and probe lasers. With the lasers configured,

we can now call the <code>solve\_steady\_state()</code> function to solve as before, this time with the optional argument <code>doppler=True</code>.

```
solution_doppler = rq.solve_steady_state(sensor_doppler, doppler=True)
print(f"Solution shape: {solution_doppler.rho.shape}")
```

Solution shape: (201, 15)

Note that by default, the solution shape is the same as it was without doppler. rydiqule performs a weighted average of the solutions for each doppler slice. This behavior can be disabled with the optional sum\_doppler=False flag. In this case, the wighted solution to each doppler class will be returned so they can be inspected.

```
absorption_doppler = rq.get_rho_ij(solution_doppler.rho,0,1).imag
print(f"Absorption_shape: {absorption_doppler.shape}")
```

```
plt.plot(detunings, absorption_doppler)
```

```
Absorption_shape: (201,)
```





Notice that apart from the doppler broadening, this system is identical to the first one we solved over a range of detunings. Now, with the doppler broadening, its features have been smeared out a little as expected with a doppler distribution.

It is also worth mentioning that the same argument works identically in the solve\_time() function.

## 3.7 5. Cell and real atoms

So far all of the functionality shown so far have used the Sensor object, providing the barebones physics needed to run simulations. However, in an applied setting, we would like to avoid manually filling all these parameters in with the properties of real atoms. Thus, we have created the Cell class, which inherites Sensor. This inheritence structure means that a Cell uses all the same functions as Sensor, in our case with some extra bells and whistles. First, and most importantly, we can specify a physical atom to associate with the sensor. This (behind the scenes) automatically fills in things like state lifetimes and transition frequencies.

The first argument one can specify a particluar Rydberg atom isotope via one of the following strings: ['H', 'Li6', 'Li7', 'Na', 'K39', 'K40', 'K41', 'Rb85', 'Rb87', 'Cs'], corresponding respecively to Hydrogen-1, Lithium-6, Lithium-7, Sodium-23, Potassium-39, Potassium-40, Potassium-41, Rubidium-85, Rubidium-87, and Caesium-133. After the atom, the next arguments are sequence of atomic states formatted with the Quantum numbers [n, l, j, m]. Finally, this is where experimental parameters are defined in order to calculate system observables (such as optical path length and beam\_area). If we wanted to create a Cell with the D1 line of the Rubidium atom for example, we might do the following:

Rb\_Cell = rq.Cell('Rb85', [5, 0, 1/2, 1/2], [5, 1, 1/2, 1/2], cell\_length=1e-3,... →beam\_area=1e-6)

Of course, it might get tedious to add common transitions like D1 and D2, so Rydiqule adds a shorthand for calculating them,  $D1\_states$  and  $D2\_states$ . These can be specified either with a principle quantum number n, or with one of the strings we use to specify the atom (additionally, the non-isotope-specified chemical symbol can be used, such as "Rb").

```
print(rq.D1_states('Rb85'))
print(rq.D2_states(5))
```

([5, 0, 0.5, 0.5], [5, 1, 0.5, 0.5]) ([5, 0, 0.5, 0.5], [5, 1, 1.5, 0.5])

Using this method, the cell can be created as follows:

```
atom = 'Rb85'
Rb_Cell = rq.Cell(atom, *rq.D1_states(atom))
```

So we have created out cell, but how can we be sure what states are in the system? We can use the Cell. states\_list() function.

```
print(Rb_Cell.states_list())
```

```
[[5, 0, 0.5, 0.5], [5, 1, 0.5, 0.5]]
```

These are the 2 states we are considering in our Cell, formatted with the quantum numbers [n, l, j, m]. As you can see, they do indeed correspond to the D1 line of Rubidium-85. But what if we wanted to add more states? Additional states can be defined as part of the system, but must be declared when the Cell is created. Let's add something in a higher state n = 20.

```
atom = 'Rb85'
new_state = [20, 0, 0.5, 0.5]
Rb_Cell = rq.Cell(atom, *rq.D1_states(atom), new_state)
```

Importantly, while the constructor is a little, different, it is still a Sensor under the hood, we just no longer need to specify transition frequencies and decoherences manually (although decoherences can still be added further if desired). As such we can call all the usual sensor functions, and all the information is still stored on the couplings attribute of Cell.

Additional self-broadening terms can be added to the decoherence matrix using the usual methods. Note that to make a new decoherence additive rather than overriding something, give it a unique label.

```
gamma_collisional = 2*np.pi*1.0 #radMHz
Rb_Cell.add_self_broadening(1, gamma_collisional, label="collisional")
print(Rb_Cell.decoherence_matrix())
```

```
[[4.11728555e-01 0.0000000e+00 0.0000000e+00]
[3.65262306e+01 6.28318531e+00 0.00000000e+00]
[5.51030221e-01 2.69737753e-02 0.00000000e+00]]
```

So we now have a 3-level system with the expected states, so far so good. And it even generated a gamma matrix based on state lifetimes! From here we can add couplings as before.

Be aware that when using Cell, if detuning is not specified, the Hamiltonian will be written in the laboratory frame and the frequency of the transition will be calculated automatically. This can lead to very large frequencies in the Hamiltonian,

```
detunings = 2*np.pi*np.linspace(-10,10,201) #201 values between -10 and 10 MHz
laser_01 = {"states": (0,1), "detuning": detunings, "rabi_frequency": 3}
laser_12 = {"states": (1,2), "detuning": 2, "rabi_frequency": 5}
Rb_Cell.add_couplings(laser_01, laser_12)
```

To drive home that this really is just a sensor, let's have a look at the couplings attribute.

print(Rb\_Cell.couplings.nodes(data=True))
print(Rb\_Cell.couplings.edges(data=True))

| [(0, {'gnums': [5, 0, 0.5, 0.5], 'energy': 0, 'gamma_lifetime': 0}), (1, {'gnums': |               |               |               |  |  |  |  |
|--|---------------|---------------|---------------|--|--|--|--|
| →[5, 1, 0.5, 0.5], 'energy': 2369435838.3044744, 'gamma lifetime': 36.             |               |               |               |  |  |  |  |
| →11450209100816}), (2, {'qnums': [20, 0, 0.5, 0.5], 'energy': 6273525803.532067,   |               |               |               |  |  |  |  |
| <pre></pre>  |               |               |               |  |  |  |  |
| [(0, 0, {'gamma transit': 0.41172855461658464, 'label': '(0,0)'}), (0, 1, {'rabi   |               |               |               |  |  |  |  |
| →frequency': 3, 'detuning': array([-62.83185307, -62.20353454, -61.57521601, -60.  |               |               |               |  |  |  |  |
| ↔94689748,   |               |               |               |  |  |  |  |
| -60.31857895,  | -59.69026042, | -59.06194189, | -58.43362336, |  |  |  |  |
| -57.80530483,  | -57.1769863 , | -56.54866776, | -55.92034923, |  |  |  |  |
| -55.2920307  | -54.66371217, | -54.03539364, | -53.40707511, |  |  |  |  |
| -52.77875658,  | -52.15043805, | -51.52211952, | -50.89380099, |  |  |  |  |
| -50.26548246,  | -49.63716393, | -49.0088454 , | -48.38052687, |  |  |  |  |
| -47.75220833,  | -47.1238898 , | -46.49557127, | -45.86725274, |  |  |  |  |
| -45.23893421,  | -44.61061568, | -43.98229715, | -43.35397862, |  |  |  |  |
| -42.72566009,  | -42.09734156, | -41.46902303, | -40.8407045   |  |  |  |  |
| -40.21238597,  | -39.58406744, | -38.9557489 , | -38.32743037, |  |  |  |  |
| -37.69911184,  | -37.07079331, | -36.44247478, | -35.81415625, |  |  |  |  |
| -35.18583772,  | -34.55751919, | -33.92920066, | -33.30088213, |  |  |  |  |
| -32.6725636  | -32.04424507, | -31.41592654, | -30.78760801, |  |  |  |  |
| -30.15928947,  | -29.53097094, | -28.90265241, | -28.27433388, |  |  |  |  |
| -27.64601535,  | -27.01769682, | -26.38937829, | -25.76105976, |  |  |  |  |
| -25.13274123,  | -24.5044227 , | -23.87610417, | -23.24778564, |  |  |  |  |
| -22.61946711,  | -21.99114858, | -21.36283004, | -20.73451151, |  |  |  |  |
| -20.10619298,  | -19.47787445, | -18.84955592, | -18.22123739, |  |  |  |  |
| -17.59291886,  | -16.96460033, | -16.3362818 , | -15.70796327, |  |  |  |  |
| -15.07964474,  | -14.45132621, | -13.82300768, | -13.19468915, |  |  |  |  |
| -12.56637061,  | -11.93805208, | -11.30973355, | -10.68141502, |  |  |  |  |
| -10.05309649,  | -9.42477796,  | -8.79645943,  | -8.1681409 ,  |  |  |  |  |
| -7.53982237,   | -6.91150384,  | -6.28318531,  | -5.65486678,  |  |  |  |  |
| -5.02654825,   | -4.39822972,  | -3.76991118,  | -3.14159265,  |  |  |  |  |
| -2.51327412,   | -1.88495559,  | -1.25663706,  | -0.62831853,  |  |  |  |  |
| 0. ,   | 0.62831853,   | 1.25663706,   | 1.88495559,   |  |  |  |  |
| 2.51327412,  | 3.14159265,   | 3.76991118,   | 4.39822972,   |  |  |  |  |

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|   |                       |                      | (continued from previous page)    |  |  |  |
|---|-----------------------|----------------------|-----------------------------------|--|--|--|
| 5.02654825,   | 5.65486678,           | 6.28318531,          | 6.91150384,                       |  |  |  |
| 7.53982237,   | 8.1681409 ,           | 8.79645943,          | 9.42477796,                       |  |  |  |
| 10.05309649,  | 10.68141502,          | 11.30973355,         | 11.93805208,                      |  |  |  |
| 12.56637061,  | 13.19468915,          | 13.82300768,         | 14.45132621,                      |  |  |  |
| 15.07964474,  | 15.70796327,          | 16.3362818 ,         | 16.96460033,                      |  |  |  |
| 17.59291886,  | 18.22123739,          | 18.84955592,         | 19.47787445,                      |  |  |  |
| 20.10619298,  | 20.73451151,          | 21.36283004,         | 21.99114858,                      |  |  |  |
| 22.61946711,  | 23.24778564,          | 23.87610417,         | 24.5044227 ,                      |  |  |  |
| 25.13274123,  | 25.76105976,          | 26.38937829,         | 27.01769682,                      |  |  |  |
| 27.64601535,  | 28.27433388,          | 28.90265241,         | 29.53097094,                      |  |  |  |
| 30.15928947,  | 30.78760801,          | 31.41592654,         | 32.04424507,                      |  |  |  |
| 32.6725636 ,  | 33.30088213,          | 33.92920066,         | 34.55751919,                      |  |  |  |
| 35.18583772,  | 35.81415625,          | 36.44247478,         | 37.07079331,                      |  |  |  |
| 37.69911184,  | 38.32743037,          | 38.9557489 ,         | 39.58406744,                      |  |  |  |
| 40.21238597,  | 40.8407045 ,          | 41.46902303,         | 42.09734156,                      |  |  |  |
| 42.72566009,  | 43.35397862,          | 43.98229715,         | 44.61061568,                      |  |  |  |
| 45.23893421,  | 45.86725274,          | 46.49557127,         | 47.1238898 ,                      |  |  |  |
| 47.75220833,  | 48.38052687,          | 49.0088454 ,         | 49.63716393,                      |  |  |  |
| 50.26548246,  | 50.89380099,          | 51.52211952,         | 52.15043805,                      |  |  |  |
| 52.77875658,  | 53.40707511,          | 54.03539364,         | 54.66371217,                      |  |  |  |
| 55.2920307 ,  | 55.92034923,          | 56.54866776 <b>,</b> | 57.1769863 ,                      |  |  |  |
| 57.80530483,  | 58.43362336,          | 59.06194189 <b>,</b> | 59.69026042,                      |  |  |  |
| 60.31857895,  | 60.94689748,          | 61.57521601,         | 62.20353454,                      |  |  |  |
| 62.83185307])   | , 'phase': 0,         | 'kvec': (0, 0,       | 0), 'dipole_moment': 1.           |  |  |  |
| →7277475900721146 <b>, '</b>  | label': '(0,1)        | '}), (1, 0, {'       | gamma_transition': 36.            |  |  |  |
| →11450209100816, 'la  | bel': '(1,0)',        | 'gamma_transi        | t': 0.41172855461658464}), (1, 1, |  |  |  |
| ↔{'gamma_collisional  | <b>':</b> 6.283185307 | 179586, 'label       | ': '(1,1)'}), (1, 2, {'rabi_      |  |  |  |
| →frequency': 5, 'det  | uning': 2, 'ph        | hase': 0, 'kvec      | : (0, 0, 0), 'dipole_moment': -0. |  |  |  |
| →022325338449401693, 'label': '(1,2)'}), (2, 1, {'gamma_transition': 0. |                       |                      |                                   |  |  |  |
| →026973775254682874, 'label': '(2,1)'}), (2, 0, {'gamma_transit': 0.    |                       |                      |                                   |  |  |  |
| ↔41172855461658464, 'label': '(2,0)'})]                                 |                       |                      |                                   |  |  |  |
|   |                       |                      |                                   |  |  |  |

There is a **lot** more information, but the structure is identical. The only difference is that values like decoherences from natural state lifetimes have been added automatically. If we added states without the RWA, transition frequencies would be added automatically as well, since "absolute energy" (energy difference with the ground state) is stored on the nodes. Given that it is the same as any other Sensor, let's show that by solving the system as we would have before, then we can call it a day!

In this case, we can easily call a convenience function, Solution.get\_transmission\_coef() to return the transmission coefficient for the calculated solution(s).

```
sol = rq.solve_steady_state(Rb_Cell)
absorption_cell = sol.get_transmission_coef()
plt.plot(detunings, absorption_cell)
plt.xlabel('probe detuning (Mrad/s)')
plt.ylabel('transmission coefficient')
```

C:UsersDavidsrcRydiqulesrcrydiqulesensor\_solution.py:223: UserWarning: At→ →least one solution has optical depth greater than 1. Integrated results\_ →are likely invalid. warnings.warn(('At least one solution has optical depth '

Text(0, 0.5, 'transmission coefficient')



This is a very minimal example introducing the concept of the Cell class as an extension of Sensor. For a more detailed example of its use, other notebooks make heavy use of the Cell to do meaningful physics. It also illustrates that Sensor is extensible, which actually has some very helpful implications for what you can do with rydiqule. Sensor, or even Cell, can be extended further to model very specific experimental setups so they can be re-created easily, specifying only the parameters that are likely to change. If you are comfortable with object-oriented programming in python, the sky is the limit in terms of what you can store on the couplings graph and what you can calculate automatically. From here, feel free to play around with other notebooks, and use rydiqule for your own problems! We are constantly trying to improve the library, so feedback is welcome.

## 3.8 Acknowledgments

The authors recognize financial support from the US Army and Defense Advanced Research Projects Agency (DARPA). Rydiqule has been approved for unlimited public release by DEVCOM Army Research Laboratory and DARPA. This software is released under the xx licence through the University of Maryland Quantum Technology Center. The views, opinions and/or findings expressed here are those of the authors and should not be interpreted as representing the official views or policies of the Department of Defense or the U.S. Government.

```
rq.about()
```

Matplotlib Version:3.6.2ARC Version:3.3.0Python Version:3.8.15Python Install Path:C:Miniconda3envsarcPlatform Info:Windows (AMD64)CPU Count:4Total System Memory:16 GB

# CHAPTER FOUR

# CHANGELOG

## 4.1 v1.2.2

### 4.1.1 Improvements

• Now also distribute rydiqule via an anaconda channel.

### 4.1.2 Bug Fixes

• Fixed bug where t=0 time-dependent hamiltonians calculated in solve\_steady\_state were double counted if more than one time-dependent coupling was present.

# 4.2 v1.2.1

#### 4.2.1 Bug Fixes

• Fixed bug in energy level shifts where shifts overwrote detunings instead of adding.

## 4.3 v1.2.0

### 4.3.1 Improvements

- Level diagrams now use Sensor.get\_rotating\_frames to provide better plotting of energy ordering of levels.
- Level diagrams now allow for optional control of plotting parameters by manually specifying ld\_kw options on nodes and edges.
- Added the ability to specify energy level shifts (additional Hamiltonian digonal terms) not accounted for by the coupling infrastructure.

#### 4.3.2 Bug Fixes

- Sensor.make\_real now returns correct sized const array when ground is not removed.
- Many updates to type hints to improve their accuracy.

### 4.3.3 Deprecations

- Remove Solution.\_variable\_parameters in favor of property checking the observable parameters.
- Renamed Sensor.basis() and Solution.basis to Sensor.dm\_basis() and Solution. dm\_basis to disambiguate physical basis from computational basis.

## 4.4 v1.1.0

#### 4.4.1 Improvements

- Added the ability to specify hyperfine states in a Cell. They are distiguished by having 5 quantum numbers [n, l, j, F, m\_F].
- kappa and eta are now proprties of Cell which are calculated on the fly.
- Separated rotating frame logic from hamiltonian diagonal generation into a new function Sensor. get\_rotating\_frames(). Allows for simple inspection of what rotating frame rydiqule is using in a solve.
- Reworked the under-the-hood parameter zipping framework. This should have minimal impact on user-facing functionality. Hamiltonians with zipped parameters are no longer generated with a diag operation. Zipped parameters are now handled with a dictionary rather than a list. Zipped parameters can now be given a shorthand label rather than the default behavior of concatenating individual labels.
- The rearrangement of axes in a stack is now defined completely by the behavior of axis\_labels().
- Added a diff\_nearest boolean argument to get\_snr. When true, calculates SNR based on nearest neighbor diff. This is in contrast to the default behavior of taking the difference relative to the first element. One case where this is necessary is when getting SNR vs LO Rabi frequency of a heterodyne measurement.
- Added the ability to label states of a sensor with the label\_states method. States with a label matching a particular pattern can be accessed with the states\_with\_label function.
- Timesolver now allows for returning doppler-averaged solutions without applying the doppler weight factors. This is mostly useful for internal testing.
- solve\_steady\_state now treats time-dependent couplings as having their t = 0 value. Most importantly, this affects the default behavior for timesolve initial condition generation and should limit large transient behavior. This also allows the user to specify if time-dependent couplings should be solved with field on or off in steady-state by altering their t = 0 value (eg changing between sin and cos).
- Added unit tests for observables, (susceptibility, optical depth, transmission coefficient, and phase shift).
- All Observables (susceptibility, optical depth, etc) now only require a Solution object to run.
- rq.D1\_states and rq.D2\_states can now specify the atom via string with any isotope specification (including none)
- get\_snr now warns if any couplings have time-dependence, which are ignored.
- Zipped parameter labels may now include underscores
- about function now conceals the user's home directory by default when printing paths
- Moved level diagram plotting to use an external library

### 4.4.2 Bug Fixes

- Fixed return units of get\_snr to actually return in 1s BW. Previously was returning in 1us BW.
- Sign errors when specifying detunings both in and out of the rotating frame have been fixed. All detuning signs now follow the convention that positive = blue detuned from atomic resonance, so long as the couplings are added correctly (ie second state of states tuple is always the higher energy one).
- Fixed potential issue in get\_snr where output results could be overwritten to views of intermediate arrays
- Fixed numerical bugs in observables: phase shift, susceptibility, optical depth, transmission coef. Now unit tested against Steck Quantum Optics notes.
- Ensure that non-dipole-allowed transitions are properly warned about in Cell.add\_coupling with ARC==3.4

### 4.4.3 Deprecations

- The new kappa and eta properties of Cell directly calculate from Cell properties.
- Time-solver backends (except scipy) are now optional dependencies that are no longer installed by default. To install them, use the pip install rydigule[backends] command.
- The uncollapsed stack shape can no longer be accessed to avoid confusion.
- Removed the ability to pass additional parameters to np.meshgrid through the get\_parameter\_mesh function.
- get\_snr no longer returns in units of lus.
- Default timesolver initial conditions no longer assume time-dependent couplings have the value of rabi\_frequency. It is now rabi\_frequency times the time\_dependence.
- Multiple sign errors have been corrected in Sensor and Cell with regards to detunings. Results that are asymmetric about zero detuning are likely to change. Please ensure all couplings are following correct sign conventions for consisten results (ie second state of states tuple has higher energy).
- most of the functions in experiments py have been moved to become methods of Solution class.

# 4.5 v1.0.0

#### 4.5.1 Improvements

- Steady-state behavior for time-dependent fields (and thus initial conditions for time solves) is now computed as a static value rather than zero (previous behavior).
- Added a flag in scipy\_solve to specify how to define the right-hand function of the differential equation, to use either loops (the newer method) or list comprehension (the older method).
- Implemented ruff linting rules as an action for new PRs to help enforce good coding practices.
- Implemented unit-testing action for new PRs to help automate catching regression bugs.

### 4.5.2 Bug Fixes

- Fixed a broken uinit test that did not affect package functionality.
- Fixed issue where level diagrams don't draw correctly if all non-zero dephasings are equal.

### 4.5.3 Deprecations

## 4.6 v1.0.0rc2

#### 4.6.1 Improvements

- Added a copy method to solution.
- Expanded the Solution object to include more clear axis labels and the basis of the sensor used.
- Begin hosting public documentation on readthedocs.

## 4.6.2 Bug Fixes

- Changed an isinstance check to hasattr, fixing an occasional issue with reloading rydiqule in jupyter notebooks.
- Fixed issue where submodules wree not installed outside of editable mode.
- Fixed a bug where additional arguments like warning suppression could not be passed to Sensor.add\_couplings

## 4.6.3 Deprecations

## 4.7 v1.0.0rc1

## 4.7.1 Improvements

- Added a warning in cell if add\_coupling is called a dipole-forbidden transition.
- The zip\_parameters function can now be called on parameters of different types (e.g. detuning with rabi\_frequency)
- The time solver now can call ivp solvers outside its own module. This allows for more quickly using different backend solvers for time-dependent problems.
- Implement timesolver backends based on CyRK's cython and numba ode solvers
- Optimize scipy backend of the timesolver for smaller dimensional problems

### 4.7.2 Bug Fixes

- Fixed issue where solvers would save doppler axes labels and values even when they are summed over to the solution object
- Fixed a bug where energy level diagrams broke when decochernce rates were scanned.
- Fixed issue where compiled timesolvers could not solve doppler averaged problems.
- · Fixed issue where certain doppler solves could not be sliced correctly
### 4.7.3 Deprecations

# 4.8 v0.5.0

### 4.8.1 Improvements

- Add isometric-population meshing option to doppler\_mesh
- Allow get\_rho\_ij to accept a Solution object directly, in addition to solution numpy arrays
- Add get\_rho\_populations helper function to efficiently get the trace of density matrix solutions
- Allow beam\_power or beam\_waist to be scanned parameters in a Cell coupling
- Add more information to Solution objects returned by the solvers
- Allow dephasings to be scannable parameters.
- Updated the framework for scanning parameters to generate relevant lists on the fly
  - Note: This changes the order of axes in a stack. Previously, the axes would be ordered based on the order they were added to the system. They are now ordered based on python's sort() applied to a tuple of ((low\_state, high\_state), parameter\_name). As a result, they will be ordered first by lower state, then by upper state, then alphabetically by parameter name (e.g. "detuning", "rabi\_frequency") In cases where the code was being used for simulations, this may affect cases where axes were defined specifically by number, and these may need to be updated.
- Added a distinction between stack shapes in steady-state vs time-dependent. For example, a steady-state hamiltonian stack may have shape (10, 1, 3, 3) while the time dependent portion may have shape (1, 25, 3, 3).
- Renamed the ham\_slice function to matrix\_slice and allowed it to iterate over any number of matrices. - Updated internals of solver functions to use this framework.
- zip\_parameters function no longer enforces parameters be the same type.

### 4.8.2 Bug Fixes

- Fixed several issues with parameter zipping functionality producing errors when sensor methods were called multiple times.
- Fixed issue where get\_rho\_ij incorrectly calculated the rho\_00 element
- Allow Cell.add\_coupling to accept a list of e-field values
- Fixed an bug where specifying a list of rabi\_frequency in a coupling with time-dependence would raise an error when solved
- Fixed issue with dephasing broadcasting preventing hamiltonian slices for large solves

### 4.8.3 Deprecations

- Removed all sensor\_management functionality as too difficult to maintain generally and securely.
- Removed the internal \_variable\_couplings, \_variable\_parameters, and \_variable\_values attributes from sensor.

## 4.9 v0.4.0

### 4.9.1 Improvements

- Changed the handling of decoherent transitions to be stored on graph edges rather than as a separate attribute.
  - Gamma matrix is now calculated on the fly with the decoherence\_\_\_matrix () method.
  - Decoherent transitions are now added with with the add\_decoherence () function in Sensor.
  - Cell now calculates tranistion frequencies and decay rates automatically and places them on the appropriate graph edges.
- Changed the Sensor.couplings attribute from a nx.Graph to an nx.DiGraph. This has multiple advantages:
  - A less vague definition of detuning convention.
  - Precise definition of energy ordering: couplings now always point from lower to higher absolute energy.
  - More flexibility in decoherence. Decoherent transions now point "from" one state "to" another rather than just "between" 2 states. This fixes a limitation where gamma matrices no longer must be lower triangular.
- get\_snr() function in rq.experiments now takes kappa and eta as optional arguments to allow for running on any Sensor object. They can still be inferred from a Sensor subclass that has them as attributes if unspecified.
- time solver now properly handles complex time dependences in the rotating wave approximation
- Added type hints to code base that can be used to static type check with mypy
- Added functions rq.calc\_kappa and rq.calc\_eta to properly calculate kappa and eta constants for experimental parameters.
- Added function rq.get\_OD that calculates the optical depth of a solution
- Improved accuracy of the solver memory estimates
- · Increased input validation unit test coverage
- Generalized handling of transit broadening to allow for multiple repopulation states with varying branching ratios

### 4.9.2 Bug Fixes

- Fixed an issue with time dependence in the probe laser
- · Modified solver to allow for complex time dependence
- · Fixed non-hermitian hamiltonians in time solver
- Fixed error with multiple time-dependences in time solver
- Added functionality to solver error with complex time dependences
- Modified experimental return functions (get\_transmission\_coef(), get\_phase\_shift(), and get\_susceptibility()`) to allow scanning of probe rabi frequency
- Fixed get\_rho\_ij so that it correctly calculates the (0,0) population element
- Fix error in test\_sensor\_management which fails if temporary directory does not exist.
- Tighten test\_decoherences tolerances to the 2pi\*100Hz level to catch errors in decoherence matrix generation.
- Fixed issue where get\_snr ignored the optical path length input parameter
- Fixed issue where calling solve\_steady\_state with sum\_doppler=False would double memory footprint.

• Fixed issue where solve\_steady\_state could be called with weight\_doppler=False and sum\_doppler=True.

### 4.9.3 Deprecations

- get\_snr no longer allows manually specifying Sensor.eta and Sensor.kappa, these values must be passed as args for Sensor input
- Removed unused gamma\_transit argument from Sensor init
- Re-ordered argument list to Cell.add\_coupling to match order of Sensor.add\_coupling
- Sensor.add\_fields has been fully removed and no longer works as a deprecated alias of Sensor. add\_couplings

# 4.10 v0.3.0

### 4.10.1 Improvements

- Expanded documention
- Removed restrictions on ARC and numpy versions during installation.
- · Vectorized equation of motion generation to support prepending axes to a hamiltonian
- Updated the internal mechanism for sensor handling fields of various type
  - Fields are now internally called couplings
  - Fields are specified as either having rabi\_frequency or transition\_frequency, corresponding to RWA or non-RWA fields
  - Fields are specified as either having detuning or transition\_frequency, corresponding to steady-state or time-dependent fields
  - Fields with specific traits can be accessed with the couplings\_with() function
- · Added a feature to save/load sensors/cells
- Implemented NumbaKitODE which considerably speeds up solve\_time. This feature can be enabled by setting parameter compile=True of solve\_time.
- Improved logic for building diagonal terms of Hamiltonian using NetworkX graph library that allows for diagonal terms to be built from any set of values.
- Generalized doppler averaging to support prepended axes on hamiltonians.
- Improved time solver logic for improved modularity across doppler solving and multivalue parameters.
- · Added a feature to draw level diagram
- Seamlessly generate all Hamiltonians from lists of parameters in sensor.
- Added ability to label couplings.
- · Added capability to make any coupling time-dependent
- Sped up time solving considerably by simultaneously solving all equations rather than looping.
- Allow for user to specify fields by beam power, beam waist, and electric field, in the Cell framework.
- Solve functions now return a bunch-type object rather than a tuple.
- · Added functionality that breaks equations into slices based on memory requirements
- Quantum numbers and absolute energies are now stored on the nodes of a Cell couplings graph
- Cell now adds decay rates and decoherences to the nodes and edges of the Cell couplings graph

- Cell now calculates the gamma matrix in an arbitrary way, and is no longer limited to two laser, ladder schemes
- Added function to calculate sensor SNR with repect to any varied sensor coupling parameter
- Added function to return sensor parameter mesh

### 4.10.2 Bug Fixes

- Fixed example notebook.
- Fixed issue where doppler averaging breaks if there are uncoupled levels.
- Fixed doppler averaging so that doppler shifts are applied with signs consistent with the hamiltonian.
- Fixed a bug where doppler averaging did not properly solve separately for each doppler class.
- Fixed issue where spatial dimension of doppler averaging is not introspected correctly in the presence of round-off errors.

### 4.10.3 Deprecations

- All "field" functionality are being deprecated in favor of "coupling"
- The rf\_couplings, target\_state, and rf\_dipole\_matrix arguments of solve\_time()
- All functions relating to sensor.transtion\_map are deprecated
- Cell now does not accept gamma\_excited or gamma\_Rydberg as these are always calculated or Sensor can be used with a given gamma matrix
- Cell now does not accept gamma\_doppler as Doppler broadening width is given by mutiplying the most proable velocity and the laser k-vector

# 4.11 v0.2.0

Beta release. Contains very large number of backwards-incompatible changes over alpha release.

# 4.12 v0.1.0

Alpha release. Minimum viable product release that does basic modeling tasks slowly.

# PHYSICS DOCUMENTATION

The following pages contain white-ups that explain the theoretical basis for the many operations performed by rydiqule.

# 5.1 Equations of Motion Generation

### 5.1.1 Introduction

This document details a few notes about the theoretical operations taking place under the hood in the Rydiqule Modelling package. In particular, we discuss the methods that Rydiqule uses to numerically solve differential equations for density matrices.

### 5.1.2 Hamiltonian and Rotating Wave Approximation

For a two level atom interacting with an electric field E, the dipole interaction Hamiltonian is,

$$H = \omega |e\rangle \langle e| - \mathbf{d} \cdot \mathbf{E}$$

where the Rabi frequency is defined as  $\Omega = \mathbf{d} \cdot \mathbf{E}/\hbar$ . The electric field is,

$$\mathbf{E} = \mathbf{E}_0 \cos(\omega t + \phi)$$
$$= \frac{\mathbf{E}_0}{2} (e^{i\omega t} + e^{-i\omega t})$$

The dipole operator can be written [1]

$$\mathbf{d} = \langle g | \mathbf{d} | e \rangle \left( | g \rangle \langle e | + | e \rangle \langle g | \right)$$

The operator  $|g\rangle\langle e|$  evolves at frequency  $e^{i\omega t}$  under the bare Hamiltonian, so we expand and take the slowing evolving terms (RWA, see [1]).

$$\begin{split} H_{\rm RWA} &= \omega \left| e \right\rangle \langle e | \\ &- \left\langle g \right| \mathbf{d} \left| e \right\rangle \cdot \frac{\mathbf{E}_0}{2} (\sigma^+ e^{-i\omega t} + \sigma^- e^{i\omega t}) \end{split}$$

where  $\sigma^+ = |g\rangle \langle e|$  and  $\sigma^- = |e\rangle \langle g|$ 

### 5.1.3 Equations of Motion

The Master equation is,

$$\dot{\rho} = -i[H,\rho] - \mathcal{L}$$

We write this in summation notation,

$$\dot{\rho}_{ij} = -i(H_{ik}\rho_{kj} - \rho_{ik}H_{kj}) - L_{ij}$$

More, generally, we can re-write this equation as a matrix equation,

 $\dot{\rho}_{ij} = R_{ik}\rho_{kj}$ 

By re-shaping these equations, using numpy.reshape, we can convert this into a linear set of differential equations in matrix form (see, for example Sensor.\_hamiltonian\_term() and Sensor. \_decoherence\_term() in Rydiqule). I am not going to focus on these right now. I will call the re-shaped density vector p

$$\dot{p}_l = M_{li} p_i$$

This is a linear set of equations we can easily solve with linalg.solve. As a note, our reshaping procedure produces a **basis that is**, for basis size **b** 

$$l = b \times j + i$$

 $\frac{1}{0}$   $\frac{1}{00}$ 

For example,

For the programmatic code, we need knowledge of this relationship.

### 5.1.4 Removing the Ground State

The density vector (matrix) is physically constrained, so that the total population is one. This constraint is not included in the equations of motion. This leads to numerical instabilities. The best way to fix this instability is to algebraically remove one of the equations of motion (ie the ground state). To remove the ground state, we apply the constraint

$$\rho_{00} = 1 - \rho_{ii}.$$

Writing this in terms of  $\rho'$  gives,

$$p_0 = 1 - \sum_x p_{[(b+1) \times x]}$$

We use this to re-write Eq. \ref{eq:master},

$$\dot{p}_l = M_{li}p_i - M_{l0}p_0 + M_{l0}(1 - \sum_x p_{[(b+1) \times x]})$$

This is the equation we must implement to remove the ground state.

In the code, we can apply Eq. \ref{eq:groundRemoved} and then we can simply remove the first column of  $M_{il}$ . In the code, we implement this transformation by replacing the set of equations  $M_{li}$ ,

$$M_{li}\rho_i \to (M_{li} + M'_{li})\rho_i + c_l$$

The constant term c is equivalent to the first column of  $M_{li}$ .

$$c_l = M_{l0}$$

The term we need to add, M' is

$$M'_{li} = -M_{l0} \sum_{x} p_{[i=(b+1) \times x]}$$

This can be implemented as the tensor product of two vectors

$$M'_{li} = -M_{l0} \otimes p *$$

where  $M_{i0}$  is just M[:,0] and  $p = p_{[j=(b+1)\times x]}$  is a vector of ones and zeros that is generated with list comprehension.

The end result is an equation where each ground state term of the density matrix  $\rho_0 0$  is replaced by the sum of all excited states.

### 5.1.5 Making the Equations Real

Numerically, converting to a real set of equations is important, because it prohibits the buildup of "imaginary populations" in quantum states. In other words, some equations in the equations of motion are physically required to be real, and some are complex. Machine rounding errors causes leakage into the imaginary parts of the populations equation, which is unphysical. Under certain solving conditions the equations are not stable to this buildup. Converting all the equations to real solves the issue.

The equation we want to solve (for the density vector p) is,

$$\dot{p_c} = M_c \cdot p_c + c_c$$

where the  $_c$  notation represents that each term is complex.

The change in basis that we implement is shown below in equation and table format,

$$\begin{array}{l} \rho_{ii} \rightarrow \rho_{ii} \\ \rho_{ij} \rightarrow Re(\rho_{ij}), \ i > j \\ \rho_{ji} \rightarrow Im(\rho_{ij}), \ i < j \end{array}$$

| l | real $ij$   | complex <i>ij</i>              |
|---|-------------|--------------------------------|
| 0 | $ ho_{00}$  | $ ho_{00}$                     |
| 1 | $ ho_{10}$  | $\operatorname{Re}(\rho_{10})$ |
| 2 | $\rho_{20}$ | $\operatorname{Re}(\rho_{20})$ |
| 3 | $ ho_{30}$  | $\operatorname{Re}(\rho_{30})$ |
| 4 | $\rho_{01}$ | $\operatorname{Im}(\rho_{10})$ |
| 5 | $\rho_{11}$ | $\rho_{11}$                    |

We implement this with a transformation matrix U that is unitary up to a scale factor,

$$M_r = U \cdot M_c \cdot U^{-1}$$
$$c_r = U \cdot c_c$$

This matrix is calculated in the get\_basis\_transformation() helper function and is subsequently used to transform between the complex and real bases.

### References

[1]D. A. Steck, Quantum and Atom Optics, 0.13.15 ed. (2022).

# 5.2 Stacking Conventions

### 5.2.1 Introduction

For many probelms, Rydiqule is designed to implicitly handle multiple possible values for a single parameter. For example, sweeping over a range of detuning values is handled in Rydiqule simply by specifying the value of interest a list or array rather than a single value. This enables a tremendous amount of flexibility in the problems that Rydiqule can solve naturally, but there are some things worth noting about how Rydiqule specifically handles these problems, which are outlined in this document.

### 5.2.2 Numpy arrays

Typically, python lists are quite slow to perform operations on since they are dynamically sized and typed. This allows tremendous flexibility in what can be put into a list but some problems with how fast elements are accessed from that list and operating on. Numpy arrays were created to address this limitation and Rydiqule makes extensive use of them to make its calculations fast without losing the ease-of-use benefits of a Python interface. Fundamentally, a numpy ndarray is a grid of numbers that has dimensionality m1 by m2 by m3 and so on. Numpy routines are written to operate on these arrays very quickls for large numbers of dimensions.

### 5.2.3 Stacking

While numpy's own way of handling arrays via matrix broadcasting is well-documented, and most of Rydiqule's own functions use the standard numpy conventions, there are some additional assumptions Rydiqule makes when performing these operations that are worth outlining. Fundamentally, Rydiqule thinks about these ndarray objects as groups of matrices, meaning that calculations are performed assuming, for example, that an array of shape (25, 3, 3) represents  $25.3 \times 3$  matrices. This is the array that would be generated if a list of 25 values were provided for a detuning value in a 3-level Sensor, and that Sensor's get\_hamiltonian function were called. Rydiqule seamlessly handles all the work of generating those Hamiltonian matrices for each value, and returns a single array object as an output. Similarly, if 2 values are specified as lists of length 25, a single arary of shape (25, 25, 3, 3) would be returned, with a different  $3 \times 3$  Hamiltonian matrix for every combination of parameter values, for a total of 625 Hamiltonian matrices. Rydiqule terms this array a "stack" of Hamiltonians, and the "stack shape" are the axes preceding the actual matrix value axes (in this case (25, 25)), and is typically, denoted in Rydiqule as \*1 to make clear that it could be any length of set of values depending on the problem.

Hamiltonian generations is created using this convention, and that carries through to generation of equations of motion, and any other quantities that may have a different matrix for each parameter value. A Hamiltonian stack of shape (\*1, 3, 3) will generate an equation of motion (eom) stack of shape (\*1, 8, 8), with all stack demensions remaining consistent. Rydiqule's internals are, broadly, agnostic to exactly what the dimensions \*1 represent, and work regardless, as long as the dimensions corresponding to the actual quantities are in the expected position at the end.

### 5.2.4 Parameter Ordering

Given that any number of parameters may be defined as a list, Rydiqule needs a convention to ensure, in the final result, the values represent what is expected and has not been turned around. It is important to Rydiqule's design philosophy that internal variables not by tracked opaquely, and that quantities are, to the extent possible, generated on the fly in a predictable and reprodicuble way. This begs the questions, which axis corresponds to which value? Suppose the coupling between states 0 and 1 is swept in detuning over 25 values, as is the coupling between states 1 and 2, the stack shape will be (25, 25), but there are some uncertainties. One might assume that the first axis corresponds the the first laser, and the second axis corresponds to the second laser. However, this is not necessarily obvious, and it might be the other way around without a unifying convention. Rydiqule's solution to this problem turns out to be simple: python's .sort() function. Since it always orders things according to the same rules, there is a predictable outcome to which axis is which. The parameters are represent by tuples: ((0, 1), "detuning") and ((1, 2), "detuning")..sort() will sort them first by the lower state of a transition, then by the upper state, then alphabetically by the string parameter name (in this case detuning for both).

With this simple convention, Rydiqule makes these arrays consistent accross functions. One can be sure that all values will be exactly what is expected and line up properly for all quantities. Hamiltonians, equations of motion, and solutions will all use the same rules. To avoid figuring this out manually for every system, the Sensor module contains the .axis\_labels() method, which returns a list of which axes are which in string form for results interpretation. Note that the internal functions which calculate these values don't actually care what the axis are, but they do keep them consistent between calculations.

### 5.2.5 Doppler

It is worth a quick note how Rydiqule handles doppler broadening, because it leverages the same conventions around stacking as other parameter scans, and it may be encountered and cause confusion if you use Rydiqule enough. If doppler is accounted for in a solve, that typically is not invoked until the relevant solve function is called. Given a case of n\_doppler velocity classes in 1 dimension, a new axis will be prepended to the stack, resuling in a n\_doppler new dopple-shifted Hamiltonian matrices matrix that was previously in the stack. Typically, this is done under the hood, and these other solutions are averaged over before a result is returned, but examining intermediate values may ultimately result in seeing these axes, even if they are not present in the solution that is returned. Importantly, the solver internals are still agnostic to what these preceding doppler axes represent, giving flexibility and allowing a single function to handle all cases. Again, this is an intermediate step that typically does not affect how results are interpreted, it just helps to understand the internals a little better.

# 5.3 Observables

### 5.3.1 Introduction

Rydiqule can be used to calculate physical outcomes of experiments. These functions get placed into two categories, **Experiments** and **Observables**. Observables are quantities that can be computed directly from a Solution object, with no additional information. These functions can be found as methods of *Solution*. Examples of Observables are the susceptibility, optical depth, transmission coefficient, and phase shift of a probing field. Experiments are quantities that require more information. At the time of writing, the only example is the *get\_snr()* function.

### 5.3.2 Observable Derivation

Most of the Observables are derived from the optical/electrical susceptibility. Susceptibility is given by the optical polarizability  $P^+$ ,

$$P^{+} = n \langle g | \hat{d} | e \rangle \rho_{eg} = \epsilon_0 \chi E_{tot} / 2$$

This equation may be found in Steck Eq. 6.69 [1].  $\langle g | \hat{d} | e \rangle$  is the dipole matrix element,  $\rho_{eg}$  is the density matrix element, n is the atomic density,  $\chi$  is susceptibility, and  $E_{tot}$  is to amplitude of the electric field. The factor of two arises from the rotating wave approximation, such that  $P^+$  represents the atomic polarizability in the rotating frame.

### 5.3.3 Observable Validation

Rydiqule calculates the susceptibility using equivalent equations, but written in terms of atomic constants  $\kappa$  and  $\eta$  (see [2] for definitions). We validate that rydiqule calculates these observable quantities in a manner consistent with a canonical reference, namely Steck's Quantum and Atom Optics notes [1]. The unit tests in test\_experiments.py test that rydiqule and Steck align, but assume that the density matrix element  $\rho_{eg}$  is correct. Validity of density matrix elements is checked in numerous other tests.

Another more stringent test of Rydiqule is comparing the optical depth using two different methods that are both appropriate for a 2-level atom. All losses from an ideal two-level atom arise from scattering from the excited state. This allows one to write the scattering rate in terms of  $\rho_{ee}$ , as is done in Steck's Quantum and Atom Optics notes, Eq. 5.273 [1]. Another way to calculate the scattering rate is using the imaginary term of the susceptibility corresponding to the probing field coupling. This is the method Rydiqule uses, and can be found in Eq 6.73 of [1]. This test is implemented in test\_experiments.py as the test\_OD\_with\_steck unit test.

Running just these observable and experiment unit tests can be done by installing the pytest dependencies (see *Unit Tests*), and running the following command from the package parent directory.

```
pytest . \tests -m experiments
```

#### References

[1] D. A. Steck, Quantum and Atom Optics, 0.13.15 ed. (2022)

[2] D. H. Meyer et. al., Optimal atomic quantum sensing using electromagnetically-induced-transparency readout, Phys. Rev. A **104** 043103 (2021)

# 5.4 Doppler Averaging

### 5.4.1 Introduction

This document discusses the methods rydiqule uses to implement doppler-averaging of modelling results. The theoretical background is provided for completeness, but is fairly standard. Rydiqule's implementation of this is less obvious in order to optimize computational efficiency by fully leveraging numpy's vectorized operations. The primary goal of this document is to clearly outline, in a single place, the underlying conventions used by rydiqule when doppler averaging.

### Assumptions

Rydiqule currently makes implicit assumptions when modelling atomic systems that influence the treatment of doppler averaging. First, rydiqule's equations of motion are single atom, meaning that atom-atom interactions are ignored. Second, rydiqule only solves these equations under the optically-thin assumption, meaning that input parameters do not change. In particular, absorption of the optical fields through an extended ensemble is not considered.

Both assumptions greatly simplify doppler averaging. Specifically, these assumptions allow us to further assume that atoms in different velocity classes do not interact, meaning that doppler averaging entails a simple weighted average of the atomic response at different velocities by the velocity distribution.

The basic process under these assumptions is as follows:

- 1. Calculate the density matrix solutions to the equations of motion for a wide range of velocity classes.
- 2. Weight the density matrix solutions with the Maxwell-Distribution, assigning the relative atomic density per velocity class to each solution.
- 3. Sum the weighted solutions.

Note that rydiqule assumes a three dimensional distribution of velocities, as is the case for a vapor.

### 5.4.2 Choosing Velocity Classes to Calculate

The primary influence of doppler velocities on the atomic physics is via Doppler shifts of the applied optical fields: defined as  $\Delta = \vec{k} \cdot \vec{v}$ , where  $\vec{k} = 2\pi/\lambda \cdot \hat{k}$  is the k-vector of the the optical field and  $\vec{v}$  is the velocity vector of the atomic velocity class in question. The Doppler shift experienced by an atom is due to the sum of Doppler shifts from each component projection of the atomic velocity relative to the k-vector of the field. In practice, the optical fields are often configured such that there is a basis where some of the k-vector components are zero, reducing the number of dimensions that need to be considered. In the simplest case, all optical fields are colinear, meaning all Doppler shifts are due to velocities projected along a single axis.

Choosing which velocity classes to calculate when performing doppler averaging is a fairly complex meshing problem. Our ultimate goal is to numerically approximate a continuous integratal in one to three dimensions using a discrete sum approximation. For thermal vapors, where the spread of doppler velocities is large, resulting in Doppler shifts much greater than other detunings, linewidths, or Rabi frequenices in the problem, most velocity classes only contribute minor incoherent absorption to the final result. This allows for much coarser meshes. The difficulty lies in determining which velocity classes, a-priori, can participate in generally narrow coherent processes. This difficulty scales with the number of optical fields in the problem, as each new field increases the number of possible coherent resonances.

In rydiqule, we have striven to keep the specification of Doppler classes fairly flexible, with the constraint that velocity classes along each averaged dimension are the same (ie a rectangular grid). These classes are calculated in the *doppler\_classes()* function, which contains options for complete user specification of all classes, as well as some convenience distributions that can be specified via a few parameters.

### 5.4.3 Maxwell-Boltzmann Distribution

Given that rydiqule gives single-atom solutions, the total atomic response for a given set of parameters is directly proportional to the total number of atoms represented by those parameters. The Maxwell-Boltzmann distribution is used to determine the fraction of the total population that is in each velocity class.

Following the conventions used by the Wikipedia page for the Maxwell-Boltzmann Distribution, the distribution of velocities for an ensemble of three dimensions is

$$f_{\vec{v}(v_x,v_y,v_z)=\left(\frac{m}{2\pi kT}\right)e^{-\frac{m}{2kT}\left(v_x^2+v_y^2+v_z^2\right)}}$$

Here,  $v_i$  represents the atomic velocity component along the cartesian axes, k is Boltzmann's constant, T is the ensemble temperature in Kelvin, and m is the atomic mass in kilograms.

This distribution has a number of general properties. To begin, it is normalized such that integrating over all velocities in 3D space will give unity. There are also a few characteristic speeds associated with this 3D distribution: the most

probable speed  $v_p$ , the mean speed  $\langle v \rangle$ , and the rms speed  $v_{rms}$ .

$$v_{p} = \sqrt{\frac{2kT}{m}}$$

$$\langle v \rangle = \sqrt{\frac{8kT}{\pi m}}$$

$$v_{rms} = \sqrt{\frac{3kT}{5.3}}$$
(5.1)

Note that speed is defined as the magnitude of the velocity vector. Also note that all of these quantities are related to each other by simple numerical prefactors. Finally, observe that the distribution above can be easily separated into each cartesian component.

$$\frac{f}{\vec{v} = \prod_i \frac{1}{v_p \sqrt{\pi}}} e^{-\frac{-v_i^2}{v_p^2}}$$

Note that the velocity distribution of each spatial component of the velocity is independently normalized. This allows us to readily produce the appropriate weighting distribution for 1, 2 and 3 dimensional averages as needed without having to perform redundant calculations of distributions where the density matrices to be averaged do not depend on a particular  $v_i$ . This function is implemented in gaussian3d().

### 5.4.4 Doppler Averaging

Given the above assumptions, the doppler average of the density matrix solutions is given by the integral

$$\bar{\rho_{ij}} = \int \rho_{ij}(\vec{v}) f_{\vec{v}d^3v}$$

This integral is numerically approximated via a finite sum.

$$\bar{\rho_{ij}} \approx \sum_{klm} \rho_{ij}(v_k, v_l, v_m) f_{\vec{v}(v_k, v_l, v_m) \Delta v_k \Delta v_l \Delta v_m}$$

In rydiqule, the weighting function  $f_{\vec{v}}$  is implemented in gaussian3d(), the volume element  $\Delta v_k \Delta v_l \Delta v_m$  is calculated as the product of the gradients along each axis as calculated by numpy.gradient() on the specified velocity classes.

We again note that when all k-vectors along a particular axis are zero,  $\rho_{ij}(v_k, v_l, v_m)$  is constant along that axis and that axis of the sum can be separated and assumed to sum to unity due to normalization of the weighting distribution along each dimension.

### 5.4.5 Rydiqule's Implementation

Rydiqule's implementation of Doppler averaging is optimized to minimize duplicate calculations and fully leverage numpy's vectorized and broadcasting operations. The general steps are are follows:

- 1. Choose the doppler velocities to use for the mesh in the average.
- 2. Generate the Equations of Motion (EOMs) for the base zero velocity class using the machinery described in *Equations of Motion Generation*.
- 3. Generate the part of the EOMs that are proportional to the atomic velocity components  $v_i$ . This is done by generating EOMs for the system with all parameters set to zero except for the optical detunings with associated non-zero k-vector components  $k_i$ .
- 4. Generate the complete set of EOMs for all velocity classes via a broadcasting sum of the base EOMs with the Doppler EOMs multiplied by the velocity classes along each axis. Each non-zero spatial axis that is to be summed over is pre-pended as an axis to the EOM tensor, as described in *Stacking Conventions*.
- 5. Solve the entire stack of EOMs.

- 6. Weight the EOMs according to their velocity classes via the Maxwell-Boltzmann distribution and the discrete velocity volume element, as described above.
- 7. Sum the solutions along the velocity axes.

Of particular note is the somewhat unconventional definition that Rydiqule uses for the "k-vector" of each optical field. To begin, all quantities in the EOMs are given in units of Mrad/s, so the "k-vector" must be defined so that multiplication by the velocity in m/s will produce these scaled units. Second, the "k-vector" defined for each coupling is *not* the optical k-vector, but rather the associated vector of most probable Doppler shift.

$$K_i = k_i v_p$$

where  $k_i$  is the optical k\_vector component along the *i*-th axis,  $v_p$  is the most probable speed. The Doppler shift is found by multiplying  $K_i$  by  $d_i$ , the normalized velocity along the *i*-th axis. The velocity along the *i*-th axis is given by  $v_i = v_p d_i$ .

This construction has two benefits. First, it allows for meshes (ie velocity classes) to be defined in a general way relative to the distribution width  $v_p$ , making them easily re-usable for any velocity distribution that obeys the Maxwell-Boltzmann distribution. Second, it allows the user the flexibility to define non-symmetric Doppler distributions, such as would be found in an atomic beam. This is done by defining the optical field "k-vectors" as  $K_i = k_i v_{p_i}$ , where  $v_{p_i}$  is the most probable speed along each axis. When doing this, the prefactor applied to the sum in gaussian3d() will need to be modified for quantitative accuracy.

# 5.5 Time-Dependence

### 5.5.1 Introduction

This document discusses how rydiqule implements time-dependent couplings between states. It discusses the how to define these couplings in terms of the relevant coupling parameters as well as some theoretical considerations when working in the rotating wave approximation.

### 5.5.2 Time-Dependent Couplings

The general form for a time-dependent field is

$$A(t)\cos(\omega(t)t + \phi(t))$$

As it will be helpful later, we will break each time-dependent component into relevant static and time-dependent parts. So  $A(t) \equiv A_0(1 + A_t(t))$ ,  $\phi(t) \equiv \phi_0 + \phi_t(t)$ , and  $\omega(t) \equiv \omega_0 + \Delta + \omega_t(t)$ . Note that we have made an explicit choice to allow for a static detuning relative to a static rotating-frame frequency  $\omega_0$ .

### 5.5.3 Rydiqule Coupling Parameters for Time dependence

When defining a coupling in rydiqule, there are three parameters that define the time-dependence, all specified using specific keys in the coupling dictionary.

- 1. The amplitude scale factor: 'rabi\_frequency' or 'e\_field'. A constant scalar that multiplies the time-dependence function. Only one can be defined. If 'e\_field' is defined, the corresponding dipole moment is used internally to convert it to a Rabi frequency. Rydiqule will automatically apply the factor of 1/2 from the RWA when building the Hamiltonian.
- 2. The normalized time dependence function: 'time\_dependence'. A python function that takes a single argument, *t*. It is normalized such that a value of 1 corresponds to the field amplitude set by 'rabi\_frequency' or 'e\_field'.

3. The static detuning from the rotating frame: 'detuning'. A constant scalar that defines a fixed detuning relative to the rotating frame. When set, this implicitly defines the coupling in the rotating frame defined by  $\omega_0$  with the Rotating Wave Approximation applied. Rydiqule's convention is that positive detunings represent a blue detuning relative to the atomic transition (ie photon has more energy than the energy difference between the levels).

Defining the time-dependence in this way allows us to efficiently construct the time-dependent equations of motion (EOMs) as an expansion of EOMs proportional to each time-dependent function. If we let  $M_i$  be an EOM tensor,  $A_i$  the amplitude scale factor,  $\Delta_i$  the detuning, and  $f_i(t)$  the time-dependent function, we can express this expansion as

$$M_{tot} = M_0(\Delta_i, \ldots) + \sum M_i(A_i) \cdot f_i(t)$$

Note that  $M_0$  represents the steady-state EOMs which includes the static detunings for all of the couplings, time-dependent or not.

### 5.5.4 Example Time-Dependencies

We now provide a few examples of how to write a time-dependent field coupling into the parameters exposed by rydiqule.

#### **RF Heterodyne**

In this situation, we want to couple a single transition with two fields with a small detuning between them. One field is the local oscillator (LO), which has constant amplitude, frequency, and phase. It is detuned from the transition resonance by  $\Delta_{LO}$ . The second field is the signal (S), and is detuned from the LO by a frequency  $\delta_S$ . It's amplitude is fixed and smaller than the LO amplitude. The phase and frequency of this field is fixed.

One can write this total field as

$$E_{tot} = E_{LO} + E_S = E_{LO}\cos((\omega_0 + \Delta_{LO})t) + E_S\cos((\omega_0 + \Delta_{LO} + \delta_S)t)$$

To convert to rydiqule parameters, we first move to the rotating frame defined by the transition frequency  $\omega_0$ . We then separate the constant amplitude prefactor from the normalized time-dependence.

$$E_{tot-rwa} = \frac{E_{LO}}{2} \left( 1 + \frac{E_S}{E_{LO}} e^{i\delta_S t} \right)$$

Note that the rotating wave approximation has discarded the counter-rotating term from cos, leaving the single complex exponential in the time-dependence.

The three rydiqule parameters are now defined as

- 1. Constant amplitude:  $E_{LO}$
- 2. Time-dependence:  $\left(1 + \frac{E_S}{E_{LO}}e^{i\delta_S t}\right)$
- 3. Detuning:  $\Delta_{LO}$

The constant amplitude does not include the factor of 2 from the rotating wave approximation because rydiqule will automatically add it if the detuning coupling parameter is provided. Note that the detuning parameter corresponds to the diagonal term of the resulting RWA hamiltonian.

#### **Non-Rotating Frame**

In some instances, one may wish to solve for a time-dependent coupling outside the rotating frame approximation. This situation is signaled to rydiqule by not defining the 'detuning' parameter of the relevant coupling.

As an example, we can consider the rf heterodyne field coupling in Eq. \ref{eq:heterodyne\_field}. The rydiqule parameters without the rotating wave approximation would be

- 1. Constant amplitude:  $E_{LO}$
- 2. Time-dependence:  $\cos((\omega_0 + \Delta_{LO})t) + \frac{E_{LO}}{E_S}\cos((\omega_0 + \Delta_{LO} + \delta_S)t)$
- 3. Detuning: undefined

Note that in this case, a factor of 1/2 will not be applied by rydiqule to the amplitude.

#### Frequency Sweep in the Rotating-Frame

In this situation, we want to work in a rotating frame which will remove the bulk of the field's frequency, relaxing the time solver's timesteps. We assume a fixed amplitude and a linear frequency sweep through resonance at a rate b, starting at detuning  $-\delta_0$ .

This field coupling is written as

$$\Omega(t) = \Omega_0 \cos(\phi(t))$$

where

$$\phi(t) = \int_0^t \omega(\tau) d\tau$$

and  $\omega(t) = \omega_0 + bt - \delta_0$ .

The field coupling with the integration performed is

$$\Omega(t) = \Omega_0 \cos((\omega_0 - \delta_0)t + \frac{bt^2}{2})$$

Moving to the rotating frame and re-writing to match rydiqule's inputs we have

$$\Omega_{rwa}(t) = \frac{\Omega_0}{2} e^{\frac{ibt^2}{2}}$$

The three rydiqule parameters are now defined as

- 1. Constant amplitude:  $\Omega_0$
- 2. Time-dependence:  $e^{\frac{ibt^2}{2}}$
- 3. Detuning:  $-\delta_0$

#### **Static Phase Offsets**

When doing time-dependent calculations of multi-photon coherent effects to study steady-state spectra (eg studying response to frequency modulations), it can be helpful to set random static phase offsets to the couplings to help the solution converge to steady-state faster. If this isn't done, you often observe are large transient at t = 0 due to all fields being approximately coherent even if their frequencies are different.

The field coupling is

$$\Omega(t) = \Omega_0 \cos((\omega_0 + \Delta)t + \phi_0)$$

This phase offset can be moved to the static amplitude scaling factor, reducing the computational complexity of the time-dependence.

$$\Omega_{rwa}(t) = \frac{\Omega_0}{2} e^{i\phi_0}$$

The three rydiqule parameters are now defined as

- 1. Constant amplitude:  $\Omega_0 e^{i\phi_0}$
- 2. Time-dependence: undefined
- 3. Detuning:  $\Delta$

Note that this coupling does not have time-dependence and would be solved as a steady-state field by not setting the time\_dependence coupling parameter.

#### **Closed-Loops**

If your system involves a closed-loop of couplings (ie there is a circular coupling path), you have to track the overall phase of the circular path when moving to a rotating frame. In particular, a time-dependent phase will accumulate in the loop if any of the couplings in the loop have non-zero detuning from atomic resonance.

Modelling a diamond scheme in a four-level atom would have the following four couplings.

$$\Omega^{(a)}(t) = \Omega_a \cos((\omega_1 + \delta_a)t + \phi_a)$$

$$\Omega^{(b)}(t) = \Omega_b \cos((\omega_2 + \delta_b)t + 5\phi_b)$$

$$\Omega^{(c)}(t) = \Omega_c \cos((\omega_3 + \delta_c)t + 5\phi_b)$$

$$\Omega^{(d)}(t) = \Omega_d \cos((\omega_4 + \delta_d)t + 5\phi_b)$$
(5.4)

The atomic transition frequencies obey the relationship  $\omega_1 + \omega_2 - \omega_3 - \omega_4 = 0$ , with fields 1 and 4 coupling to the ground state, and fields 2 and 3 coupling the highest excited state. Note that the detunings for each field are defined such that a positive value corresponds to a blue detuning from atomic resonance. The optical frequencies obey the relationship  $\omega_a + \omega_b - \omega_c - \omega_d - \Delta = 0$ , where  $\Delta = \delta_a + \delta_b - \delta_c - \delta_d$ .

Moving to a rotating frame is a non-unique transformation (ie there are many equally valid choices). This means that the time-dependent phase due to non-zero detuning of any field could be accounted for on any of the field couplings in a self-consistent way. However, rydiqule makes an explicit choice for the rotating frame via its shortest path determination of the graph for each state. Accurate modelling requires writing the couplings in the specific rotating frame chosen by rydiqule.

The basic choice made by rydiqule is to use the shortest path from the lowest index node of the connected sub-graph (typically 0). If there are multiple shortest paths (ie multiple paths with the same shortest length), only one is returned. Typically it is the first equal-length path traversed by the algorithm. Which one that depends on internals of python (namely dictionary ordering).

Because of these choices, rydiqule will choose multiple branching paths from the ground state in a closed-loop. In order to correctly define the rotating frame, you must ensure that your couplings are defined in rydiqule such that each path is relative to the ground state. An example can demonstrate this subtlety.

In rydiqule code, the above couplings would be defined as (ignoring time dependence)

```
fa = {'states':(0,1), 'detuning':delta_a, 'rabi_frequency':Omega_a, 'phase':phi_a}
fb = {'states':(1,2), 'detuning':delta_b, 'rabi_frequency':Omega_b, 'phase':phi_b}
fc = {'states':(3,2), 'detuning':delta_c, 'rabi_frequency':Omega_c, 'phase':phi_c}
fd = {'states':(0,3), 'detuning':delta_d, 'rabi_frequency':Omega_d, 'phase':phi_d}
s = rq.Sensor(4)
s.add_couplings(fa,fb,fc,fd)
```

Note that we have set the fc coupling with reversed ordering to indicate state 2 has higher energy than state 3. We can use rydiqule to tell us which rotating frames will be chosen by calling get\_rotating\_frames(). This will return

```
{<networkx.classes.digraph.DiGraph at 0x1ef491e1910>: {0: [0],
1: [0, 1],
3: [0, 3],
2: [0, 1, 2]}}
```

Note that state 3 has been defined directly from ground, instead of the path [0, 1, 2, -3] as is often done when solving this problem on paper. As a result, we have defined the f4 coupling to be (0, 3) instead of (3, 0)to match this convention. This is important since all states need to rotate in a frame that starts from the same state. If we instead defined coupling f4 with 'states': (3, 0), the resulting path for state 3 is [0, -3] indicating state 3 is lower in energy than state 0 because all paths must start at 0. Put another way, all coupling 'states' tuples are assumed to be ordered such that the second state has higher energy than the first.

Rotating the above couplings into rydiqule's default frame is accomplished using the unitary rotation operator

$$\left(\begin{array}{ccccc}
1 & 0 & 0 & 0\\
0 & e^{-it\omega_a} & 0 & 0\\
0 & 0 & e^{-it(\omega_a+\omega_b)} & 0\\
0 & 0 & 0 & e^{-it\omega_d}
\end{array}\right)$$

The couplings now in the rotating wave approximation are

$$\Omega_{rwa}^{(a)}(t) = \frac{\Omega_a}{2} e^{i\phi_a}$$

$$\Omega_{rwa}^{(b)}(t) = \frac{\Omega_b}{2} \delta^{i} \theta$$

$$\Omega_{rwa}^{(c)}(t) = \frac{\Omega_c}{2} e^{-i\phi_c} e^{i(\delta_a + \delta_b - \delta} \delta^{i} \delta^{j} \delta^{i}$$

$$\Omega_{rwa}^{(d)}(t) = \frac{\Omega_c}{2} \delta^{i} \delta^{j} \delta^{j}$$
(5.8)

Note that only coupling  $\pm 3$  has any time-dependence for these CW fields. Obviously, if any of the fields are not CW, that extra time-dependence will need to be accounted for as described in the above examples in addition to the time-dependence described here.

The rydiqule coupling parameters would be written as (letting i = [a, b, c, d])

- 1. Constant amplitude:  $\Omega_i e^{i\phi_i}$  with f3 differing by a sign  $\Omega_d e^{-i\phi_c}$
- 2. Time-dependence (coupling f 3 only):  $e^{i(\delta_a + \delta_b \delta_c \delta_d)t}$
- 3. Detuning:  $\delta_i$  with  $\delta_c$  not actually being inserted on the diagonal of the hamiltonian

# **API DOCUMENATION**

| rydiqule | Parent computational module. |
|----------|------------------------------|

# 6.1 rydiqule

Parent computational module.

### Modules

| rydiqule.atom_utils      | Utilities for interacting with atomic parameters and     |
|--------------------------|--|
|                          | ARC.   |
| rydiqule.cell            | Physical Cell objects for use in solvers.                |
| rydiqule.doppler_utils   | Utilities for implementing Doppler averaging             |
| rydiqule.experiments     | Standard methods for converting results to physical val- |
|                          | ues.   |
| rydiqule.rydiqule_utils  | General rydiqule package utilities                       |
| rydiqule.sensor          | Sensor objects that control solvers.                     |
| rydiqule.sensor_solution | Bunch-like object use to store aspects of a solution     |
|                          | when calling rydiule.solve() Adds essential keys with    |
|                          | "None" entries   |
| rydiqule.sensor_utils    | Utilities used by the Sensor classes.                    |
| rydiqule.slicing         |  |
| rydiqule.solvers         | Steady-state solvers of the Optical Bloch Equations.     |
| rydiqule.stack_solvers   |  |
| rydiqule.timesolvers     | Solvers for time domain analysis with an arbitrary RF    |
|                          | field  |

# 6.1.1 rydiqule.atom\_utils

Utilities for interacting with atomic parameters and ARC.

### **Module Attributes**

| ATOMS | Alkali atoms defined by ARC that can be used with |
|-------|---|
|       | Cell.   |

#### rydiqule.atom\_utils.ATOMS

```
rydiqule.atom_utils.ATOMS = {'Cs': <class 'arc.alkali_atom_data.Caesium'>,
'H': <class 'arc.alkali_atom_data.Hydrogen'>, 'K39': <class
'arc.alkali_atom_data.Potassium39'>, 'K40': <class
'arc.alkali_atom_data.Potassium40'>, 'K41': <class
'arc.alkali_atom_data.Potassium41'>, 'Li6': <class
'arc.alkali_atom_data.Lithium6'>, 'Li7': <class
'arc.alkali_atom_data.Lithium7'>, 'Na': <class
'arc.alkali_atom_data.Sodium'>, 'Rb85': <class
'arc.alkali_atom_data.Rubidium85'>, 'Rb87': <class
'arc.alkali_atom_data.Rubidium87'>}
```

Alkali atoms defined by ARC that can be used with Cell.

### **Functions**

| D1_states(n)                              | Retrieve the quantum numbers for the states corre-   |
|---|--|
|   | sponding to the D1 line for a given Rydberg atom or  |
|   | principle quantum number.                            |
| D2_states(n)                              | Retrieve the quantum numbers for the states corre-   |
|   | sponding to the D2 line for a given Rydberg atom or  |
|   | principle quantum number.                            |
| calc_eta(omega, dipole_moment, beam_area) | Calculates the eta constant needed from some experi- |
|   | ment calculations                                    |
| calc_kappa(omega, dipole_moment, density) | Calculates the kappa constant needed for observable  |
|   | calculations.  |

#### rydiqule.atom\_utils.D1\_states

rydiqule.atom\_utils.D1\_states (n: Union[int, str])

Retrieve the quantum numbers for the states corresponding to the D1 line for a given Rydberg atom or principle quantum number.

#### Parameters

**n** (*int* or *str*) – Either the string flag of the atom or the principle quantum number n of an atom. If string, must begin with ['H', 'Li', 'Na', 'K', 'Rb', 'Cs'].

#### Returns

- *list* Quantum numbers [n, l, j, m] of the atoms ground state.
- *list* Quantum numbers [n, l, j, m] of the first excited state corresponding to the D1 line of the Rydberg atom.

#### rydiqule.atom\_utils.D2\_states

rydiqule.atom\_utils.D2\_states (n: Union[int, str])

Retrieve the quantum numbers for the states corresponding to the D2 line for a given Rydberg atom or principle quantum number.

#### Parameters

**n** (*int* or *str*) – Either the string flag of the atom or the principle quantum number **n** of an atom. If string, must begin with ['H', 'Li', 'Na', 'K', 'Rb', 'Cs'].

Returns

- *list* Quantum numbers [n, l, j, m] of the atoms ground state.
- *list* Quantum numbers [n, l, j, m] of the first excited state corresponding to the D2 line of the Rydberg atom.

#### rydiqule.atom\_utils.calc\_eta

```
rydiqule.atom_utils.calc_eta(omega: float, dipole_moment: float, beam_area: float) → float
```

Calculates the eta constant needed from some experiment calculations

The value is computed with the following formula Eq. 7 of Meyer et. al. PRA 104, 043103 (2021)

$$\eta = \sqrt{\frac{\omega\mu^2}{2c\epsilon_0\hbar A}}$$

Where  $\omega$  is the probing frequency,  $\mu$  is the dipole moment, A is the beam area, c is the speed of light,  $\epsilon_0$  is the dielectric constant, and  $\hbar$  is the reduced Plank constant.

#### Parameters

- **omega** (*float*) The atomic transition frequency, in rad/s
- **dipole\_moment** (*float*) The atomic transition dipole moment, in C\*m
- beam\_area (float) The cross-sectional area of the beam, in m<sup>2</sup>

#### Returns

The value of eta, in root(Hz)

**Return type** 

float

### rydiqule.atom\_utils.calc\_kappa

rydiqule.atom\_utils.calc\_kappa (*omega: float, dipole\_moment: float, density: float*)  $\rightarrow$  float Calculates the kappa constant needed for observable calculations.

The value is computed with the following formula Eq. 5 of Meyer et. al. PRA 104, 043103 (2021)

$$\kappa = \frac{\omega n \mu^2}{2c\epsilon_0 \hbar}$$

Where  $\omega$  is the probing frequency,  $\mu$  is the dipole moment, n is atomic cloud density, c is the speed of light,  $\epsilon_0$  is the dielectric constant, and  $\hbar$  is the reduced Plank constant.

#### Parameters

- omega (float) Atomic transition frequency, in rad/s
- dipole\_moment (float) Dipole moment of the atomic transition, in C\*m
- **density** (float) The atomic number density, in m<sup>(-3)</sup>

**Returns** The value of kappa, in (rad/s)/m

Return type

float

### 6.1.2 rydiqule.cell

Physical Cell objects for use in solvers.

#### Classes

| Cell(atom_flag, *atomic_states[,]) | Subclass of Sensor that creates a Sensor with addi-    |
|------------------------------------|--|
|                                    | tional physical properties corresponding to a specific |
|                                    | Rydberg atom.  |
|                                    |  |

#### rydiqule.cell.Cell

Bases: Sensor

Subclass of *Sensor* that creates a Sensor with additional physical properties corresponding to a specific Rydberg atom.

In addition to the core functionality of ~.Sensor, this class allows for labelling of states with quantum numbers, calculating of state lifetimes and decoherences and tracking of of some physical laser parameters. A key distictinction between a *Cell* and a *Sensor* is that a cell supports (and requires) and absolute ordering of energy between states, which allows for implicit calculation of decay rates an transition frequencies.

\_\_init\_\_\_(atom\_flag: Literal['H', 'Li6', 'Li7', 'Na', 'K39', 'K40', 'K41', 'Rb85', 'Rb87', 'Cs'], \*atomic\_states: Sequence, cell\_length: float = 0.001, gamma\_transit: Optional[float] = None, beam\_area: float = 1e-06, beam\_diam: Optional[float] = None, temp: float = 300.0, probe\_tuple: tuple = (0, 1)) → None

Initialize the Rydberg cell from the given parameters.

#### Parameters

- atom\_flag (*str*) Which atom is used in the cell for calculating physical properties with ARC Rydberg. One of ['H', 'Li6', 'Li7', 'Na', 'K39', 'K40', 'K41', 'Rb85', 'Rb87', 'Cs'].
- **atomic\_states** (*list[list]*) List of states to be added to the cell. Each state is an iterable whose elements are each a list of the form [n, l, j, m], representing the Rydberg atomic quantum numbers of the state. At least two states must be added so that the system is nontrivial. The number of states will determine the basis size of the system. Note that the first state in the list is assumed to be a meta-stable ground.
- **cell\_length** (*float*) Length of the atomic vapor in meters.
- gamma\_transit(float, optional) Decoherence due to atom transit through the optical beams. Specified in units of Mrad/s. If None, will calculate based on value of beam\_area. See add\_transit\_broadening() for details on how transit broadening is treated. Default is None.
- **beam\_area** (*float*, *optional*) Area of probing field cross-section in m^2. Used to calculate kappa and gamma\_transit. Default is 1e-6.

- **beam\_diam**(*float*, *optonal*)-Diameter of the probing field cross section in meters. Used to calculate gamma\_transit. If None, it is calculated from beam\_area assuming the beam cross-section is a circle. Default is None.
- temp (float, optional) Temperature of the gas in Kelvin. Used in calculations of enery level lifetime. Default is 300 K.

### Raises

- **ValueError** If at least two atomic states are not provided.
- ValueError If atom\_flag is not one of ARC's supported alkali atoms.

### Methods

| init(atom_flag, *atomic_states[,])                 | Initialize the Rydberg cell from the given param-     |
|--|---|
|  | eters.  |
| add_coupling(states[, rabi_frequency,])            | Overload of add_coupling() which allows for           |
|  | different specification of coupling fields which are  |
|  | more reflective of real experimental setups.          |
| add_couplings(*couplings, **extra_kwargs)          | Add any number of couplings between pairs of          |
|  | states.   |
| add_decoherence(states, gamma[, label])            | Add decoherent coupling to the graph between two      |
|  | states.   |
| _add_energy_shift(state, shift)                    | Add an energy shift to a state.                       |
| _add_energy_shifts(shifts)                         | Add multiple energy shifts to different nodes.        |
| <pre>add_self_broadening(node, gamma[, la-</pre>   | Specify self-broadening (such as collisional broad-   |
| bel])  | ening) of a level.                                    |
| add_states()                                       | Deprecated.   |
| <pre>add_transit_broadening(gamma_transit[,</pre>  | Adds transit broadening by adding a decoherence       |
| ])   | from each node to ground.                             |
| axis_labels([collapse, full_labels])               | Get a list of axis labels for stacked hamiltonians.   |
| <pre>couplings_with(*keys[, method])</pre>         | Returns a version of self.couplings with only the     |
|  | keys specified.                                       |
| decoherence_matrix()                               | Get the decoherence matrix for a system.              |
| dm_basis()   | Generate basis labels of density matrix components.   |
| <pre>get_cell_dipole_moment(state1, state2[,</pre> | Get the diploe moment between 2 cell state.           |
| <u>q])</u>   |   |
| get_cell_hfs_coefficient(state)                    | Get the hyperfine splitting coefficients of the given |
|  | state using ARC.                                      |
| get_cell_hfs_shift(state)                          | Return the hyperfine energy shift for the given hy-   |
|  | perfine state.  |
| <pre>get_cell_tansition_frequency(state1,</pre>    | Get the transition frequency between 2 states, ac-    |
| state2)  | counting for hyperfine splitting.                     |
| get_coupling_rabi([coupling_tuple])                | Helper function that returns the Rabi frequency of    |
|  | the coupling from a Sensor for use in functions that  |
|  | return experimental values.                           |
| get_couplings()                                    | Returns the couplings of the system as a dictionary   |
| get_doppler_shifts()                               | Returns the Hamiltonian with only detunings set to    |
|  | the kvector values for each spatial dimension.        |
| get_hamiltonian()                                  | Creates the Hamiltonians from the couplings defined   |
|  | by the fields.  |
| get_namiltonian_diagonal(values[,                  | Apply addition and subtraction logic corresponding    |
| no_stack])   | to the direction of the couplings.                    |
| get_parameter_mesh()                               | Keturns the parameter mesh of the sensor.             |
| get_qnums(state)                                   | Gets the quantum numbers for a given states.          |

continues on next page

|   | a nom previous page                                  |
|---|--|
| get_rotating_frames()                               | Determines the rotating frames for the disconnected  |
|   | subgraphs.   |
| get_state_num(state)                                | Return the integer number in the bases of a node     |
|   | with the given quantum numbers.                      |
| get_time_couplings()                                | Returns the list of matrices of all couplings in the |
|   | system defined with a time_dependence key.           |
| get_time_dependence()                               | Function which returns a list of the time_depen-     |
|   | dence functions.                                     |
| get_time_hamiltonians()                             | Get the hamiltonians for the time solver.            |
| get_transition_frequencies()                        | Gets an array of the diagonal elements of the Hamil- |
|   | tonian from the field detunings.                     |
| get_value_dictionary(key)                           | Get subset of dictionary coupling parameters.        |
| level_ordering()                                    | Return a list of the integer numbers of each state   |
|   | (not the quantum numbers) in descending order by     |
|   | energy order.  |
| <pre>set_experiment_values(probe_tuple,[,</pre>     | Sensor specific method.                              |
| ])  |  |
| _set_gamma_matrix(gamma_matrix)                     | Set the decoherence matrix for the system.           |
| spatial_dim()                                       | Returns the number of spatial dimensions doppler     |
|   | averaging will occur over.                           |
| states_list()                                       | Returns a list of quantum numbers for all states in  |
|   | the cell.  |
| states_with_label(label)                            | Return a dict of all states with a label matching a  |
|   | given regular expression (regex) pattern.            |
| <pre>unzip_parameters(zip_label[, verbose])</pre>   | Remove a set of zipped parameters from the internal  |
|   | zipped_parameters list.                              |
| <pre>variable_parameters([apply_mesh])</pre>        | Property to retrieve the values of parameters that   |
|   | were stored on the graph as arrays.                  |
| <pre>zip_parameters(*parameters[, zip_label])</pre> | Define 2 scannable parameters as "zipped" so they    |
|   | are scanned in parallel.                             |

Table 6.1 - continued from previous page

### Attributes

| basis_size  | Property to return the number of nodes on the Sen-     |
|-------------|--|
|             | sor graph.   |
| beam_area   | Cross-sectional area of the probing beam, in square    |
|             | meters.  |
| cell_length | Optical path length of the medium, in meters.          |
| eta         | Get the eta value for the system.                      |
| kappa       | Property to calculate the kappa value of the system.   |
| probe_freq  | Get the probe transition frequency, in rad/s           |
| probe_tuple | Coupling edge that corresponds to the probing field.   |
| states      | Property which gets a list of labels for the sensor in |
|             | the order defined in().                                |

**\_add\_coupling** (*states: Tuple[Union[int, str]*, *Union[int, str]*], \*\*field\_params)  $\rightarrow$  None

Function for internal use which will ensure the supplied couplings is valid, add the field to self.couplings.

Exists to abstract away some of the internally necessary bookkeeping functionality from user-facing classes.

#### **Parameters**

• **states** (*tuple*) – The integer pair of states to be coupled.

• **\*\*field\_params** (*dict*) – The dictionry of couplings parameters. For details on the keys of the dictionry see *add\_coupling()*.

#### \_add\_decay\_to\_graph() $\rightarrow$ None

Internal helper method to add population decay rates to the nodes to calculate gamma matrix.

- 1. add the state lifetime to each node
- 2. add the transition rate to each edge

#### **\_add\_state** (*state: Sequence*) $\rightarrow$ None

Internal method to add a single state to the Cell.

Should only be used by the \_add\_states() function, but can be overloaded in custom implementations of Cell

#### **Parameters**

```
state (int or list of ints) – The quantum numbers of the state to be added.
Should be either length 4 of form [n, l, j, m] or length 5 of form [n, l, j, F, mF]
```

#### **\_add\_states** (\**states: Sequence*) $\rightarrow$ None

Internal method to add states to the system and update internal variables for energy and decay rates.

Quantum numbers and other states information are stored on the couplings graph nodes. The first state added to the system is treated as the ground state, and all "absolute energies" are calculated as a difference from ground. Should only be called in  $\__init\__()$ .

#### **Parameters**

**\*states** (*list[list[int or float]]*) – States that are added to the list of atomic states of interest for the cell. Arguments should be lists of the form [n, l, j, m], where n, l, j, and m are the usual quantum numbers describing the state: principal, orbital, total angular momentum, and magnetic quantum numbers respectively.

#### \_collapse\_mesh(mesh)

Collapses the given mesh using rydiqule logic for parameter zipping.

Expected to be given a mesh which is generated by applying numpy.meshgrid function on the output of *variable\_parameters()* for the system. Given such a mesh, ensures that output mesh matches the shape expected by rydiqule's stacking convention, meaning that parameters that are zipped together will share an axis in the hamiltonian stack.

#### Parameters

**mesh** (tuple (numpy.ndarray)) – The uncollapsed meshgid of parameters for the system. Typically the output of numpy.meshgrid called on variable\_parameters().

#### Returns

The collapsed meshgid with zipped parameters sharing and axis.

#### Return type

tuple(np.ndarray)

#### \_coupling\_with\_label (*label: str*) → Tuple[Union[int, str], Union[int, str]]

Helper function to return the pair of states corresponding to a particular label string. For internal use.

#### \_remove\_edge\_data (states: Tuple[Union[int, str], Union[int, str]], kind: str)

Helper function to remove all data that was added with a *add\_coupling()* call or *add\_decoher-ence()* call. Needed to ensure that two nodes do not have coherent couplings pointing both ways and to invalidate existing zip parameter couplings.

#### **Parameters**

- **states** (*tuple*) Edge from which to remove data.
- **kind** (*str*) What type of data to remove. Valid options are coherent coherent couplings or the incoherent key to be cleared (must start with gamma).

Raises

ValueError - If kind is not 'coherent' and doesn't begin with 'gamma'

**\_stack\_shape** (*time\_dependence: Literal['steady', 'time', 'all']* = 'all')  $\rightarrow$  Tuple[int, ...]

Internal function to get the shape of the tuple preceding the two hamiltonian axes in get\_hamiltonian()

**\_states\_valid** (*states: Sequence*)  $\rightarrow$  Tuple[Union[int, str], Union[int, str]]

Confirms that the provided states are in a valid format.

Typically used internally to validate states added. If provided as a form other than a tuple, first casts to a tuple for consistent indexing.

Checks that states contains 2 elements, can be interpreted as a tuple, and that both states lie inside the basis.

#### Parameters

**states** (*iterable*) – iterable of to validate. Should be a pair of integers that can be cast to a tuple.

Returns

Length 2 tuple of validated state labels.

**Return type** 

tuple

Raises

- ValueError If states has more than two elements.
- **TypeError** If states cannot be converted to a tuple.
- ValueError If either state in states is outside the basis.

#### \_validate\_qnums (qnums: Sequence)

Validate the quantum numbers provided are appropriately formated and cast to a list.

States should either be 4 quantum numbers [n, l, j, m\_j] for a pure electron angular momentum state or 5 quantum numbers [n, l, j, F, m\_F] for a hyperfine state.

#### Parameters

**qnums** (*list* (*float*)) – Quantum numbers for the state.

#### Raises

**ValueError** – If the list of quantum numbers is not length 4 or 5.

add\_coupling (states: Tuple[Union[int, str], Union[int, str]], rabi\_frequency: Optional[Union[float,

 $\begin{array}{l} List[float], ndarray]] = None, detuning: Optional[Union[float, List[float], ndarray]] = \\ None, transition_frequency: Optional[float] = None, phase: Union[float, List[float], \\ ndarray] = 0, kvec: Tuple[float, float, float] = (0, 0, 0), time_dependence: \\ Optional[Callable[[float], float]] = None, label: Optional[str] = None, e_field: \\ Optional[Union[float, List[float], ndarray]] = None, beam_power: Optional[float] = \\ None, beam_waist: Optional[float] = None, q: Literal[-1, 0, 1] = 0, **extra_kwargs) \rightarrow \\ None \end{array}$ 

Overload of *add\_coupling()* which allows for different specification of coupling fields which are more reflective of real experimental setups.

Rabi frequency is a mandatory argument in *Sensor* but in *Cell*, there are 3 options for laser power specification:

- 1. Explicit rabi-frequency definition identical to Sensor.
- 2. Electric field strength, in V/m.
- 3. Specification of both beam power and beam waist.

Any one of these options can be used in place of the standard`rabi\_frequency` argument of add\_coupling().

As in *Sensor*, if detuning is specified, the coupling is assumed to act under the rotating-wave approximation (RWA), and transition\_frequency can not be specified. However, unlike in a *Sensor*, if detuning is not specified, in a *Cell*, transition\_frequency will be calculated automatically based on atomic properties rather than taken as an argument.

#### **Parameters**

- **states** (*sequence*) Length-2 list-like object (list or tuple) of integers corresponding to the numbered states of the cell. Tuple order indicates which state to has higher energy: namely the second state is always assumed to have higher energy. This order must match the actual energy levels of the atom.
- **rabi\_frequency** (*float*, *optional*) The rabi frequency, in Mrad/s, of the coupling field. If specified, e\_field, beam\_power, and beam\_waist cannot be specified.
- **detuning** (*float*, *optional*) Field detuning, in Mrad/s, of a coupling in the RWA. If specified, RWA is assumed, otherwise RWA not assumed, and transition frequency will be calculated based on atomic properties.
- transition\_frequency (float, optional) Kept such that method signature matches parent. Value must be None as the transition frequency is calculated from atomic properties.
- **phase** (*float*, *optional*) The relative phase of the field in radians. Defaults to zero.
- **kvec** (*sequence*, *optional*) A three-element iterable that defines the atomic doppler shift on a particular coupling field. It should have magnitude equal to the doppler shift (in the units of Mrad/s) of an atom moving at the Maxwell-Boltzmann distribution most probable speed, vP=np.sqrt(2\*kB\*T/m). I.E. np.linalg. norm(kvec)=2\*np.pi/lambda\*vP. If equal to (0,0,0), solvers will ignore doppler shifts on this field. Defaults to (0,0,0).
- time\_dependence (scalar function, optional) A scalar function that specifies a time-dependent field. The time dependence function is defined as a function that returns a unitless value as a function of time that is multiplied by the rabi\_frequency parameter.
- **label** (*str*, *optional*) The user-defined name of the coupling. This does not change any calculations, but can be used to track individual couplings, and will be reflected in the output of *axis\_labels()* Default None results in using the states tuple as the label.
- **e\_field**(*float*, *optional*) Electric field strenth of the coupling in Volts/meter. If specified, rabi\_frequency, beam\_power, and beam\_waist cannot be specified.
- beam\_power (float, optional) Beam power in Watts. If specified, beam\_waist must also be supplied, and rabi\_frequency and e\_field cannot be specified. beam\_power and beam\_waist cannot be scanned simultaneously.
- **beam\_waist** (*float*, *optional*) 1/e<sup>2</sup> Beam waist (radius) in units of meters. Only necessary when specifying beam\_power.
- q(int, optional) Coupling polarization in spherical basis. Valid values are -1,
   0, 1 for -σ, linear, +σ. Default is 0 for linear.

#### Raises

- **ValueError** If states is not a list-like of 2 integers.
- ValueError If an invalid combination of rabi\_frequency, e\_field, beam\_power, and beam\_waist is provided.

- ValueError If tranistion\_frequency is passed as an argument (it is calculated from atomic properties).
- ValueError If beam\_power and beam\_waist are both sequences.

#### Warns

**UserWarning** – If any coupling has time-dependence specified, which get\_snr cannot currently handle as it is steady-state only.

#### Notes

**Note:** Note that while this function can be used directly just as in *Sensor*, it will often be called implicitly via *add\_couplings()* which Cell inherits. While they are equivalent, the second of these options is often the more clear approach.

Note: Specifying the beam power by beam parameters or electric field still computes the rabi\_frequency and adds that quantity to the Cell to maintain consistency across rydiqule's other calculations. In other words, beam\_power, beam\_waist, and e\_field will never appear as quantities on the graph of a Cell.

#### **Examples**

In the simplest case, physical properties are calculated automatically in a Cell All the familiar quantities are present, as well as many more.

```
>>> cell = rq.Cell("Rb85", *rq.D2_states("Rb85"), cell_length = .0001)
>>> cell.add_coupling(states=(0,1), detuning=1, rabi_frequency=2)
>>> print(dict(cell.couplings.edges))
{(0, 0): {'gamma_transit': 0.41172855461658464, 'label': '(0,0)'},
(0, 1): {'rabi_frequency': 2, 'detuning': 1,
'phase': 0, 'kvec': (0, 0, 0), 'label': '(0,1)'},
(1, 0): {'gamma_transition': 37.829349995476726,
'label': '(1,0)', 'gamma_transit': 0.41172855461658464}}
```

Here we see implicitly calling this overloaded function through add\_couplings().

```
>>> cell = rq.Cell("Rb85", *rq.D2_states("Rb85"), cell_length = .0001)
>>> c = {"states":(0,1), "detuning":1, "rabi_frequency":2}
>>> cell.add_couplings(c)
>>> print(dict(cell.couplings.edges))
{(0, 0): {'gamma_transit': 0.41172855461658464,
'label': '(0,0)'}, (0, 1): {'rabi_frequency': 2, 'detuning': 1,
'phase': 0, 'kvec': (0, 0, 0),
'label': '(0,1)'}, (1, 0): {'gamma_transition': 37.829349995476726,
'label': '(1,0)', 'gamma_transit': 0.41172855461658464}}
```

e\_field can be specified in stead of rabi\_frequency, but a rabi\_frequency will still be added to the system based on the e\_field, rather than e\_field directly.

```
>>> cell = rq.Cell("Rb85", *rq.D2_states("Rb85"), cell_length = .0001)
>>> c = {"states":(0,1), "detuning":1, "e_field":6}
>>> cell.add_couplings(c)
>>> print(cell.couplings.edges(data='e_field'))
>>> print(cell.couplings.edges(data='rabi_frequency'))
[(0, 0, None), (0, 1, None), (1, 0, None)]
[(0, 0, None), (0, 1, -1.172912676105507), (1, 0, None)]
```

As can beam\_power and beam\_waist, with similar behavior regarding how information is stored.

```
>>> cell = rq.Cell("Rb85", *rq.D2_states("Rb85"), cell_length = .0001)
>>> c = {"states":(0,1), "detuning":1, "beam_power":1, "beam_waist":1}
>>> cell.add_couplings(c)
>>> print(cell.couplings.edges(data='beam_power'))
>>> print(cell.couplings.edges(data='rabi_frequency'))
[(0, 0, None), (0, 1, None), (1, 0, None)]
[(0, 0, None), (0, 1, 4.28138982322625), (1, 0, None)]
```

#### add\_couplings (\*couplings: Dict, \*\*extra\_kwargs) $\rightarrow$ None

Add any number of couplings between pairs of states.

Acts as an alternative to calling *add\_coupling()* individually for each pair of states. Can be used interchangably up to preference, and all of keyword *add\_coupling()* are supported dictionary keys for dictionaries passed to this function.

#### **Parameters**

- **couplings** (*tuple of dicts*) Any number of dictionaries, each specifying the parameters of a single field coupling 2 states. For more details on the keys of each dictionry see the arguments for *add\_coupling()*. Equivalent to passing each dictiories keys and values to *add\_coupling()* individually.
- **\*\*extra\_kwargs** (*dict*) Additional keyword-only arguments to pass to the relevant add\_coupling method. The same arguments will be passed to each call of *add\_coupling()*. Often used for warning suppression.

#### Raises

ValueError – If the states parameter is missing.

#### **Examples**

```
>>> s = rq.Sensor(3)
>>> blue = {"states":(0,1), "rabi_frequency":1, "detuning":2}
>>> red = {"states":(1,2), "rabi_frequency":3, "detuning":4}
>>> s.add_couplings(blue, red)
>>> print(s.couplings.edges(data=True))
[(0, 1, {'rabi_frequency': 1, 'detuning': 2, 'phase': 0, 'kvec': (0, 0, 0)}
...,),
(1, 2, {'rabi_frequency': 3, 'detuning': 4, 'phase': 0, 'kvec': (0, 0, 0)}
...,)]
```

Add decoherent coupling to the graph between two states.

If gamma is list-like, the sensor will scan over the values, solving the system for each different gamma, identically to the scannable parameters in coherent couplings.

#### Parameters

- **states** (*tuple of ints*) Length-2 tuple of integers corresponding to the two states. The first value is the number of state out of which population decays, and the second is the number of the state into which population decays.
- gamma (float or sequence) The decay rate, in Mrad/s.
- **label** (*str or None, optional*) Optional label for the decay. If None, decay will be stored on the graph edge as "gamma". Otherwise, will cast as a string and decay will be stored on the graph edge as "gamma\_"+label.

#### Notes

**Note:** Adding a decoherece with a particular label (including None) will override an existing decoherent transition with that label.

#### **Examples**

s = rq.Sensor(3) >>> s.add\_coupling(states=(0,1), detuning=1, rabi\_frequency=1) >>> s.add\_coupling(states=(1,2), detuning=1, rabi\_frequency=1) >>> s.add\_decoherence((2,0), 0.1, label="misc") >>> print(s.decoherence\_matrix()) [[0. 0. 0. ] [0. 0. 0. ] [0.1 0. 0. ]]

Decoherence values can also be scanned. Here decoherece from states 2->0 is scanned between 0 and 0.5 for 11 values. We can also see how the Hamiltonian shape accounts for this to allow for clean broadcasting, indicating that the hamiltonian is identical accross all decoherence values.

```
>>> s = rq.Sensor(3)
>>> gamma = np.linspace(0,0.5,11)
>>> s.add_coupling(states=(0,1), detuning=1, rabi_frequency=1)
>>> s.add_coupling(states=(1,2), detuning=1, rabi_frequency=1)
>>> s.add_decoherence((2,0), gamma)
>>> print(s.decoherence_matrix().shape)
(11, 3, 3)
>>> print(s.get_hamiltonian().shape)
(11, 3, 3)
```

add\_energy\_shift (state: Union[int, str], shift: Union[float, List[float], ndarray])

Add an energy shift to a state.

First perfoms validation that the provided state is actually a node in the graph, then adds the shift specified by shift to a self-loop edge keyed with "e\_shift". This value will be added to the corresponding diagonal term when the hamiltonian is generated. If the provided node

#### **Parameters**

- **state** (*str or int*) The label corresponding to the atomic state to which the shift will be added.
- **shift** (float or list-like of float) The magnitude of the energy shift, in Mrad/s

#### Raises

**KeyError** – If the supplied state is not in the system.

#### add\_energy\_shifts (shifts: dict)

Add multiple energy shifts to different nodes.

Shifts are specified with the shifts dictionary, which is keyed with states and has values corresponding to the energy shift applied to the state in Mrad/s. Error handling and validation is done with the add\_energy\_shift() function.

#### Parameters

**shifts** (*dict*) – Dictionary keyed with states with values corresponding to the energy shift, in Mrad/s, of the corresponding state.

add\_self\_broadening (node: int, gamma: Union[float, List[float], ndarray], label: str = 'self')

Specify self-broadening (such as collisional broadening) of a level.

Equivalent to calling *add\_decoherence()* and specifying both states to be the same, with the "self" label. For more complicated systems, it may be useful to further specify the source of self-broadening as, for example, "collisional" for easier bookkeeping and to ensure no values are overwritten.

#### **Parameters**

- **node** (*int*) The integer number of the state node to which the broadening will be added. The integer corresponds to the state's position in the graph.
- gamma (float or sequence) The broadening width to be added in Mrad/s.
- **label** (*str*, *optional*) Optional label for the state. If None, decay will be stored on the graph edge as "gamma". Otherwise, will cast as a string and decay will be stored on the graph edge as "gamma\_"+label

### Notes

**Note:** Just as with the *add\_decoherence()* function, adding a decoherence value with a label that already exists will overwrite an existing decoherent transition with that label. The "self" label is applied to this function automatically to help avoid an unwanted overwrite.

#### Examples

```
>>> s = rq.Sensor(3)
>>> s.add_self_broadening(1, 0.1)
>>> print(s.couplings.edges(data=True))
>>> print(s.decoherence_matrix())
[(1, 1, {'gamma_self': 0.1, 'label': '(1,1)'})]
[[0.  0.  0. ]
[0.  0.1 0. ]
[0.  0.  0. ]]
```

#### add\_states()

Deprecated.

Use "atomic\_state" keyword argument of the constructor instead.

add\_transit\_broadening (gamma\_transit: Union[float, List[float], ndarray], repop: Union[None, Dict[Union[int, str], float]] = None, label:  $str = 'transit') \rightarrow None$ 

Adds transit broadening by adding a decoherence from each node to ground.

For each graph node n, adds a decoherent transition from n the specified state (0 by default) using the *add\_decoherence()* method with the "transit" label. See *add\_decoherence()* for more details on labeling.

If an array of transit values are provided, they will be automatically zipped together into a single scanning element.

#### **Parameters**

- gamma\_transit (float or sequence) The transit broadening rate in Mrad/s.
- **repop** (*dict*, *optional*) Dictionary of states for transit to repopulate in to. The keys represent the state labels. The values represent the fractional amount that goes to that state. If the sum of values does not equal 1, population will not be conserved. Default is to repopulate everything into the ground state (either state 0 or the first state in the basis passed to the \_\_init\_\_() method).

#### Warns

- If the values of the `repop` parameter do not sum to 1, thus meaning
- population will not be conserved.

#### **Examples**

```
>>> s = rq.Sensor(['g', 'e1', 'e2'])
>>> repop = {'g':0.75, 'e1': 0.25}
>>> s.add_transit_broadening(0.2, repop=repop)
>>> print(s.decoherence_matrix())
[[0.15 0.05 0. ]
[0.15 0.05 0. ]
[0.15 0.05 0. ]]
```

**axis\_labels** (*collapse: bool* = *True*, *full\_labels: bool* = *False*)  $\rightarrow$  List[str]

Get a list of axis labels for stacked hamiltonians.

The axes of a hamiltonian stack are defined as the axes preceding the usual hamiltonian, which are always the last 2. These axes only exist if one of the parametes used to define a Hamiltonian are lists.

Be default, labels which have been zipped using *zip\_parameters()* will be combined into a single label, as this is how *get\_hamiltonian()* treats these axes.

The ordering of axis labels is

Returns

Strings corresponding to the label of each axis on a stack of multiple hamiltonians.

Return type list of str

#### **Examples**

There are no preceding axes if there are no list-like parameters.

```
>>> s = rq.Sensor(3)
>>> blue = {"states":(0,1), "rabi_frequency":1, "detuning":2}
>>> red = {"states":(1,2), "rabi_frequency":3, "detuning":4}
>>> s.add_couplings(blue, red)
>>> print(s.get_hamiltonian().shape())
>>> print(s.axis_labels())
(3,3)
[]
```

Adding list-like parameters expands the hamiltonian

The ordering of labels may change if string state names are used. The ordering is determined by the output of the *variable\_parameters()* method. See method documentation for more detail.

Zipping parameters combines their corresponding labels, since their Hamiltonians now lie on a single axis of the stack. Here the axis of length 7 (axis 0) corresponds to the rabi frequencies and the axis of shape 11 (axis 1) corresponds to the zipped detunings

#### property basis\_size

Property to return the number of nodes on the Sensor graph.

#### Returns

The number of nodes on the graph, corresponding to the basis size for the system.

#### **Return type**

int

#### beam\_area: Optional[float] = None

Cross-sectional area of the probing beam, in square meters.

### cell\_length: Optional[float] = None

Optical path length of the medium, in meters.

**couplings\_with** (\*keys: str, method: Literal['all', 'any', 'not any'] = 'all')  $\rightarrow$  Dict[Tuple[Union[int, str], Union[int, str]], Dict]

Returns a version of self.couplings with only the keys specified.

Can be specified with a several criteria, including all, none, or any of the keys specified.

#### Parameters

- **str**) (*keys* (*tuple of*) parameter names for a state. See *add\_coupling(*) for which names are valid for a Sensor object.
- method ({'all', 'any', 'not any'}) Method to see if a given field matches the keys given. Choosing "all" will return couplings which have keys matching all of the values provided in the keys argument, while coosing "any", will return all couplings with keys matching at least one of the values specified by keys. For example, sensor.couplings\_with("rabi\_frequency")

returns a dictionary of all couplings for which a rabi\_frequency was specified. sensor.couplings\_with("rabi\_frequency", "detuning", method="all") returns all couplings for which both rabi\_frequency and detuning are specified. 'sensor.couplings\_with("rabi\_frequency", "detuning", method="any")` returns all couplings for which either rabi\_frequency or detuning are specified. Defaults to "all".

#### Returns

A copy of the sensor.couplings dictionary with only couplings containing the specified parameter keys.

#### Return type

dict

#### **Examples**

Can be used, for example, to return couplings in the roating wave approximation.

```
>>> s = rq.Sensor(3)
>>> sinusoid = lambda t: 0 if t<1 else sin(100*t)
>>> f2 = {"states": (0,1), "detuning": 1, "rabi_frequency":2}
>>> f1 = {"states": (1,2), "transition_frequency":100, "rabi_frequency":1,
-> "time_dependence": sinusoid}
>>> s.add_couplings(f1, f2)
>>> gamma = np.array([[.2,0,0],
... [.1,0,0],
... [0.05,0,0]])
>>> s.set_gamma_matrix(gamma)
>>> print(s.couplings_with("detuning"))
{(0, 1): {'rabi_frequency': 2, 'detuning': 1, 'phase': 0, 'kvec': (0, 0,_
->0), 'no_rwa_warning': False, 'label': '(0,1)'}}
```

#### $\texttt{decoherence\_matrix()} \rightarrow \texttt{ndarray}$

Get the decoherence matrix for a system.

This overload differs from decoherence\_matrix() by including state lifetimes and decay rates calculated from arc rydberg without any explicit definition of decoherence terms. In other words, it ensures that the calculated decoherence terms match what is expected for a particular real-world atom.

#### Returns

The decoherence matrix stack of the system.

#### **Return type**

numpy.ndarray

dm\_basis()  $\rightarrow$  ndarray

Generate basis labels of density matrix components.

The basis corresponds to the elements in the solution. This is not the complex basis of the sensor class, but rather the real basis of a solution after calling one of rydiqule's solvers. This means that the ground state population has been removed and it has been transformed to the real basis.

#### Returns

Array of string labels corresponding to the solving basis. Is a 1-D array of length n\*\*2-1.

#### Return type

numpy.ndarray

#### **Examples**

```
>>> s = rq.Sensor(3)
>>> print(s.basis())
['01_real' '02_real' '01_imag' '11_real' '12_real' '02_imag' '12_imag'
'22_real']
```

#### property eta

Get the eta value for the system.

The value is computed with the following formula Eq. 7 of Meyer et. al. PRA 104, 043103 (2021)

$$\eta = \sqrt{\frac{\omega\mu^2}{2c\epsilon_0\hbar A}}$$

Where  $\omega$  is the probing frequency,  $\mu$  is the dipole moment, A is the beam area, c is the speed of light,  $\epsilon_0$  is the dielectric constant, and  $\hbar$  is the reduced Plank constant.

This value is only computed if there is not a \_eta attribute in the system. If this attribute does exist, this function acts as an accessor for that attribute.

#### Notes

There is no way to set the eta attribute directly at present, it is always inferred with the above formula. However, this functionality exists so that custom implementations or specific use cases of *Cell* may set it for their own purposes.

#### Returns

The value eta for the system.

#### Return type float

get\_cell\_dipole\_moment (state1: Union[Sequence, int], state2: Union[Sequence, int], q=0)

Get the diploe moment between 2 cell state.

Either both states must be hyperfine, or both states must not be hyperfine states. Currently dipole moments cannot be calculated for a mix of state types.

#### Parameters

- **state1** (Union[QState, int]) The state from which the electron is transitioning.
- **state2** (*Union[QState, int]*) The state to which the electron is transitioning.
- **q** (*int*, *optional*) Polarization of probing optical field in spherical basis. Must be -1, 0, 1. Defaults to 0 for linear polarization.

#### Returns

The dipole moment of the transition in units of e\*a\_0.

**Return type** 

float

Raises

**ValueError** – If both states are not of the same type.

#### get\_cell\_hfs\_coefficient (state: Union[Sequence, int])

Get the hyperfine splitting coefficients of the given state using ARC.

State can either be given as a list of quantum numbers or an integer value corresponding to a key in the basis of the Cell. Returns 0 if not a hyperfine state and the values A, B returned by ARC Rydberg's getHFSCoefficients() function if it is a hyperfine state.

#### **Parameters**

```
state (Union[QState, int]) – The state to calculate. Can either be an integer corresponding to a graph node or the quantum numbers of a state in the system.
```

#### Returns

- *float* The hyperfine splitting coefficient A.
- *float* The hyperfine splitting coefficient B.

#### get\_cell\_hfs\_shift (state: Union[Sequence, int])

Return the hyperfine energy shift for the given hyperfine state.

Returns the energy shift if state is a hyperfine state (defined with 5 quantum numbers) or 0 if the state is not a hyperfine state (defined by 4 quantum numbers)

#### **Parameters**

state (Union[QState, int]) - The state for which to calculate the hyperfine shift. Can be a list of quantum numbers or an integer state level of Cell

#### Returns

The hyperfine energy shift in units of Mrad/s.

#### Return type

float

get\_cell\_tansition\_frequency (state1: Union[Sequence, int], state2: Union[Sequence, int])

Get the transition frequency between 2 states, accounting for hyperfine splitting.

If either state is a hyperfine state, its associated hyperfine shift is added or or subtracted to calculate the total energy difference between 2 states

#### **Parameters**

- **state1** (*Union[QState, int]*) The state the electron is transitioning from. Either a integer of one of the basis states, or a list of quantum numbers.
- **state2** (*Union[QState, int]*) The state the electron is transitioning to. Either an integer of one of the basis states, or a list of quantum numbers.

#### Returns

The total energy difference between two states accounting for hyperfine splitting.

### **Return type**

float

get\_coupling\_rabi (*coupling\_tuple: Tuple[Union[int, str], Union[int, str]]* = (0, 1))  $\rightarrow$  Union[float, ndarray]

Helper function that returns the Rabi frequency of the coupling from a Sensor for use in functions that return experimental values.

#### Parameters

**coupling\_tuple** (*tuple of int*) – The tuple that defines the coupling to extract to rabi frequencies from

#### Returns

Rabi frequency defined in the Sensor

#### Return type

float of numpy.ndarray

#### Warns

**UserWarning** – If the coupling has time dependence. In this case, the returned Rabi frequency may not be well defined.
# get\_couplings () → Dict[Tuple[Union[int, str], Union[int, str]], Dict]

Returns the couplings of the system as a dictionary

Deprecating in favor of calling the couplings.edges attribute directly.

#### Returns

A dictionary of key-value pairs with the keys corresponding to levels of transition, and the values being dictionaries of coupling attributes.

#### **Return type**

dict

#### get\_doppler\_shifts() $\rightarrow$ ndarray

Returns the Hamiltonian with only detunings set to the kvector values for each spatial dimension.

Determining if a float should be treated as zero is done using numpy.isclose, which has default absolute tolerance of 1e-08.

#### Returns

Array of shape (used\_spatial\_dim,n,n), Hamiltonians with only the doppler shifts present along each non-zero spatial dimension specified by the fields' "kvec" parameter.

#### **Return type**

numpy.ndarray

## get\_hamiltonian() $\rightarrow$ ndarray

Creates the Hamiltonians from the couplings defined by the fields.

They will only be the steady state hamiltonians, i.e. will only contain terms which do not vary with time. Implicitly creates hamiltonians in "stacks" by creating a grid of all supported coupling parameters which are lists. This grid of parameters will not contain rabi-frequency parameters which vary with time and are defined as list-like. Rather, the associated axis will be of length 1, with the scanning over this value handled by the get\_time\_couplings() function.

For m list-like parameters  $x_{1,x_{2,...,x_{m}}}$  with shapes N1,N2,...,Nm, and basis size n, the output will be shape (N1,N2,...,Nm, n, n). The dimensions N1,N2,...Nm are labeled by the output of  $axis\_labels()$ .

If any parameters have been zipped with the  $\_zip\_parameters()$  method, those parameters will share an axis in the final hamiltonian stack. In this case, if axis N1 and N2 above are the same shape and zipped, the final Hamiltonian will be of shape (N1, ..., Nm, n, n).

In the case where the basis of the Sensor was explicitly defined with a list of states, the ordering of rows and coulumns in the hamiltonian corresponds to the ordering of states passed in the basis.

See rydiqule's conventions for matrix stacking for more details.

## Returns

The complex hamiltonian stack for the sensor.

## Return type np.ndarray

# Examples

```
>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)
>>> blue = {"states":(0,1), "rabi_frequency":1, "detuning":det}
>>> red = {"states":(1,2), "rabi_frequency":3, "detuning":det}
>>> s.add_couplings(red, blue)
>>> print(s.get_hamiltonian().shape)
(11, 11, 3, 3)
```

Time dependent couplings are handled separately. The axis that contains array-like parameters with time dependence is length 1 in the steady-state Hamiltonian.

```
>>> s = rq.Sensor(3)
>>> rabi = np.linspace(-1,1,11)
>>> step = lambda t: 0 if t<1 else 1
>>> blue = {"states":(0,1), "rabi_frequency":rabi, "detuning":1}
>>> red = {"states":(1,2), "rabi_frequency":rabi, "detuning":0, 'time_
->> dependence': step}
>>> s.add_couplings(red, blue)
>>> print(s.get_hamiltonian().shape)
(11, 1, 3, 3)
```

Zipping parameters means they share an axis in the Hamiltonian.

If the basis is provided as a list of string labels, the ordering of Hamiltonian rows And columns will correspond to the order of states provided.

```
>>> s = rq.Sensor(['g', 'e1', 'e2'])
>>> s.add_coupling(('g', 'e1'), detuning=1, rabi_frequency=1)
>>> s.add_coupling(('e1', 'e2'), detuning=1.5, rabi_frequency=1)
>>> print(s.get_hamiltonian())
[[ 0. +0.j 0.5+0.j 0. +0.j]
[ 0.5-0.j -1. +0.j 0.5+0.j]
[ 0. +0.j 0.5-0.j -2.5+0.j]]
```

get\_hamiltonian\_diagonal (values: dict, no\_stack: bool = False)  $\rightarrow$  ndarray

Apply addition and subtraction logic corresponding to the direction of the couplings.

For a given state n, the path from ground will be traced to n. For each edge along this path, values will be added where the path direction and coupling direction match, and subtracting values where they do not. The sum of all such values along the path is the n th term in the output array.

Primarily for internal functions which help generate hamiltonians. Most commonly used to calculate total detunings for ranges of couplings under the RWA

## Parameters

- **values** (*dict*) Key-value pairs where the keys correspond to transitions (agnostic to ordering of states) and values corresponding to the values to which the logic will be applied.
- **no\_stack** (*bool*, *optional*) Whether to ignore variable parameters in the system and use only basic math operations rather than reshape the output. Typically only True for calculating doppler shifts.

#### Returns

The digonal of the hamiltonian of the system of shape (\*l, n), where l is the shape of the hamiltonian stack for the sensor.

## **Return type**

numpy.ndarray

# get\_parameter\_mesh() $\rightarrow$ List[ndarray]

Returns the parameter mesh of the sensor.

The parameter mesh is the flattened grid of variable parameters in all the couplings of a sensor. Wraps numpy.meshgrid with the indexing argument always "ij" for matrix indexing.

## Returns

list of mesh grids for every variable parameter

```
Return type
```

list of numpy.ndarray

## **Examples**

```
>>> s = rq.Sensor(3)
>>> rabi1 = np.linspace(-1,1,11)
>>> rabi2 = np.linspace(-2,2,21)
>>> s.add_coupling(states=(0,1), rabi_frequency=rabi1, detuning=1)
>>> s.add_coupling(states=(1,2), rabi_frequency=rabi2, detuning=1)
>>> for p in s.get_parameter_mesh():
... print(p.shape)
(11, 1)
(1, 21)
```

## get\_qnums (state: Union[Sequence, int])

Gets the quantum numbers for a given states.

Works by either retrieving quantum numbers for an integer state, or transparently passing through a state already defined by its quantum numbers.

## Parameters

**state** (Union [QState, int]) – The state the get the quantum numbers for.

#### Returns

The quantum numbers of the state. If state is already a list of quantum numbers, just returns the value of state

## **Return type**

list(int)

#### Raises

ValueError – If the integer provided is outside the basis of the Cell.

## get\_rotating\_frames() $\rightarrow dict$

Determines the rotating frames for the disconnected subgraphs.

Each returned path gives the states traversed, and the sign gives the direction of the coupling. If the sign is negative, the coupling is going to a lower energy state. Choice of frame depends on graph distance to lowest indexed node on subgraph, ties broken by lowest indexed path traversed first.

#### Returns

Dictionary keyed by disconnected subgraphs, values are path dictionaries for each node of the subgraph. Each path shows the node indexes traversed, where a negative sign denotes a transition to a lower energy state.

#### **Return type**

```
dict
```

#### get\_state\_num (state: Union[Sequence, int])

Return the integer number in the bases of a node with the given quantum numbers.

Quantum numbers for a state are determined by the "qnums" dictionary key on that node. Can handle either a list of quantum numbers or an integer state. In the case of an integer state, just returns the integer value passed in.

#### **Parameters**

state (Union[QState, int]) - Either the quantum numbers or integer value of the states.

#### Raises

ValueError: - If there is no state matching the given quantum numbers

#### Returns

The integer value corresponding the number of the state in the basis.

#### **Return type**

int

# get\_time\_couplings() $\rightarrow$ Tuple[List[ndarray], List[ndarray]]

Returns the list of matrices of all couplings in the system defined with a time\_dependence key.

The ouput will be two lists of matricies representing which terms of the hamiltonian are dependent on each time-dependent coupling. The lists will be of length M and shape ( $*l\_time, n, n$ ), where M is the number of time-dependent couplings,  $l\_time$  is time-dependent stack shape (possibly all ones), and n is the basis size. Each matrix will have terms equal to the rabi frequency (or half the rabi frequency under RWA) in positions that correspond to the associated transition. For example, in the case where there is a time\_dependence function defined for the (2, 3) transition with a rabi frequency of 1, the associated time coupling matrix will be all zeros, with a 1 in the (2, 3) and (3, 2) positions.

Typically, this function is called internally and multiplied by the output of the get\_time\_dependence() function.

### Returns

- *list of numpy.ndarray* The list of M (\*1, n, n) matrices representing the real-valued time-dependent portion of the hamiltonian. For 0 <= i <= M, the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.
- *list of numpy.ndarray* The list of M (\*1, n, n) matrices representing the imaginary-valued time-dependent portion of the hamiltonian. For  $0 \le i \le M$ , the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.

# **Examples**

```
>>> s = rq.Sensor(3)
>>> step = lambda t: 0 if t<1 else 1
>>> wave = lambda t: np.sin(2000*np.pi*t)
>>> f1 = {"states": (0,1), "transition_frequency":10, "rabi_frequency": 1,

→ "time_dependence":wave}

>>> f2 = {"states": (1,2), "transition_frequency":10, "rabi_frequency": 2,

→ "time_dependence":step}

>>> s.add_couplings(f1, f2)
>>> time_hams, time_hams_i = s.get_time_couplings()
>>> for H in time hams:
       print(H)
. . .
[[0.+0.j 1.+0.j 0.+0.j]
[1.+0.j 0.+0.j 0.+0.j]
[0.+0.j 0.+0.j 0.+0.j]]
[[0.+0.j 0.+0.j 0.+0.j]
[0.+0.j 0.+0.j 2.+0.j]
[0.+0.j 2.+0.j 0.+0.j]]
```

To handle stacking across the steady-state and time hamiltonians, the dimensions are matched in a way that broadcasting works in a numpy-friendly way

```
>>> s = rq.Sensor(3)
>>> rabi = np.linspace(-1,1,11)
>>> step = lambda t: 0 if t<1 else 1
>>> blue = {"states":(0,1), "rabi_frequency":rabi, "detuning":1}
```

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## $\texttt{get\_time\_dependence()} \rightarrow \texttt{List[Callable[[float], complex]]}$

Function which returns a list of the time\_dependence functions.

The list is returned with in the order that matches with the time hamiltonians from  $get\_time\_cou$ plings() such that the ith element of the return of this functions corresponds with the ith Hamiltonian terms returned by that function.

#### Returns

List of scalar functions, representing all couplings specified with a time\_dependence.

Return type list

#### **Examples**

# get\_time\_hamiltonians() → Tuple[ndarray, List[ndarray], List[ndarray]]

Get the hamiltonians for the time solver.

Get both the steady state hamiltonian (as returned by get\_hamiltonian()) and the time\_dependent hamiltonians (as returned by get\_time\_couplings()). The time dependent hamiltonians give 2 terms, the hamiltonian corresponding to the real part of the coupling and the hamiltonian corresponding to the imaginary part.

In the case where the basis of the Sensor was explicitly defined with a list of states, the ordering of rows and coulumns in the hamiltonian corresponds to the ordering of states passed in the basis.

## Returns

- hamiltonian\_base (*np.ndarray*) The (\*1, n, n) shape base hamiltonian of the system containing all elements that do not depend on time, where n is the basis size of the sensor.
- **dipole\_matrix\_real** (*np.ndarray*) The (M, n, n) shape array of matrices representing the real time-dependent portion of the hamiltonian. For 0 <= i <= M, the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.
- **dipole\_matrix\_imag** (*nd.ndarray*) The (M, n, n) shape array of matrices representing the imaginary time-dependent portion of the hamiltonian. For 0 <= i <= M, the

ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.

## Examples

```
>>> s = rq.Sensor(2)
>>> step = lambda t: 0. if t<1 else 1.
>>> s.add_coupling(states=(0,1), detuning=1, rabi_frequency=1, time_
        -dependence=step)
>>> H_base, H_time_real, H_time_imaginary = s.get_time_hamiltonians()
>>> print(H_base)
>>> print(H_time_real)
>>> print(H_time_imaginary)
[[0.+0.j 0.+0.j]
[0.+0.j 1.+0.j]]
[array([[0. +0.j, 0.5+0.j],
        [0.5+0.j, 0. +0.j]])]
[array([[0.+0.j, 0.+0.5j],
        [0.-0.5j, 0.+0.j]])]
```

If the basis is passed as a list, rows and columns are in the order specified:

### get\_transition\_frequencies() $\rightarrow$ ndarray

Gets an array of the diagonal elements of the Hamiltonian from the field detunings.

Wraps the get\_hamiltonian\_diagonal() function using both transition frequencies and detunings. Primarily for internal use.

## Returns

N-D array of the hamiltonian diagonal. For an n-level system with stack shape (1, n)

### **Return type**

numpy.ndarray

# get\_value\_dictionary (key: str) $\rightarrow$ dict

Get subset of dictionary coupling parameters.

Return a dictionary of key value pairs where the keys are couplings added to the system and the values are the value of the parameter specified by key. Produces an output that can be passed directly to get\_hamiltonian\_diagonal(). Only couplings whose parameter dictionaries contain "key" will be in the returned dictionary.

#### Parameters

key (str) – String value of the parameter name to build the dictionary. For example,

get\_value\_dictionary ("detuning") will return a dictionary with keys corresponding to transitions and values corresponding to detuning for each transition which has a detuning.

## Returns

Coupling dictionary with couplings as keys and corresponding values set by input key.

Return type dict

# **Examples**

```
>>> s = rq.Sensor(4)
>>> f1 = {"states": (0,1), "detuning": 2, "rabi_frequency": 1}
>>> f2 = {"states": (1,2), "detuning": 3, "rabi_frequency": 2}
>>> f3 = {"states": (2,3), "rabi_frequency": 3, "transition_frequency": 3}
>>> s.add_couplings(f1, f2, f3)
>>> print(s.get_value_dictionary("detuning"))
{(0,1): 2, (1,2): 3}
```

## property kappa

Property to calculate the kappa value of the system.

The value is computed with the following formula Eq. 5 of Meyer et. al. PRA 104, 043103 (2021)

$$\kappa = \frac{\omega n \mu^2}{2c\epsilon_0 \hbar}$$

Where  $\omega$  is the probing frequency,  $\mu$  is the dipole moment, n is atomic cloud density, c is the speed of light,  $\epsilon_0$  is the dielectric constant, and  $\hbar$  is the reduced Plank constant.

This value is only computed if there is not a  $_kappa$  attribute in the system. If this attribute does exist, this function acts as an accessor for that attribute.

### Notes

There is no way to set the kappa attribute directly at presence, it is always inferred with the above formula. However, this functionality exists so that custom implementations or specific use cases of Cell may set it for their own purposes.

#### Returns

The value kappa for the system.

Return type float

# **level\_ordering()** $\rightarrow$ List[int]

Return a list of the integer numbers of each state (*not* the quantum numbers) in descending order by energy order.

All energies are calculated with respect to the ground state energy, which is defined as 0. Ground state is determined by the first state added to the system (state 0). Thus, state 0 will always be last in the list.

#### Returns

The level numbers of the states in order of decending energy relative to the ground state (state 0).

## **Return type**

list[int]

## Examples

For the following example, states are added to the cell in ascending energy order, so the return reflects that, with the highest-energy state first.

```
>>> state1 = [50, 2, 2.5, 2.5]
>>> state2 = [51, 2, 2.5, 2.5]
>>> cell = rq.Cell("Rb85", *rq.D2_states("Rb85"), state1, state2,
>>> cell_length = .00001) #uses the D2 line of Rb85
>>> print(cell.states_list())
>>> print(cell.level_ordering())
[[5, 0, 0.5, 0.5], [5, 1, 1.5, 0.5], [50, 2, 2.5, 2.5], [51, 2, 2.5, 2.5]]
[3, 2, 1, 0]
```

If we add state1 and state2 in the opposite order (thus switching their positions in the states list), the level ordering will change since state2 is still a higher energy.

## property probe\_freq

Get the probe transition frequency, in rad/s

Returns

Probe transitiion frequency, in rad/s

Return type

float

```
probe_tuple: Optional[States] = None
```

Coupling edge that corresponds to the probing field. Defaults to (0, 1) in Cell.

Sensor specific method. Do not use with Cell.

This function does not do anything as Cell automatically handles this functionality internally.

Warns

UserWarning (Warns if function is used.)

set\_gamma\_matrix(gamma\_matrix: ndarray)

Set the decoherence matrix for the system.

Works by first removing all existing decoherent data from graph edges, then individually adding all nonzero terms of a provided gamma matrix to the corresponding graph edges. Can be used to set all decoherence attributes to edges simultaneously, but *add\_decoherence()* is preferred.

Unlike *add\_decoherence()*, does not support scanning multiple decoherence values, rather should be used to set the decoherences of the system to individual static values.

## Parameters

```
gamma_matrix (numpy.ndarray) - Array of shape (basis_size, basis_size). Element (i,j) describes the decoherence rate, in Mrad/s, from state i to state j.
```

Raises

- **TypeError** If gamma\_matrix is not a numpy array.
- ValueError If gamma\_matrix is not a square matrix of the appropriate size
- ValueError If the shape of gamma\_matrix is not compatible with self. basis\_size.

## **Examples**

```
>>> s = rq.Sensor(2)
>>> f1 = {"states": (0,1), "transition_frequency":10, "rabi_frequency": 1}
>>> s.add_couplings(f1)
>>> gamma = np.array([[.1,0],[.1,0]])
>>> s.set_gamma_matrix(gamma)
>>> print(s.decoherence_matrix())
[[0.1 0. ]
[0.1 0. ]]
```

#### $\texttt{spatial}_dim() \rightarrow int$

Returns the number of spatial dimensions doppler averaging will occur over.

Determining if a float should be treated as zero is done using numpy.isclose, which has default absolute tolerance of 1e-08.

### Returns

Number of dimensions, between 0 and 3, where 0 means no doppler averaging kvectors have been specified or are too small to be calculates.

Return type

int

## **Examples**

No spatial dimesions specified

```
>>> s = rq.Sensor(2)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1)
>>> print(s.spatial_dim())
0
```

One spatial dimension specified

```
>>> s = rq.Sensor(2)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1, kvec=(0,0,1))
>>> print(s.spatial_dim())
1
```

Multiple spatial dimensions can exist in a single coupling or across multiple couplings

```
>>> s = rq.Sensor(2)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1, kvec=(1,0,1))
>>> print(s.spatial_dim())
2
```

```
>>> s = rq.Sensor(3)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1, kvec=(1,0,1))
>>> s.add_coupling((1,2), detuning = 2, rabi_freqency=2, kvec=(0,1,0))
>>> print(s.spatial_dim())
3
```

#### property states

Property which gets a list of labels for the sensor in the order defined in <u>\_\_init\_\_</u>(). This is also the order corresponding the rows and columns in the system Hamiltonian and decoherence matrix.

#### Returns

List of states of the system defined the constructor, in the order corresponding to rows and columns of the Hamiltonian.

#### **Return type**

list

#### states\_list() $\rightarrow$ List[Sequence]

Returns a list of quantum numbers for all states in the cell.

States position in the list will be in the order they were added, and correspond to the density matrix values numbered with the same index.

### Returns

List of quantum states of the form [n, l, j, m] that are stored on graph nodes in the cell.

```
Return type
list[list]
```

## Examples

### states\_with\_label(label: str) → List[Union[int, str]]

Return a dict of all states with a label matching a given regular expression (regex) pattern. The dictionary will be consist of keys which are string labels applied to states with the label\_states() function, and values which are the corresponding integer values of the node on the graph. For more information on using regex patterns see this guide <https://docs.python.org/3/howto/regex.html#regex-howto>.

## Parameters

**label** (*string*) – Regular expression pattern to match labels to. All labels matching the string will be returned in the keys of the dictionary.

### Returns

List of all labels of states in the sensor which match the provided regex pattern.

## **Return type**

list

#### Raises

**ValueError** – If label is not a regular expression string.

### **Examples**

```
>>> s = rq.Sensor(3)
>>> s.add_coupling((0,1), detuning=1, rabi_freqency=1, label="hi mom")
>>> s.add_coupling((1,2), detuning=2, rabi_requency=2)
>>> s.label_states({0:"g", 1:"e1", 2:"e2"})
>>> print(s.states_with_label("e[12]"))
['e1', 'e2']
```

## unzip\_parameters (zip\_label, verbose=True)

Remove a set of zipped parameters from the internal zipped\_parameters list.

If an element of the internal \_zipped\_parameters array matches ALL labels provided, removes it from the internal zipped\_parameters method. If no such element is in \_zipped\_parameters, does nothing.

#### **Parameters**

**zip\_label** (*str*) – The string label corresponding the key to be deleted in the \_zipped\_parameters attribute.

## Notes

**Note:** This function should always be used rather than modifying the \_zipped\_parameters attribute directly.

## **Examples**

If the labels provided are not a match, a message is printed and nothing is altered.

**variable\_parameters** (*apply\_mesh: bool* = *False*) → List[Tuple[Tuple[Union[int, str], Union[int, str]], str, ndarray]]

Property to retrieve the values of parameters that were stored on the graph as arrays.

Values are returned as a list of tuples in the standard order of pythons default sorting, applied first to the tuple indicating states and then to the key of the parameter itself. This means that couplings are sorted first by lower state, then by upper state, then alphabetically by the name of the parameter. To determine order, all state labels treated as their integer position in the basis as determined by ordering in the constructor \_\_\_\_\_init\_\_\_().

## Returns

A list of tuples corresponding to the parameters of the systems that are variable (i.e. stored as an array). They are ordered according to states, then according to variable name. Tuple entries of the list take the form (states, param\_name, value)

## Return type

list of tuples

## **Examples**

```
>>> s = rq.Sensor(3)
>>> vals = np.linspace(-1,2,3)
>>> s.add_coupling(states=(1,2), rabi_frequency=vals, detuning=1)
>>> s.add_coupling(states=(0,1), rabi_frequency=vals, detuning=vals)
>>> for states, key, value in s.variable_parameters():
... print(f"{states}: {key}={value}")
(0, 1): detuning=[-1. 0.5 2.]
(0, 1): rabi_frequency=[-1. 0.5 2.]
(1, 2): rabi_frequency=[-1. 0.5 2.]
```

The order is important; in the unzipped case, it will sort as though all state labels were cast to strings, meaning integers will always be treated as first.

```
>>> s = rq.Sensor([None, 'e1', 'e2'])
>>> det1 = np.linspace(-1, 1, 3)
>>> det2 = np.linspace(-1, 1, 5)
>>> blue = {"states":(0,'e1'), "rabi_frequency":1, "detuning":det1}
>>> red = {"states":('e1','e2'), "rabi_frequency":3, "detuning":det2}
>>> s.add_couplings(blue, red)
>>> for states, key, value in s.variable_parameters():
... print(f"{states}: {key}={value}")
>>> print(f"Axis Labels: {s.axis_labels()}")
('g', 1): detuning=[-1. 0. 1.]
(1, 2): detuning=[-1. -0.5 0. 0.5 1. ]
Axis Labels: ["('g',1)_detuning", '(1,2)_detuning']
```

## zip\_parameters (\*parameters: str, zip\_label: Optional[str] = None)

Define 2 scannable parameters as "zipped" so they are scanned in parallel.

Zipped parameters will share an axis when quantities relevant to the equations of motion, such as the gamma\_matrix and hamiltonian are generated. Note that calling this function does not affect internal quanties directly, but adds their labels together in the internal self.\_zipped\_parameters dict, and they are zipped at calculation time for hamiltonian and decoherence\_matrix.

#### Parameters

**parameters** (*str*) - Parameter labels to scan together. Parameter labels are strings of the form "<coupling\_label>\_<parameter\_name>", such as "(0, 1)\_detuning". Must be at least 2 labels to zip. Note that couplings are specified in the *add\_coupling()* function. If unspecified in this function, the pair of states in the coupling cast to a string will be used.

#### zip\_label

[optional, str] String label shorthand for the zipped parameters. The label for the axis of these parameters in *axis\_labels()*. Does not affect functionality of the Sensor. If unspecified, the label used will be "zip\_" + <number>.

### Raises

- ValueError If fewer than 2 labels are provided.
- ValueError If any of the 2 labels are the same.
- ValueError If any elements of labels are not labels of couplings in the sensor.
- ValueError If any of the parameters specified by labels are already zipped.
- ValueError If any of the parameters specified are not list-like.
- **ValueError** If all list-like parameters are not the same length.

#### Notes

**Note:** This function should be called last after all Sensor couplings and dephasings have been added. Changing a coupling that has already been zipped removes it from the self.zipped\_parameters list.

**Note:** Modifying the Sensor.zipped\_parameters attribute directly can break some functionality and should be avoided. Use this function or *unzip\_parameters()* instead.

**Note:** When defining the zip strings for states labelled with strings, be sure to additional ' or " characters on either side of the labels, as demonstrated in the second example below.

## **Examples**

Make sure to add the appropriate additional string markings when the states are strings.

# 6.1.3 rydiqule.doppler\_utils

Utilities for implementing Doppler averaging

# **Functions**

| apply_doppler_weights(sols, velocities, vol-             | Calculates and applies the weight for each doppler class    |
|--|---|
| umes)  | given unweighted solutions to doppler-shifted equa-         |
|  | tions.  |
| doppler_classes([method])                                | Defines which velocity classes to sample for doppler av-    |
|  | eraging.  |
| <pre>doppler_mesh(doppler_velocities, spatial_dim)</pre> | Creates meshgrids of evaluation points and point "vol-      |
|  | umes" for doppler averaging.                                |
| gaussian3d(Vs)   | Evaluate a multi-dimensional gaussian for the given de-     |
|  | tunings (in units of most probable speed).                  |
| <pre>generate_doppler_shift_eom(doppler_hamilt</pre>     | confixence) rates the EOMs for the supplied doppler shifts. |
| <pre>get_doppler_equations(base_eoms,)</pre>             | Returns the equations for each slice of the doppler pro-    |
|  | file.   |

# rydiqule.doppler\_utils.apply\_doppler\_weights

rydiqule.doppler\_utils.apply\_doppler\_weights (sols: ndarray, velocities: ndarray, volumes: ndarray)  $\rightarrow$  ndarray

Calculates and applies the weight for each doppler class given unweighted solutions to doppler-shifted equations.

Works for both time-domain and stead-state solutions.

### Parameters

- **sols** (*numpy.ndarray*) The array of solutions over which to calculate weights.
- **velocities** (*numpy.ndarray*) Array of shape (n\_dim, \*n\_dop) where n\_dim is the number of dimensions over which doppler shifts are being considered and \*n\_dop is a number of axes equal to n\_dim with length equal to the number of doppler velocity classes which are being considered. The values correspond the velocity class in units of most probable speed.
- **volumes** (*numpy.ndarray*) Array of shape equal to velocities. The values correspond to the spacings between doppler classes on each axis.

#### Returns

The weighted solution array of shape equal to that of sols.

## **Return type**

numpy.ndarray

### Raises

**ValueError** – If the shapes of velocities and volumes do not match.

# rydiqule.doppler\_utils.doppler\_classes

rydiqule.doppler\_utils.doppler\_classes(method: Optional[Union[UniformMethod,

IsoPopMethod, SplitMethod, DirectMethod]] = None)  $\rightarrow$  ndarray

Defines which velocity classes to sample for doppler averaging.

These are defined in units of the most probable speed of the Maxwell-Boltzmann distribution.

**Note:** To avoid issues, optical detunings should not leave densely sampled velocity classes. To avoid artifacts, the density of points should provide  $>\sim 10$  points over the narrowest absorptive feature. The default is a decent first guess, but for many problems the sampling mesh should be adjusted.

### Parameters

**method** (*dict*) – Specifies method to use and any control parameters. Must contain the key "method" with one of the following options. Each method has suboptions that also need to be specified. Valid options are:

- "uniform": Defines a uniformly spaced, dense grid. Configuration parameters include:
  - "width\_doppler": Float that specifies one-sided width of gaussian distribution to average over, in units of most probable speed. Defaults to 2.0.
  - "n\_uniform": Int that specifies how many points to use. Defaults to 1601.
- "isopop": Defines a grid with uniform population in each interval. This method highly emphasises physics happening near the 0 velocity class. If stuff is happening for non-zero velocity classes, it is likely to alias it unless n\_isopop is large. See Ref<sup>1</sup> for details. Configuration parameters include:
  - "n\_isopop": Int that specifies how many points to use. Defaults to 400.
- "split": Defines a grid with a dense central spacing and wide spacing wings. This method provides a decent compromise between uniform and isopop. It uses fewer points than uniform, but also works well for non-zero velocity class models (like Autler-Townes splittings). This is the default meshing method. Configuration parameters include:
  - "width\_doppler": Float that specifies one-sided width of coarse grided portion of the gaussian distribution. Units are in most probable speed. Defaults to 2.0.
  - "width\_coherent": Float that specifies one-sided width of fine grided portion of gaussian distribution. Units are in most probable speed. Defaults to 0.4.
  - "n\_doppler": Int that specifies how many points to use for the coarse grid. Note that points of the coarse grid that fall within the fine grid are dropped. Default is 201.
  - "n\_coherent": Int that specifies how many points to use for the fine grid. Default is 401.

Note: For the "split" method, a union of 2 samplings is taken, so the number of total points will not necessary be equal to the sum of "n\_coherent" and "n\_doppler".

- "direct": Use the supplied 1-D numpy array to build the mesh.
  - "doppler\_velocities": Mandatory parameter that holds the 1-D numpy array to use when building the mesh grids. Given in units of most probably speed.

#### Returns

1-D array of velocities to be sampled.

<sup>&</sup>lt;sup>1</sup> Andrew P. Rotunno, et. al. Inverse Transform Sampling for Efficient Doppler-Averaged Spectroscopy Simulation, AIP Advances 13, 075218 (2023) https://doi.org/10.1063/5.0157748

#### **Return type**

numpy.ndarray

### **Examples**

The defaults will sample more densely near the center of the distribution, (the "split" method) with a total of 561 classes.

```
>>> classes = rq.doppler_classes() #use the default values
>>> print(classes.shape)
(561,)
```

Specifying "uniform" with no additional arguments produces 1601 evenly spaced classes by default.

```
>>> m = {"method":"uniform"}
>>> classes = rq.doppler_classes(method=m)
>>> print(classes.shape)
(1601,)
```

Further specifying the number of points allows more dense or sparse sampling of the velocity distribution.

```
>>> m = {"method":"uniform", "n_uniform":801}
>>> classes = rq.doppler_classes(method=m)
>>> print(classes.shape)
(801,)
```

The "split" method also has further specifications

```
>>> m = {"method":"split", "n_coherent":301, "n_doppler":501}
>>> classes = rq.doppler_classes(method=m)
>>> print(classes.shape)
(701,)
```

# References

## rydiqule.doppler\_utils.doppler\_mesh

```
rydiqule.doppler_utils.doppler_mesh (doppler_velocities: ndarray, spatial_dim: int) → Tuple[ndarray, ndarray]
```

Creates meshgrids of evaluation points and point "volumes" for doppler averaging.

#### Parameters

- **dop\_velocities** (*numpy.ndarray*) A 1-D array of velocities to evaluate over. These should be normalized to the most probable velocity used by *gaussian3d()*.
- **spatial\_dim** (*int*) Number of spatial dimensions to grid over.

### Returns

- Vs (*numpy.ndarray*) Velocity evaluation points array of shape (spatial\_dim, spatial\_dim\*[len(dop\_vel)]).
- Vols (numpy.ndarray) "Volume" of each meshpoint. Has same shape as Vs.

# **Examples**

```
>>> m = {"method":"uniform", "n_uniform":801}
>>> classes = rq.doppler_classes(method=m)
>>> mesh, vols = rq.doppler_mesh(classes, 2)
>>> print(type(mesh), type(vols))
>>> mesh_np = np.array(mesh)
>>> vols_np = np.array(vols)
>>> print(mesh_np.shape, vols_np.shape)
<class 'numpy.ndarray'> <class 'numpy.ndarray'>
(2, 801, 801) (2, 801, 801)
```

# rydiqule.doppler\_utils.gaussian3d

rydiqule.doppler\_utils.**gaussian3d**(*Vs: ndarray*) → ndarray

Evaluate a multi-dimensional gaussian for the given detunings (in units of most probable speed).

This is equivalent to a gaussian distribution with rms width  $\sigma = 1/\sqrt{2}$ .

#### Parameters

**Vs** (*numpy.ndarray*) – Array of normalized velocity classes for which to get the gaussian weighting.

#### Returns Gauss

Gaussian weights for the velocity classes. Has same shape as Vs.

### **Return type**

numpy.ndarray

## rydiqule.doppler\_utils.generate\_doppler\_shift\_eom

 $\label{eq:complex_doppler_shift_eom} rydiqule.doppler_utils.generate_doppler_shift_eom(\mathit{doppler\_hamiltonians: ndarray}) \rightarrow ndarray$ 

Generates the EOMs for the supplied doppler shifts.

Multiply the output by the velocity in each dimension, then add to the normal EOMs to get the full Doppler shifted EOMs.

### Parameters

**doppler\_hamiltonians** (*numpy.ndarray*) – Hamiltonians of only the doppler shifts, one for each spatial dimension to be averaged over.

### Returns

Corresponding LHS EOMs with ground removed and in the real basis.

#### **Return type**

numpy.ndarray

# rydiqule.doppler\_utils.get\_doppler\_equations

```
rydiqule.doppler_utils.get_doppler_equations (base_eoms: ndarray, doppler_hamiltonians: ndarray, Vs: ndarray) → ndarray
```

Returns the equations for each slice of the doppler profile.

A new axes corresponding to these slices are appended to the beginning. For example, if equations are of shape (m, m) and there are n\_doppler doppler values being sampled, the return will be of shape  $(n_doppler, m, m)$ .

#### **Parameters**

- **base\_eoms** (*numpy.ndarray*) Stacked square arrays representing the unshifted equations, i.e. the theoretical equations for an ensemble of atoms with zero momentum.
- doppler\_hamiltonians (*numpy.ndarray*) Arrays of hamiltonians with only doppler shifts present. One for each spatial dimension needed. See *get\_doppler\_shifts()* for details.
- Vs (*numpy.ndarray*) Mesh of velocity classes to sample, with same spatial dimensions as dop\_ham. See *doppler\_mesh()* for details.

## Returns

An array of shape (\*Vs.shape[1:], \*base\_eoms.shape) which is a, potentially multi-dimensional, stack of individual equations of shape (m, m). Each slice of this stack is an equation of shape (m, m) with the corresponding doppler shifts applied.

# **Return type**

numpy.ndarray

**Note:** Each doppler shift is equal to k\_i\*vP\*det\_i, in units of Mrad/s, where i denotes the einstein summation along the spatial dimensions. det is the normalized velocity class, with vP\*det\_i=v\_i giving the velocity. vP is the most probable speed from the Maxwell-Boltzmann distribution: sqrt(2\*kB\*T/m). k\_i is the k-vector of the field along the same axis as det\_i. doppler\_hamiltonians provides k\_i\*vP, Vs provides det\_i.

# Classes

| DirectMethod  |  |
|---------------|--|
| IsoPopMethod  |  |
| SplitMethod   |  |
| UniformMethod |  |

# rydiqule.doppler\_utils.DirectMethod

class rydiqule.doppler\_utils.DirectMethod

Bases: TypedDict

\_\_init\_\_(\*args, \*\*kwargs)

## Methods

| init(*args, **kwargs)                 |  |
|---------------------------------------|--|
| clear()                               |  |
| copy()                                |  |
| <pre>fromkeys([value])</pre>          | Create a new dictionary with keys from iterable and values set to value. |
| get(key[, default])                   | Return the value for key if key is in the dictionary, else default.      |
| items()                               |  |
| keys()                                |  |
| pop(k[,d])                            | If the key is not found, return the default if given;                    |
|                                       | otherwise, raise a KeyError.   |
| popitem()                             | Remove and return a (key, value) pair as a 2-tuple.                      |
| <pre>setdefault(key[, default])</pre> | Insert key with a value of default if key is not in the                  |
|                                       | dictionary.  |
| update([E,]**F)                       | If E is present and has a .keys() method, then does:                     |
|                                       | for k in E: $D[k] = E[k]$ If E is present and lacks a                    |
|                                       | .keys() method, then does: for k, v in E: $D[k] = v$                     |
|                                       | In either case, this is followed by: for k in $F: D[k] =$                |
|                                       | F[k]   |

values()

# Attributes

| method             |  |  |
|--------------------|--|--|
| doppler_velocities |  |  |

**clear** ()  $\rightarrow$  None. Remove all items from D.

```
\operatorname{copy}() \to \operatorname{a shallow copy of } D
```

### doppler\_velocities: Union[ndarray, Sequence]

#### fromkeys(value=None,/)

Create a new dictionary with keys from iterable and values set to value.

get (key, default=None, /)

Return the value for key if key is in the dictionary, else default.

items ( )  $\rightarrow$  a set-like object providing a view on D's items

 ${\tt keys}$  ( )  $\rightarrow$  a set-like object providing a view on D's keys

```
method: Literal['direct']
```

**pop**  $(k[, d]) \rightarrow v$ , remove specified key and return the corresponding value.

If the key is not found, return the default if given; otherwise, raise a KeyError.

## popitem()

Remove and return a (key, value) pair as a 2-tuple.

Pairs are returned in LIFO (last-in, first-out) order. Raises KeyError if the dict is empty.

# setdefault (key, default=None, /)

Insert key with a value of default if key is not in the dictionary.

Return the value for key if key is in the dictionary, else default.

**update** ([E], \*\*F)  $\rightarrow$  None. Update D from dict/iterable E and F.

If E is present and has a .keys() method, then does: for k in E: D[k] = E[k] If E is present and lacks a .keys() method, then does: for k, v in E: D[k] = v In either case, this is followed by: for k in F: D[k] = F[k]

values ( )  $\rightarrow$  an object providing a view on D's values

# rydiqule.doppler\_utils.lsoPopMethod

class rydiqule.doppler\_utils.IsoPopMethod
 Bases: TypedDict

\_\_init\_\_ (\*args, \*\*kwargs)

## Methods

| init(*args, **kwargs)                 |   |
|---------------------------------------|---|
| clear()                               |   |
| сору()                                |   |
| fromkeys([value])                     | Create a new dictionary with keys from iterable and       |
|                                       | values set to value.                                      |
| get(key[, default])                   | Return the value for key if key is in the dictionary,     |
|                                       | else default.   |
| items()                               |   |
| keys()                                |   |
| pop(k[,d])                            | If the key is not found, return the default if given;     |
|                                       | otherwise, raise a KeyError.                              |
| popitem()                             | Remove and return a (key, value) pair as a 2-tuple.       |
| <pre>setdefault(key[, default])</pre> | Insert key with a value of default if key is not in the   |
|                                       | dictionary.   |
| update([E,]**F)                       | If E is present and has a .keys() method, then does:      |
|                                       | for k in E: $D[k] = E[k]$ If E is present and lacks a     |
|                                       | .keys() method, then does: for k, v in E: $D[k] = v$      |
|                                       | In either case, this is followed by: for k in $F: D[k] =$ |
|                                       | F[k]  |
| values()                              |   |

values()

# Attributes

| method   |  |  |
|----------|--|--|
| n_isopop |  |  |

**clear** ( )  $\rightarrow$  None. Remove all items from D.

```
copy ( ) \rightarrow a shallow copy of D
```

fromkeys(value=None,/)

Create a new dictionary with keys from iterable and values set to value.

```
get (key, default=None, /)
```

Return the value for key if key is in the dictionary, else default.

<code>items</code> ( )  $\rightarrow$  a set-like object providing a view on D's items

**keys** ()  $\rightarrow$  a set-like object providing a view on D's keys

method: Literal['isopop']

n\_isopop: int

**pop**  $(k[, d]) \rightarrow v$ , remove specified key and return the corresponding value.

If the key is not found, return the default if given; otherwise, raise a KeyError.

### popitem()

Remove and return a (key, value) pair as a 2-tuple.

Pairs are returned in LIFO (last-in, first-out) order. Raises KeyError if the dict is empty.

## setdefault (key, default=None, /)

Insert key with a value of default if key is not in the dictionary.

Return the value for key if key is in the dictionary, else default.

**update** ([E], \*\**F*)  $\rightarrow$  None. Update D from dict/iterable E and F.

If E is present and has a .keys() method, then does: for k in E: D[k] = E[k] If E is present and lacks a .keys() method, then does: for k, v in E: D[k] = v In either case, this is followed by: for k in F: D[k] = F[k]

**values** ( )  $\rightarrow$  an object providing a view on D's values

# rydiqule.doppler\_utils.SplitMethod

class rydiqule.doppler\_utils.SplitMethod

Bases: TypedDict

\_\_init\_\_ (\*args, \*\*kwargs)

## Methods

| (*args, **kwargs)                     |  |
|---------------------------------------|--|
| clear()                               |  |
| сору()                                |  |
| fromkeys([value])                     | Create a new dictionary with keys from iterable and values set to value.   |
| <pre>get(key[, default])</pre>        | Return the value for key if key is in the dictionary, else default.  |
| items()                               |  |
| keys()                                |  |
| pop(k[,d])                            | If the key is not found, return the default if given; otherwise, raise a KeyError.   |
| popitem()                             | Remove and return a (key, value) pair as a 2-tuple.  |
| <pre>setdefault(key[, default])</pre> | Insert key with a value of default if key is not in the dictionary.  |
| update([E,]**F)                       | If E is present and has a .keys() method, then does:<br>for k in E: $D[k] = E[k]$ If E is present and lacks a<br>.keys() method, then does: for k, v in E: $D[k] = v$<br>In either case, this is followed by: for k in F: $D[k] =$<br>F[k] |
| values()                              |  |

# Attributes

| method         |
|----------------|
| width_doppler  |
| n_doppler      |
| width_coherent |
| n_coherent     |

**clear** ( )  $\rightarrow$  None. Remove all items from D.

 $\operatorname{\textbf{copy}}(\ ) \to a \text{ shallow copy of } D$ 

fromkeys(value=None,/)

Create a new dictionary with keys from iterable and values set to value.

get (key, default=None, /)

Return the value for key if key is in the dictionary, else default.

items ( )  $\rightarrow$  a set-like object providing a view on D's items

keys ( )  $\rightarrow$  a set-like object providing a view on D's keys

```
method: Literal['split']
```

n\_coherent: int

n\_doppler: int

**pop**  $(k[, d]) \rightarrow v$ , remove specified key and return the corresponding value.

If the key is not found, return the default if given; otherwise, raise a KeyError.

popitem()

Remove and return a (key, value) pair as a 2-tuple.

Pairs are returned in LIFO (last-in, first-out) order. Raises KeyError if the dict is empty.

setdefault (key, default=None, /)

Insert key with a value of default if key is not in the dictionary.

Return the value for key if key is in the dictionary, else default.

**update** ([E], \*\**F*)  $\rightarrow$  None. Update D from dict/iterable E and F.

If E is present and has a .keys() method, then does: for k in E: D[k] = E[k] If E is present and lacks a .keys() method, then does: for k, v in E: D[k] = v In either case, this is followed by: for k in F: D[k] = F[k]

**values** ( )  $\rightarrow$  an object providing a view on D's values

width\_coherent: float

width\_doppler: float

# rydiqule.doppler\_utils.UniformMethod

class rydiqule.doppler\_utils.UniformMethod

 $Bases: {\tt TypedDict}$ 

\_\_init\_\_\_(\*args, \*\*kwargs)

# Methods

| init(*args, **kwargs)                 |  |
|---------------------------------------|--|
| clear()                               |  |
| copy()                                |  |
| fromkeys([value])                     | Create a new dictionary with keys from iterable and values set to value. |
| <pre>get(key[, default])</pre>        | Return the value for key if key is in the dictionary, else default.      |
| items()                               |  |
| keys()                                |  |
| pop(k[,d])                            | If the key is not found, return the default if given;                    |
|                                       | otherwise, raise a KeyError.   |
| popitem()                             | Remove and return a (key, value) pair as a 2-tuple.                      |
| <pre>setdefault(key[, default])</pre> | Insert key with a value of default if key is not in the                  |
|                                       | dictionary.  |
| update([E,]**F)                       | If E is present and has a .keys() method, then does:                     |
|                                       | for k in E: $D[k] = E[k]$ If E is present and lacks a                    |
|                                       | .keys() method, then does: for k, v in E: $D[k] = v$                     |
|                                       | In either case, this is followed by: for k in F: $D[k] =$                |
|                                       | F[k]   |
| values()                              |  |

# Attributes

| method        |  |
|---------------|--|
| width_doppler |  |
| n_uniform     |  |

**clear** ( )  $\rightarrow$  None. Remove all items from D.

 $\operatorname{\textbf{copy}}$  ( )  $\rightarrow$  a shallow copy of D

```
fromkeys(value=None,/)
```

Create a new dictionary with keys from iterable and values set to value.

```
get (key, default=None, /)
```

Return the value for key if key is in the dictionary, else default.

items ( )  $\rightarrow$  a set-like object providing a view on D's items

**keys** ()  $\rightarrow$  a set-like object providing a view on D's keys

```
method: Literal['uniform']
```

n\_uniform: int

**pop**  $(k[, d]) \rightarrow v$ , remove specified key and return the corresponding value.

If the key is not found, return the default if given; otherwise, raise a KeyError.

# popitem()

Remove and return a (key, value) pair as a 2-tuple.

Pairs are returned in LIFO (last-in, first-out) order. Raises KeyError if the dict is empty.

setdefault (key, default=None, /)

Insert key with a value of default if key is not in the dictionary.

Return the value for key if key is in the dictionary, else default.

**update** ([E], \*\*F)  $\rightarrow$  None. Update D from dict/iterable E and F.

If E is present and has a .keys() method, then does: for k in E: D[k] = E[k] If E is present and lacks a .keys() method, then does: for k, v in E: D[k] = v In either case, this is followed by: for k in F: D[k] = F[k]

**values** ( )  $\rightarrow$  an object providing a view on D's values

width\_doppler: float

# 6.1.4 rydiqule.experiments

Standard methods for converting results to physical values.

# Functions

| get_OD(*args, **kwargs)                           | Deprecated.  |
|---|--|
| get_phase_shift(*args, **kwargs)                  | Deprecated.  |
| get_snr(sensor, param_label[,])                   | Calculate a Sensor's signal-to-noise ratio in standard de- |
|   | viation, in a 1Hz bandwidth, to a specified signal pa-     |
|   | rameter, assuming a homodyne measurement of optical        |
|   | field.   |
| <pre>get_solution_element(*args, **kwargs)</pre>  | Deprecated.  |
| <pre>get_susceptibility(*args, **kwargs)</pre>    | Deprecated.  |
| <pre>get_transmission_coef(*args, **kwargs)</pre> | Deprecated.  |

# rydiqule.experiments.get\_OD

rydiqule.experiments.get\_OD(\*args, \*\*kwargs)
Deprecated. Please use Solution.get\_OD()

# rydiqule.experiments.get\_phase\_shift

# rydiqule.experiments.get\_phase\_shift(\*args, \*\*kwargs)

Deprecated. Please use Solution.get\_phase\_shift()

# rydiqule.experiments.get\_snr

rydiqule.experiments.get\_snr (*sensor*: Sensor, *param\_label: str*, *phase\_quadrature: bool = False*, diff\_nearest: bool = False, \*\*kwargs) → Tuple[ndarray, List[ndarray]]

Calculate a Sensor's signal-to-noise ratio in standard deviation, in a 1Hz bandwidth, to a specified signal parameter, assuming a homodyne measurement of optical field.

SNR is calculated with respect to the signal parameter, relative to the initial value of the signal parameter. The returned mesh is similarly transformed from the typical sensor mesh, by replacing the total value of the signal parameter with the deviation in the signal parameter.

The conventions used follow that  $of^1$ .

**Note:** The default is to return the SNR of an amplitude quadrature measurement. To convert to a power measurement (i.e.  $\Omega_p^2$ ), the amplitude quadrature SNR must be divided by 2. To get the SNR in variance, square the result.

### Parameters

- **sensor** (Sensor) sensor for which SNR should be calculated. The definition of sensor.couplings should contain at least one coupling with a list-like parameter. For the list-like parameter, the first array element is the "base" against which SNR for each other value is calculated.
- **param\_label** (*str*) Label of the axis with respect to which SNR is calculated. See Sensor.axis\_labels() for more details on axis labeling. The value corresponding to this label should be the list-like parameter with respect to which SNR should be calculated. This parameter list must have at least two elements, and SNR is calculated relative to the first element in the list for all other elements in the list.
- **phase\_quadrature** (bool, optional) Whether the sensor is measured in the phase quadrature of the probe laser. False denotes measurement in the amplitude quadrature. Default is False.
- diff\_nearest (bool, optional) Controls method by which the SNR is calculated. The default (False) calculates the SNR with respect to the 0 index value. Setting True calculates the SNR with respect to nearest neighbor differences.
- **kwargs** (*dict*, *optional*) Additional keyword arguments to pass to rq. solve\_steady\_state().

## Returns

- **snrs** (*numpy.ndarray*) Array of SNRs for the sensor with respect to the change in the signal parameter. Calculated in units of amplitude relative to noise standard deviation. SNR referenced to 1 second BW.
- **mesh** (*tuple(numpy.ndarray*)) Numpy meshgrid of the coupling parameters that yield each snr. The signal parameter axis now shows the signal change.

#### Raises

ValueError - If the specified param\_label is not in Sensor.axis\_labels()

<sup>&</sup>lt;sup>1</sup> D. H. Meyer, C. O'Brien, D. P. Fahey, K. C. Cox, and P. D. Kunz, "Optimal atomic quantum sensing using electromagnetically-induced-transparency readout," Phys. Rev. A, vol. 104, p. 043103, 2021.

# **Examples**

## References

## rydiqule.experiments.get\_solution\_element

```
rydiqule.experiments.get_solution_element(*args, **kwargs)
Deprecated. Please use Solution.get_solution_element().
```

## rydiqule.experiments.get\_susceptibility

```
rydiqule.experiments.get_susceptibility(*args, **kwargs)
Deprecated. Please use Solution.get_susceptibility()
```

# rydiqule.experiments.get\_transmission\_coef

```
rydiqule.experiments.get_transmission_coef(*args, **kwargs)
Deprecated. Please use Solution.get_transmission_coef().
```

# 6.1.5 rydiqule.rydiqule\_utils

General rydiqule package utilities

# Functions

| about([obscure_paths]) | About box describing Rydiqule and its core depen- |
|------------------------|---|
|                        | dencies.  |

## rydiqule.rydiqule\_utils.about

rydiqule.rydiqule\_utils.about (obscure\_paths: bool = True)

About box describing Rydiqule and its core dependencies.

Prints human readable strings of information about the system.

#### Parameters

**obscure\_paths** (*bool*, *optional*) – Remove user directory from printed paths. Default is True.

## **Examples**

```
>>> import rydiqule as rq
>>> rq.about()
       Rydiqule
    _____
Rydigule Version:
                   0.4.0
Installation Path: C:\~\rydiqule\src\rydiqule
   Dependencies
   _____
NumPy Version: 1.21.5
SciPy Version: 1.7.3
Matplotlib Version: 3.5.2
ARC Version: 3.2.1
Python Version: 3.9.12
                     3.9.12
Python Install Path: C:\~\miniconda3\envs\arc
Platform Info: Windows (AMD64)
CPU Count:
                     16
Total System Memory: 256 GB
```

# 6.1.6 rydiqule.sensor

Sensor objects that control solvers.

# **Module Attributes**

| BASE_SCANNABLE_KEYS | Reference list of all coherent coupling keys that support  |
|---------------------|--|
|                     | rydiqules stacking convention.                             |
| BASE_EDGE_KEYS      | Reference list of all keys that can be specified with val- |
|                     | ues in a coherenct coupling.                               |

## rydiqule.sensor.BASE\_SCANNABLE\_KEYS

```
rydiqule.sensor.BASE_SCANNABLE_KEYS = ['detuning', 'rabi_frequency',
'phase', 'transition_frequency', 'e_shift']
```

Reference list of all coherent coupling keys that support rydiqules stacking convention. Note that all decoherence keys (keys beginning with gamma\_) are supported, but handled separately.

### rydiqule.sensor.BASE\_EDGE\_KEYS

```
rydiqule.sensor.BASE_EDGE_KEYS = ['states', 'detuning', 'rabi_frequency',
'transition_frequency', 'phase', 'kvec', 'time_dependence', 'label',
'dipole_moment']
```

Reference list of all keys that can be specified with values in a coherenct coupling. Subclasses which inherit from *Sensor* should override the valid\_parameters attribute, NOT this list. The valid\_parameters attribute is initialized as a copy of BASE\_EDGE\_KEYS.

#### Classes

| Sensor(basis, *couplings) | Class that contains minimum information necessary to |
|---------------------------|--|
|                           | run the solvers.                                     |

## rydiqule.sensor.Sensor

class rydiqule.sensor.Sensor(basis: Union[int, List[Union[int, str]]], \*couplings: Dict)

Bases: object

Class that contains minimum information necessary to run the solvers.

Consider this class the theorist's interface to the solvers. It requires nearly complete, explicit specification of inputs. This allows for very fine control of the solvers, including the ability to solve systems that are not entirely physical.

**\_init\_\_** (*basis: Union[int, List[Union[int, str]]], \*couplings: Dict*)  $\rightarrow$  None

Initializes the Sensor with the specified basis .

Can be specified as either an integer number of states (which will automatically label the states [0, ..., basis\_size]) or list of state labels.

#### **Parameters**

- **basis** (*int* or *list* of *int*, *str*) The specification of the basis size and labelling for a new Sensor. Can be specified by either a integer or a list. If specified as an integer n, the created Sensor will have n states labelled as 0, ... n. In the case of a list, a number of states equal to the length of the list will be created in the sensor, indexed by the integer or string values of the nodes.
- **\*couplings** (*tuple(dict)*) Couplings dictionaries to pass to *add\_couplings()* on sensor construction.

Raises

- **TypeError** If basis is not an integer or iterable.
- **TypeError** If any of the state label specifications of basis are the wrong type.

## **Examples**

Providing an integer will define a sensor with the given basis size, labelled with ascending integers.

```
>>> s = rq.Sensor(3)
>>> print(s.states)
[0, 1, 2]
```

States can also be defined with a list of integers:

```
>>> s = rq.Sensor([0, 1, 2])
>>> print(s.states)
[0, 1, 2]
```

#### States can also be strings

```
>>> s = rq.Sensor(['g', 'e1', 'e2'])
>>> print(s.states)
['g', 'e1', 'e2']
```

Using None in a list will default to using the integer corresponding to the state:

```
>>> s = rq.Sensor(['g', None, None])
>>> print(s.states)
['g', 1, 2]
```

# Methods

| init(basis, *couplings)                           | Initializes the Sensor with the specified basis .    |
|---|--|
| add_coupling(states[, rabi_frequency,])           | Adds a single coupling of states to the system.      |
| add_couplings(*couplings, **extra_kwargs)         | Add any number of couplings between pairs of         |
|   | states.  |
| add_decoherence(states, gamma[, label])           | Add decoherent coupling to the graph between two     |
|   | states.  |
| add_energy_shift(state, shift)                    | Add an energy shift to a state.                      |
| add_energy_shifts(shifts)                         | Add multiple energy shifts to different nodes.       |
| add_self_broadening(node, gamma[, la-             | Specify self-broadening (such as collisional broad-  |
| bel])   | ening) of a level.                                   |
| <pre>add_transit_broadening(gamma_transit[,</pre> | Adds transit broadening by adding a decoherence      |
| ])  | from each node to ground.                            |
| <pre>axis_labels([collapse, full_labels])</pre>   | Get a list of axis labels for stacked hamiltonians.  |
| <pre>couplings_with(*keys[, method])</pre>        | Returns a version of self.couplings with only the    |
|   | keys specified.                                      |
| decoherence_matrix()                              | Build a decoherence matrix out of the decoherence    |
|   | terms of the graph.                                  |
| dm_basis()  | Generate basis labels of density matrix components.  |
| get_coupling_rabi([coupling_tuple])               | Helper function that returns the Rabi frequency of   |
|   | the coupling from a Sensor for use in functions that |
|   | return experimental values.                          |
| get_couplings()                                   | Returns the couplings of the system as a dictionary  |
| get_doppler_shifts()                              | Returns the Hamiltonian with only detunings set to   |
|   | the kvector values for each spatial dimension.       |
| get_hamiltonian()                                 | Creates the Hamiltonians from the couplings defined  |
|   | by the fields.                                       |
| get_hamiltonian_diagonal(values[,                 | Apply addition and subtraction logic corresponding   |
| no_stack])  | to the direction of the couplings.                   |
| get_parameter_mesh()                              | Returns the parameter mesh of the sensor.            |
| get_rotating_frames()                             | Determines the rotating frames for the disconnected  |
|   | subgraphs.   |
| get_time_couplings()                              | Returns the list of matrices of all couplings in the |
|   | system defined with a time_dependence key.           |
| get_time_dependence()                             | Function which returns a list of the time_depen-     |
|   | dence functions.                                     |
| <pre>get_time_hamiltonians()</pre>                | Get the hamiltonians for the time solver.            |
| get_transition_frequencies()                      | Gets an array of the diagonal elements of the Hamil- |
|   | tonian from the field detunings.                     |
| get_value_dictionary( <b>key</b> )                | Get subset of dictionary coupling parameters.        |
| <pre>set_experiment_values(probe_tuple,[,</pre>   | Sets attributes needed for observable calculations.  |
| ])  |  |
| <pre>set_gamma_matrix(gamma_matrix)</pre>         | Set the decoherence matrix for the system.           |
| spatial_dim()                                     | Returns the number of spatial dimensions doppler     |
|   | averaging will occur over.                           |
| states_with_label(label)                          | Return a dict of all states with a label matching a  |
|   | given regular expression (regex) pattern.            |
| <pre>unzip_parameters(zip_label[, verbose])</pre> | Remove a set of zipped parameters from the internal  |
|   | zipped_parameters list.                              |

continues on next page

| Table 6.2 – continued from previous page            |  |  |
|---|--|--|
| <pre>variable_parameters([apply_mesh])</pre>        | Property to retrieve the values of parameters that |  |
|   | were stored on the graph as arrays.                |  |
| <pre>zip_parameters(*parameters[, zip_label])</pre> | Define 2 scannable parameters as "zipped" so they  |  |
|   | are scanned in parallel.                           |  |

# Attributes

| basis_size  | Property to return the number of nodes on the Sen-     |
|-------------|--|
|             | sor graph.   |
| beam_area   | Cross-sectional area of the probing beam, in square    |
|             | meters.  |
| cell_length | Optical path length of the medium, in meters.          |
| eta         | Noise density prefactor, in units of root(Hz).         |
| kappa       | Differential prefactor, in units of (rad/s)/m.         |
| probe_freq  | Probing transition frequency, in rad/s.                |
| probe_tuple | Coupling edge that corresponds to the probing field.   |
| states      | Property which gets a list of labels for the sensor in |
|             | the order defined in().                                |

**\_add\_coupling** (*states: Tuple[Union[int, str], Union[int, str]*], \*\**field\_params*)  $\rightarrow$  None

Function for internal use which will ensure the supplied couplings is valid, add the field to self.couplings.

Exists to abstract away some of the internally necessary bookkeeping functionality from user-facing classes.

### **Parameters**

- **states** (*tuple*) The integer pair of states to be coupled.
- **\*\*field\_params** (*dict*) The dictionry of couplings parameters. For details on the keys of the dictionry see *add\_coupling()*.

## \_collapse\_mesh(mesh)

Collapses the given mesh using rydiqule logic for parameter zipping.

Expected to be given a mesh which is generated by applying numpy.meshgrid function on the output of *variable\_parameters()* for the system. Given such a mesh, ensures that output mesh matches the shape expected by rydiqule's stacking convention, meaning that parameters that are zipped together will share an axis in the hamiltonian stack.

### Parameters

**mesh** (*tuple* (*numpy.ndarray*)) – The uncollapsed meshgid of parameters for the system. Typically the output of numpy.meshgrid called on *variable\_parameters* ().

## Returns

The collapsed meshgid with zipped parameters sharing and axis.

### **Return type**

tuple(np.ndarray)

**\_coupling\_with\_label** (*label: str*)  $\rightarrow$  Tuple[Union[int, str], Union[int, str]]

Helper function to return the pair of states corresponding to a particular label string. For internal use.

# \_remove\_edge\_data (states: Tuple[Union[int, str], Union[int, str]], kind: str)

Helper function to remove all data that was added with a *add\_coupling()* call or *add\_decoher-ence()* call. Needed to ensure that two nodes do not have coherent couplings pointing both ways and to invalidate existing zip parameter couplings.

### **Parameters**

- **states** (*tuple*) Edge from which to remove data.
- kind (*str*) What type of data to remove. Valid options are coherent coherent couplings or the incoherent key to be cleared (must start with gamma).

### Raises

ValueError - If kind is not 'coherent' and doesn't begin with 'gamma'

**\_stack\_shape** (*time\_dependence: Literal['steady', 'time', 'all']* = 'all')  $\rightarrow$  Tuple[int, ...]

Internal function to get the shape of the tuple preceding the two hamiltonian axes in get\_hamiltonian()

**\_states\_valid** (*states: Sequence*)  $\rightarrow$  Tuple[Union[int, str], Union[int, str]]

Confirms that the provided states are in a valid format.

Typically used internally to validate states added. If provided as a form other than a tuple, first casts to a tuple for consistent indexing.

Checks that states contains 2 elements, can be interpreted as a tuple, and that both states lie inside the basis.

#### Parameters

**states** (*iterable*) – iterable of to validate. Should be a pair of integers that can be cast to a tuple.

#### Returns

Length 2 tuple of validated state labels.

Return type tuple

Raises

- ValueError If states has more than two elements.
- **TypeError** If states cannot be converted to a tuple.
- ValueError If either state in states is outside the basis.

add\_coupling (states: Tuple[Union[int, str], Union[int, str]], rabi\_frequency: Optional[Union[float, List[float], ndarray]] = None, detuning: Optional[Union[float, List[float], ndarray]] = None, transition\_frequency: Optional[float] = None, phase: Union[float, List[float], ndarray] = 0, kvec: Tuple[float, float, float] = (0, 0, 0), time\_dependence: Optional[Callable[[float], float]] = None, label: Optional[str] = None, \*\*extra\_kwargs) → None

Adds a single coupling of states to the system.

One or more of these parameters can be a list or array-like of values to represent a laser that can take on a set of discrete values during a field scan. Designed to be a user-facing wrapper for \_add\_coupling() with arguments for states and coupling parameters.

#### Parameters

- **states** (*tuple of ints or strings of length 2*) The pair of states of the sensor which the state couples. Must be a tuple of length 2, where each element is a string or integer corresponding to a state in the Sensor as defined in the constructor. Tuple order indicates which state to has higher energy; the second state is always assumed to have higher energy.
- **rabi\_frequency** (float or complex, or list-like of float or complex) The rabi frequency of the field being added. Defined in units of Mrad/s. List-like values will invoke Rydiqule's stacking convention when relevant quantities are calculated.
- **detuning**(*float* or *list-like* of *floats*, *optional*)-The frequency difference between the transition frequency and the field frequency in units of Mrad/s. List-like values will invoke Rydiqule's stacking convention when relevant quantities are

calculated. If specified, the coupling is treated with the rotating-wave approximation rather than in the lab frame, and transition\_frequency is ignored if present. A positive number always indicates a blue detuning, and a negative number indicates a blue detuning.

- transition\_frequency (float or list-like of floats, optional) - The transition frequency between a particular pair of states. Must be a positive number. List-like values will invoke Rydiqule's stacking convention when relevant quantities are calculated. Only used directly in calculations if detuning is None, ignored otherwise. Note that on its own, it only defines the spacing between two energy levels and not the field itsself. To define a field, the time\_dependence argument must be specified, or else the off-diagonal terms to drive transitions will not be generated in the Hamiltonian matrix.
- **phase** (*float*, *optional*) The relative phase of the field in radians. Defaults to zero.
- **kvec** (*iterable*, *optional*) A three-element iterable that defines the atomic doppler shift on a particular coupling field. It should have magnitude equal to the doppler shift (in the units of Mrad/s) of a n atom moving at the Maxwell-Boltzmann distribution most probable speed, vP=np.sqrt(2\*kB\*T/m). I.E. np.linalg. norm(kvec)=2\*np.pi/lambda\*vP. If equal to (0,0,0), solvers will ignore doppler shifts on this field. Defaults to (0,0,0).
- time\_dependence(scalar function, optional) A scalar function specifying a time-dependent field. The time dependence function is defined as a python funtion that returns a unitless value as a function of time (in microseconds) that is multiplied by the rabi\_frequency parameter to get a field strength scaled to units of Mrad/s.
- **label** (*str or None, optional*) Name of the coupling. This does not change any calculations, but can be used to help track individual couplings, and will be reflected in the output of *axis\_labels()*, and to specify zipping for zip\_couplings(). If None, the label is generated as the value of states cast to a string with whitespace removed. Defaults to None.

### Raises

- **ValueError** If states cannot be interpreted as a tuple.
- ValueError If states does not have a length of 2.
- ValueError If the state numbers specified by states are beyond the basis size. For example, calling this function with states=(3, 4) will raise this error if the basis size is equal to 3.
- **ValueError** If both rabi\_frequency and dipole\_moment are specified or if neither are specified.
- **ValueError** If both detuning and transition\_frequency are specified or if neither are specified.

### **Examples**

```
>>> s = rq.Sensor(2)
>>> s.add_coupling(states=(0,1), detuning=1, rabi_frequency=2)
>>> s = rq.Sensor(['g', 'e'])
>>> s.add_coupling(('g', 'e'), detuning=1, rabi_frequency=1)
>>> s = rq.Sensor(2)
>>> s.add_coupling(states=(0,1), detuning=np.linspace(-10, 10, 101), rabi_
+frequency=2, label="laser")
```

```
>>> s = rq.Sensor(2)
>>> kp = 250*np.array([1,0,0])
>>> s.add_coupling(states=(0,1), detuning=1, rabi_frequency=2, kvec=kp)
```

## add\_couplings (\*couplings: Dict, \*\*extra\_kwargs) $\rightarrow$ None

Add any number of couplings between pairs of states.

Acts as an alternative to calling *add\_coupling()* individually for each pair of states. Can be used interchangably up to preference, and all of keyword *add\_coupling()* are supported dictionary keys for dictionaries passed to this function.

## Parameters

- **couplings** (*tuple of dicts*) Any number of dictionaries, each specifying the parameters of a single field coupling 2 states. For more details on the keys of each dictionry see the arguments for *add\_coupling()*. Equivalent to passing each dictiories keys and values to *add\_coupling()* individually.
- **\*\*extra\_kwargs** (*dict*) Additional keyword-only arguments to pass to the relevant add\_coupling method. The same arguments will be passed to each call of *add\_coupling()*. Often used for warning suppression.

#### Raises

ValueError – If the states parameter is missing.

# **Examples**

```
>>> s = rq.Sensor(3)
>>> blue = {"states":(0,1), "rabi_frequency":1, "detuning":2}
>>> red = {"states":(1,2), "rabi_frequency":3, "detuning":4}
>>> s.add_couplings(blue, red)
>>> print(s.couplings.edges(data=True))
[(0, 1, {'rabi_frequency': 1, 'detuning': 2, 'phase': 0, 'kvec': (0, 0, 0)}
...,
[(1, 2, {'rabi_frequency': 3, 'detuning': 4, 'phase': 0, 'kvec': (0, 0, 0)}
...,]
```

Add decoherent coupling to the graph between two states.

If gamma is list-like, the sensor will scan over the values, solving the system for each different gamma, identically to the scannable parameters in coherent couplings.

#### Parameters

- **states** (*tuple of ints*) Length-2 tuple of integers corresponding to the two states. The first value is the number of state out of which population decays, and the second is the number of the state into which population decays.
- gamma (float or sequence) The decay rate, in Mrad/s.
- **label** (*str or None, optional*) Optional label for the decay. If None, decay will be stored on the graph edge as "gamma". Otherwise, will cast as a string and decay will be stored on the graph edge as "gamma\_"+label.

### Notes

**Note:** Adding a decoherece with a particular label (including None) will override an existing decoherent transition with that label.

## **Examples**

s = rq.Sensor(3) >>> s.add\_coupling(states=(0,1), detuning=1, rabi\_frequency=1) >>> s.add\_coupling(states=(1,2), detuning=1, rabi\_frequency=1) >>> s.add\_decoherence((2,0), 0.1, label="misc") >>> print(s.decoherence\_matrix()) [[0. 0. 0. ] [0. 0. 0. ] [0.1 0. 0. ]]

Decoherence values can also be scanned. Here decoherece from states 2->0 is scanned between 0 and 0.5 for 11 values. We can also see how the Hamiltonian shape accounts for this to allow for clean broadcasting, indicating that the hamiltonian is identical accross all decoherence values.

```
>>> s = rq.Sensor(3)
>>> gamma = np.linspace(0,0.5,11)
>>> s.add_coupling(states=(0,1), detuning=1, rabi_frequency=1)
>>> s.add_coupling(states=(1,2), detuning=1, rabi_frequency=1)
>>> s.add_decoherence((2,0), gamma)
>>> print(s.decoherence_matrix().shape)
(11, 3, 3)
>>> print(s.get_hamiltonian().shape)
(11, 3, 3)
```

add\_energy\_shift (state: Union[int, str], shift: Union[float, List[float], ndarray])

Add an energy shift to a state.

First perfoms validation that the provided state is actually a node in the graph, then adds the shift specified by shift to a self-loop edge keyed with "e\_shift". This value will be added to the corresponding diagonal term when the hamiltonian is generated. If the provided node

### Parameters

- **state** (*str or int*) The label corresponding to the atomic state to which the shift will be added.
- **shift** (float or list-like of float) The magnitude of the energy shift, in Mrad/s

### Raises

**KeyError** – If the supplied state is not in the system.

#### add\_energy\_shifts (shifts: dict)

Add multiple energy shifts to different nodes.

Shifts are specified with the shifts dictionary, which is keyed with states and has values corresponding to the energy shift applied to the state in Mrad/s. Error handling and validation is done with the add\_energy\_shift() function.

## Parameters

**shifts** (*dict*) – Dictionary keyed with states with values corresponding to the energy shift, in Mrad/s, of the corresponding state.

add\_self\_broadening (node: int, gamma: Union[float, List[float], ndarray], label: str = 'self')

Specify self-broadening (such as collisional broadening) of a level.

Equivalent to calling *add\_decoherence()* and specifying both states to be the same, with the "self" label. For more complicated systems, it may be useful to further specify the source of self-broadening as, for example, "collisional" for easier bookkeeping and to ensure no values are overwritten.

#### **Parameters**

- **node** (*int*) The integer number of the state node to which the broadening will be added. The integer corresponds to the state's position in the graph.
- gamma (float or sequence) The broadening width to be added in Mrad/s.
- **label** (*str*, *optional*) Optional label for the state. If None, decay will be stored on the graph edge as "gamma". Otherwise, will cast as a string and decay will be stored on the graph edge as "gamma "+label

# Notes

**Note:** Just as with the *add\_decoherence()* function, adding a decoherence value with a label that already exists will overwrite an existing decoherent transition with that label. The "self" label is applied to this function automatically to help avoid an unwanted overwrite.

#### **Examples**

```
>>> s = rq.Sensor(3)
>>> s.add_self_broadening(1, 0.1)
>>> print(s.couplings.edges(data=True))
>>> print(s.decoherence_matrix())
[(1, 1, {'gamma_self': 0.1, 'label': '(1,1)'})]
[[0. 0. 0. ]
[0. 0.1 0. ]
[0. 0. 0. ]]
```

add\_transit\_broadening (gamma\_transit: Union[float, List[float], ndarray], repop: Union[None, Dict[Union[int, str], float]] = None, label:  $str = 'transit') \rightarrow None$ 

Adds transit broadening by adding a decoherence from each node to ground.

For each graph node n, adds a decoherent transition from n the specified state (0 by default) using the *add\_decoherence()* method with the "transit" label. See *add\_decoherence()* for more details on labeling.

If an array of transit values are provided, they will be automatically zipped together into a single scanning element.

#### **Parameters**

- gamma\_transit(float or sequence) The transit broadening rate in Mrad/s.
- **repop** (*dict*, *optional*) Dictionary of states for transit to repopulate in to. The keys represent the state labels. The values represent the fractional amount that goes to that state. If the sum of values does not equal 1, population will not be conserved. Default is to repopulate everything into the ground state (either state 0 or the first state in the basis passed to the \_\_init\_\_() method).

## Warns

- If the values of the `repop` parameter do not sum to 1, thus meaning
- population will not be conserved.

## **Examples**

```
>>> s = rq.Sensor(['g', 'e1', 'e2'])
>>> repop = {'g':0.75, 'e1': 0.25}
>>> s.add_transit_broadening(0.2, repop=repop)
>>> print(s.decoherence_matrix())
[[0.15 0.05 0. ]
[0.15 0.05 0. ]
[0.15 0.05 0. ]]
```

**axis\_labels** (*collapse: bool* = *True*, *full\_labels: bool* = *False*)  $\rightarrow$  List[str]

Get a list of axis labels for stacked hamiltonians.

The axes of a hamiltonian stack are defined as the axes preceding the usual hamiltonian, which are always the last 2. These axes only exist if one of the parametes used to define a Hamiltonian are lists.

Be default, labels which have been zipped using *zip\_parameters()* will be combined into a single label, as this is how *get\_hamiltonian()* treats these axes.

The ordering of axis labels is

Returns

Strings corresponding to the label of each axis on a stack of multiple hamiltonians.

Return type list of str

### **Examples**

There are no preceding axes if there are no list-like parameters.

```
>>> s = rq.Sensor(3)
>>> blue = {"states":(0,1), "rabi_frequency":1, "detuning":2}
>>> red = {"states":(1,2), "rabi_frequency":3, "detuning":4}
>>> s.add_couplings(blue, red)
>>> print(s.get_hamiltonian().shape())
>>> print(s.axis_labels())
(3,3)
[]
```

Adding list-like parameters expands the hamiltonian
The ordering of labels may change if string state names are used. The ordering is determined by the output of the *variable\_parameters()* method. See method documentation for more detail.

Zipping parameters combines their corresponding labels, since their Hamiltonians now lie on a single axis of the stack. Here the axis of length 7 (axis 0) corresponds to the rabi frequencies and the axis of shape 11 (axis 1) corresponds to the zipped detunings

#### property basis\_size

Property to return the number of nodes on the Sensor graph.

#### Returns

The number of nodes on the graph, corresponding to the basis size for the system.

### **Return type**

int

#### beam\_area: Optional[float] = None

Cross-sectional area of the probing beam, in square meters.

cell\_length: Optional[float] = None

Optical path length of the medium, in meters.

**couplings\_with** (\*keys: str, method: Literal['all', 'any', 'not any'] = 'all')  $\rightarrow$  Dict[Tuple[Union[int, str], Union[int, str]], Dict]

Returns a version of self.couplings with only the keys specified.

Can be specified with a several criteria, including all, none, or any of the keys specified.

### Parameters

- **str**) (*keys* (*tuple of*) parameter names for a state. See *add\_coupling(*) for which names are valid for a Sensor object.
- method ({'all', 'any', 'not any'}) Method to see if a given field matches the keys given. Choosing "all" will return couplings which have keys matching all of the values provided in the keys argument, while coosing "any", will return all couplings with keys matching at least one of the values specified by keys. For example, sensor.couplings\_with("rabi\_frequency")

returns a dictionary of all couplings for which a rabi\_frequency was specified. sensor.couplings\_with("rabi\_frequency", "detuning", method="all") returns all couplings for which both rabi\_frequency and detuning are specified. 'sensor.couplings\_with("rabi\_frequency", "detuning", method="any")` returns all couplings for which either rabi\_frequency or detuning are specified. Defaults to "all".

### Returns

A copy of the sensor.couplings dictionary with only couplings containing the specified parameter keys.

#### Return type

dict

### **Examples**

Can be used, for example, to return couplings in the roating wave approximation.

### decoherence\_matrix() $\rightarrow$ ndarray

Build a decoherence matrix out of the decoherence terms of the graph.

For each edge, sums all parameters with a key that begins with "gamma", and places it on the appropriate location in an adjacency matrix for the couplings graph.

#### Returns

The decoherence matrix stack of the system.

#### **Return type**

numpy.ndarray

#### Examples

```
>>> s = rq.Sensor(3)
>>> s.add_decoherence((1,0), 0.2, label="foo")
>>> s.add_decoherence((1,0), 0.1, label="bar")
>>> s.add_decoherence((2,0), 0.05)
>>> s.add_decoherence((2,1), 0.05)
>>> print(s.couplings.edges(data=True))
>>> print(s.decoherence_matrix())
[(1, 0, {'gamma_foo': 0.2, 'label': '(1,0)', 'gamma_bar': 0.1}), (2, 0, {
→ 'gamma': 0.05, 'label': '(2,0)'}), (2, 1, {'gamma': 0.05, 'label': '(2,1)
[[0.
      Ο.
          0. ]
[0.3 0.
          0.]
[0.05 0.05 0. ]]
```

Decoherences can be stacked just like any parameters of the Hamiltonian:

```
>>> s = rq.Sensor(3)
>>> gamma = np.linspace(0,0.5, 11)
>>> s.add_decoherence((1,0), gamma)
>>> print(s.decoherence_matrix().shape)
(11,3,3)
```

Defining decoherences between states labelled with string values works just like coherent couplings:

```
>>> s = rq.Sensor(['g', 'e1', 'e2'])
>>> s.add_decoherence(('e1', 'g'), 0.1)
>>> s.add_decoherence(('e2', 'g'), 0.1)
>>> s.decoherence_matrix()
array([[0., 0., 0.],
        [0.1, 0., 0.],
        [0.1, 0., 0.]])
```

#### $dm\_basis() \rightarrow ndarray$

Generate basis labels of density matrix components.

The basis corresponds to the elements in the solution. This is not the complex basis of the sensor class, but rather the real basis of a solution after calling one of rydiqule's solvers. This means that the ground state population has been removed and it has been transformed to the real basis.

#### Returns

Array of string labels corresponding to the solving basis. Is a 1-D array of length n\*\*2-1.

Return type numpy.ndarray

### **Examples**

```
>>> s = rq.Sensor(3)
>>> print(s.basis())
['01_real' '02_real' '01_imag' '11_real' '12_real' '02_imag' '12_imag'
'22_real']
```

### eta: Optional[float] = None

Noise density prefactor, in units of root(Hz). Must be specified when using *Sensor*. Automatically calculated when using Cell.

get\_coupling\_rabi (*coupling\_tuple: Tuple[Union[int, str], Union[int, str]]* = (0, 1))  $\rightarrow$  Union[float, ndarray]

Helper function that returns the Rabi frequency of the coupling from a Sensor for use in functions that return experimental values.

### Parameters

**coupling\_tuple** (*tuple of int*) – The tuple that defines the coupling to extract to rabi frequencies from

### Returns

Rabi frequency defined in the Sensor

#### **Return type**

float of numpy.ndarray

#### Warns

**UserWarning** – If the coupling has time dependence. In this case, the returned Rabi frequency may not be well defined.

### get\_couplings () $\rightarrow$ Dict[Tuple[Union[int, str], Union[int, str]], Dict]

Returns the couplings of the system as a dictionary

Deprecating in favor of calling the couplings.edges attribute directly.

#### Returns

A dictionary of key-value pairs with the keys corresponding to levels of transition, and the values being dictionaries of coupling attributes.

#### **Return type**

dict

#### get\_doppler\_shifts() $\rightarrow$ ndarray

Returns the Hamiltonian with only detunings set to the kvector values for each spatial dimension.

Determining if a float should be treated as zero is done using numpy.isclose, which has default absolute tolerance of 1e-08.

#### Returns

Array of shape (used\_spatial\_dim,n,n), Hamiltonians with only the doppler shifts present along each non-zero spatial dimension specified by the fields' "kvec" parameter.

#### **Return type**

numpy.ndarray

### get\_hamiltonian() $\rightarrow$ ndarray

Creates the Hamiltonians from the couplings defined by the fields.

They will only be the steady state hamiltonians, i.e. will only contain terms which do not vary with time. Implicitly creates hamiltonians in "stacks" by creating a grid of all supported coupling parameters which are lists. This grid of parameters will not contain rabi-frequency parameters which vary with time and are defined as list-like. Rather, the associated axis will be of length 1, with the scanning over this value handled by the *get\_time\_couplings()* function.

For m list-like parameters  $x_{1,x_{2,...,x_{m}}}$  with shapes N1,N2,...,Nm, and basis size n, the output will be shape (N1,N2,...,Nm, n, n). The dimensions N1,N2,...Nm are labeled by the output of  $axis\_labels()$ .

If any parameters have been zipped with the  $\_zip\_parameters()$  method, those parameters will share an axis in the final hamiltonian stack. In this case, if axis N1 and N2 above are the same shape and zipped, the final Hamiltonian will be of shape (N1, ..., Nm, n, n).

In the case where the basis of the Sensor was explicitly defined with a list of states, the ordering of rows and coulumns in the hamiltonian corresponds to the ordering of states passed in the basis.

See rydiqule's conventions for matrix stacking for more details.

### Returns

The complex hamiltonian stack for the sensor.

### Return type np.ndarray

### Examples

```
>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)
>>> blue = {"states":(0,1), "rabi_frequency":1, "detuning":det}
>>> red = {"states":(1,2), "rabi_frequency":3, "detuning":det}
>>> s.add_couplings(red, blue)
>>> print(s.get_hamiltonian().shape)
(11, 11, 3, 3)
```

Time dependent couplings are handled separately. The axis that contains array-like parameters with time dependence is length 1 in the steady-state Hamiltonian.

```
>>> s = rq.Sensor(3)
>>> rabi = np.linspace(-1,1,11)
>>> step = lambda t: 0 if t<1 else 1
>>> blue = {"states":(0,1), "rabi_frequency":rabi, "detuning":1}
>>> red = {"states":(1,2), "rabi_frequency":rabi, "detuning":0, 'time_
->> dependence': step}
>>> s.add_couplings(red, blue)
>>> print(s.get_hamiltonian().shape)
(11, 1, 3, 3)
```

Zipping parameters means they share an axis in the Hamiltonian.

If the basis is provided as a list of string labels, the ordering of Hamiltonian rows And columns will correspond to the order of states provided.

```
>>> s = rq.Sensor(['g', 'e1', 'e2'])
>>> s.add_coupling(('g', 'e1'), detuning=1, rabi_frequency=1)
>>> s.add_coupling(('e1', 'e2'), detuning=1.5, rabi_frequency=1)
>>> print(s.get_hamiltonian())
[[ 0. +0.j 0.5+0.j 0. +0.j]
[ 0.5-0.j -1. +0.j 0.5+0.j]
[ 0. +0.j 0.5-0.j -2.5+0.j]]
```

get\_hamiltonian\_diagonal (values: dict, no\_stack: bool = False)  $\rightarrow$  ndarray

Apply addition and subtraction logic corresponding to the direction of the couplings.

For a given state n, the path from ground will be traced to n. For each edge along this path, values will be added where the path direction and coupling direction match, and subtracting values where they do not. The sum of all such values along the path is the n th term in the output array.

Primarily for internal functions which help generate hamiltonians. Most commonly used to calculate total detunings for ranges of couplings under the RWA

### Parameters

- **values** (*dict*) Key-value pairs where the keys correspond to transitions (agnostic to ordering of states) and values corresponding to the values to which the logic will be applied.
- **no\_stack** (*bool*, *optional*) Whether to ignore variable parameters in the system and use only basic math operations rather than reshape the output. Typically only True for calculating doppler shifts.

#### Returns

The digonal of the hamiltonian of the system of shape (\*l, n), where l is the shape of the hamiltonian stack for the sensor.

### **Return type**

numpy.ndarray

# get\_parameter\_mesh() $\rightarrow$ List[ndarray]

Returns the parameter mesh of the sensor.

The parameter mesh is the flattened grid of variable parameters in all the couplings of a sensor. Wraps numpy.meshgrid with the indexing argument always "ij" for matrix indexing.

Returns

list of mesh grids for every variable parameter

#### Return type

list of numpy.ndarray

### Examples

```
>>> s = rq.Sensor(3)
>>> rabi1 = np.linspace(-1,1,11)
>>> rabi2 = np.linspace(-2,2,21)
>>> s.add_coupling(states=(0,1), rabi_frequency=rabi1, detuning=1)
>>> s.add_coupling(states=(1,2), rabi_frequency=rabi2, detuning=1)
>>> for p in s.get_parameter_mesh():
... print(p.shape)
(11, 1)
(1, 21)
```

### get\_rotating\_frames() $\rightarrow$ dict

Determines the rotating frames for the disconnected subgraphs.

Each returned path gives the states traversed, and the sign gives the direction of the coupling. If the sign is negative, the coupling is going to a lower energy state. Choice of frame depends on graph distance to lowest indexed node on subgraph, ties broken by lowest indexed path traversed first.

#### Returns

Dictionary keyed by disconnected subgraphs, values are path dictionaries for each node of the subgraph. Each path shows the node indexes traversed, where a negative sign denotes a transition to a lower energy state.

Return type

dict

#### get\_time\_couplings() → Tuple[List[ndarray], List[ndarray]]

Returns the list of matrices of all couplings in the system defined with a time\_dependence key.

The ouput will be two lists of matricies representing which terms of the hamiltonian are dependent on each time-dependent coupling. The lists will be of length M and shape ( $\pm 1_tme, n, n$ ), where M is the number of time-dependent couplings,  $1_tme$  is time-dependent stack shape (possibly all ones), and n is the basis size. Each matrix will have terms equal to the rabi frequency (or half the rabi frequency under RWA) in positions that correspond to the associated transition. For example, in the case where there is a time\_dependence function defined for the (2, 3) transition with a rabi frequency of 1, the associated time coupling matrix will be all zeros, with a 1 in the (2, 3) and (3, 2) positions.

Typically, this function is called internally and multiplied by the output of the *get\_time\_depen-dence()* function.

#### Returns

- *list of numpy.ndarray* The list of M (\*l, n, n) matrices representing the real-valued time-dependent portion of the hamiltonian. For  $0 \le i \le M$ , the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.
- *list of numpy.ndarray* The list of M (\*1,n,n) matrices representing the imaginary-valued time-dependent portion of the hamiltonian. For 0 <= i <= M, the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.

#### **Examples**

```
>>> s = rq.Sensor(3)
>>> step = lambda t: 0 if t<1 else 1
>>> wave = lambda t: np.sin(2000*np.pi*t)
>>> f1 = {"states": (0,1), "transition_frequency":10, "rabi_frequency": 1,

→ "time_dependence":wave}
>>> f2 = {"states": (1,2), "transition_frequency":10, "rabi_frequency": 2,

→ "time dependence":step}
>>> s.add couplings(f1, f2)
>>> time_hams, time_hams_i = s.get_time_couplings()
>>> for H in time_hams:
       print(H)
. . .
[[0.+0.j 1.+0.j 0.+0.j]
[1.+0.j 0.+0.j 0.+0.j]
[0.+0.j 0.+0.j 0.+0.j]]
[[0.+0.j 0.+0.j 0.+0.j]
[0.+0.j 0.+0.j 2.+0.j]
[0.+0.j 2.+0.j 0.+0.j]]
```

To handle stacking across the steady-state and time hamiltonians, the dimensions are matched in a way that broadcasting works in a numpy-friendly way

```
>>> s = rq.Sensor(3)
>>> rabi = np.linspace(-1,1,11)
>>> step = lambda t: 0 if t<1 else 1
>>> blue = {"states":(0,1), "rabi_frequency":rabi, "detuning":1}
>>> red = {"states":(1,2), "rabi_frequency":rabi, "detuning":0, 'time_
...dependence': step}
>>> s.add_couplings(red, blue)
>>> time_hams, time_hams_i = s.get_time_couplings()
>>> print(s.get_hamiltonian().shape)
>>> print(time_hams[0].shape)
>>> print(time_hams_i[0].shape)
(1, 11, 3, 3)
(11, 1, 3, 3)
```

get\_time\_dependence()  $\rightarrow$  List[Callable[[float], complex]]

Function which returns a list of the time\_dependence functions.

The list is returned with in the order that matches with the time hamiltonians from get\_time\_couplings() such that the ith element of the return of this functions corresponds with the ith Hamiltonian terms returned by that function.

### Returns

List of scalar functions, representing all couplings specified with a time\_dependence.

Return type list

### **Examples**

### get\_time\_hamiltonians() → Tuple[ndarray, List[ndarray], List[ndarray]]

Get the hamiltonians for the time solver.

Get both the steady state hamiltonian (as returned by get\_hamiltonian()) and the time\_dependent hamiltonians (as returned by get\_time\_couplings()). The time dependent hamiltonians give 2 terms, the hamiltonian corresponding to the real part of the coupling and the hamiltonian corresponding to the imaginary part.

In the case where the basis of the Sensor was explicitly defined with a list of states, the ordering of rows and coulumns in the hamiltonian corresponds to the ordering of states passed in the basis.

### Returns

- hamiltonian\_base (*np.ndarray*) The (\*1, n, n) shape base hamiltonian of the system containing all elements that do not depend on time, where n is the basis size of the sensor.
- **dipole\_matrix\_real** (*np.ndarray*) The (M, n, n) shape array of matrices representing the real time-dependent portion of the hamiltonian. For 0 <= i <= M, the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.
- **dipole\_matrix\_imag** (*nd.ndarray*) The (M, n, n) shape array of matrices representing the imaginary time-dependent portion of the hamiltonian. For  $0 \le i \le M$ , the ith value along the first axis is the portion of the matrix which will be multiplied by the output of the ith time\_dependence function.

### Examples

If the basis is passed as a list, rows and columns are in the order specified:

```
>>> s = rq.Sensor(['g', 'e'])
>>> step = lambda t: 0. if t<1 else 1.
>>> s.add_coupling(states=('g','e'), detuning=1, rabi_frequency=1, time_
...dependence=step)
>>> H_base, H_time_real, H_time_imaginary = s.get_time_hamiltonians()
>>> print(H_base)
>>> print(H_time_real)
>>> print(H_time_imaginary)
[[ 0.+0.j 0.+0.j]
[ 0.+0.j -1.+0.j]]
[ array([[0. +0.j, 0.5+0.j],
        [0.5+0.j, 0. +0.j]])]
[ array([[0.+0.j, 0.+0.5j],
        [0.-0.5j, 0.+0.j]])]
```

### get\_transition\_frequencies() $\rightarrow$ ndarray

Gets an array of the diagonal elements of the Hamiltonian from the field detunings.

Wraps the get\_hamiltonian\_diagonal() function using both transition frequencies and detunings. Primarily for internal use.

#### Returns

N-D array of the hamiltonian diagonal. For an n-level system with stack shape (1, n)

#### **Return type**

numpy.ndarray

#### get\_value\_dictionary (key: str) $\rightarrow$ dict

Get subset of dictionary coupling parameters.

Return a dictionary of key value pairs where the keys are couplings added to the system and the values are the value of the parameter specified by key. Produces an output that can be passed directly to get\_hamiltonian\_diagonal(). Only couplings whose parameter dictionaries contain "key" will be in the returned dictionary.

### Parameters

**key** (*str*) - String value of the parameter name to build the dictionary. For example, get\_value\_dictionary("detuning") will return a dictionary with keys corresponding to transitions and values corresponding to detuning for each transition which has a detuning.

#### Returns

Coupling dictionary with couplings as keys and corresponding values set by input key.

#### **Return type**

dict

### **Examples**

```
>>> s = rq.Sensor(4)
>>> f1 = {"states": (0,1), "detuning": 2, "rabi_frequency": 1}
>>> f2 = {"states": (1,2), "detuning": 3, "rabi_frequency": 2}
>>> f3 = {"states": (2,3), "rabi_frequency": 3, "transition_frequency": 3}
>>> s.add_couplings(f1, f2, f3)
>>> print(s.get_value_dictionary("detuning"))
{(0,1): 2, (1,2): 3}
```

### kappa: Optional[float] = None

Differential prefactor, in units of (rad/s)/m. Must be specified when using *Sensor*. Automatically calculated when using Cell.

# probe\_freq: Optional[float] = None

Probing transition frequency, in rad/s.

- probe\_tuple: Optional[Tuple[Union[int, str], Union[int, str]]] = None
  Coupling edge that corresponds to the probing field. Defaults to (0,1) in Cell.

Sets attributes needed for observable calculations.

#### **Parameters**

- **probe\_tuple** (*tuple of int*) Coupling that corresponds to the probing field.
- probe\_freq (float) Frequency of the probing transition, in Mrad/s.
- **kappa** (*float*) Numerical prefactor that defines susceptibility, in (rad/s)/m. See *get\_susceptibility()* and Cell.kappa for details.
- **eta** (*float*) Noise-density prefactor, in root(Hz). See Cell.eta for details.
- **cell\_length**(*float*, *optional*) The optical path length through the medium, in meters.
- beam\_area (float, optional) The cross-sectional area of the beam, in m^2.

### set\_gamma\_matrix (gamma\_matrix: ndarray)

Set the decoherence matrix for the system.

Works by first removing all existing decoherent data from graph edges, then individually adding all nonzero terms of a provided gamma matrix to the corresponding graph edges. Can be used to set all decoherence attributes to edges simultaneously, but add\_decoherence() is preferred.

Unlike *add\_decoherence()*, does not support scanning multiple decoherence values, rather should be used to set the decoherences of the system to individual static values.

#### Parameters

```
gamma_matrix (numpy.ndarray) - Array of shape (basis_size, basis_size). Element (i,j) describes the decoherence rate, in Mrad/s, from state i to state j.
```

#### Raises

- **TypeError** If gamma\_matrix is not a numpy array.
- ValueError If gamma\_matrix is not a square matrix of the appropriate size
- **ValueError** If the shape of gamma\_matrix is not compatible with self. basis\_size.

### **Examples**

```
>>> s = rq.Sensor(2)
>>> f1 = {"states": (0,1), "transition_frequency":10, "rabi_frequency": 1}
>>> s.add_couplings(f1)
>>> gamma = np.array([[.1,0],[.1,0]])
>>> s.set_gamma_matrix(gamma)
>>> print(s.decoherence_matrix())
[[0.1 0. ]
[0.1 0. ]]
```

#### $spatial_dim() \rightarrow int$

Returns the number of spatial dimensions doppler averaging will occur over.

Determining if a float should be treated as zero is done using numpy.isclose, which has default absolute tolerance of 1e-08.

#### Returns

Number of dimensions, between 0 and 3, where 0 means no doppler averaging kvectors have been specified or are too small to be calculates.

Return type

int

### **Examples**

No spatial dimesions specified

```
>>> s = rq.Sensor(2)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1)
>>> print(s.spatial_dim())
0
```

One spatial dimension specified

```
>>> s = rq.Sensor(2)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1, kvec=(0,0,1))
>>> print(s.spatial_dim())
1
```

Multiple spatial dimensions can exist in a single coupling or across multiple couplings

```
>>> s = rq.Sensor(2)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1, kvec=(1,0,1))
>>> print(s.spatial_dim())
2
```

```
>>> s = rq.Sensor(3)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1, kvec=(1,0,1))
>>> s.add_coupling((1,2), detuning = 2, rabi_freqency=2, kvec=(0,1,0))
>>> print(s.spatial_dim())
3
```

#### property states

Property which gets a list of labels for the sensor in the order defined in <u>\_\_init\_\_</u>(). This is also the order corresponding the rows and columns in the system Hamiltonian and decoherence matrix.

#### Returns

List of states of the system defined the constructor, in the order corresponding to rows and columns of the Hamiltonian.

#### **Return type**

list

### states\_with\_label(label: str) → List[Union[int, str]]

Return a dict of all states with a label matching a given regular expression (regex) pattern. The dictionary will be consist of keys which are string labels applied to states with the label\_states() function, and values which are the corresponding integer values of the node on the graph. For more information on using regex patterns see this guide <https://docs.python.org/3/howto/regex.html#regex-howto>.

#### **Parameters**

**label** (*string*) – Regular expression pattern to match labels to. All labels matching the string will be returned in the keys of the dictionary.

#### Returns

List of all labels of states in the sensor which match the provided regex pattern.

#### **Return type**

list

Raises

ValueError – If label is not a regular expression string.

### **Examples**

```
>>> s = rq.Sensor(3)
>>> s.add_coupling((0,1), detuning=1, rabi_freqency=1, label="hi mom")
>>> s.add_coupling((1,2), detuning=2, rabi_requency=2)
>>> s.label_states({0:"g", 1:"e1", 2:"e2"})
>>> print(s.states_with_label("e[12]"))
['e1', 'e2']
```

#### unzip\_parameters (zip\_label, verbose=True)

Remove a set of zipped parameters from the internal zipped\_parameters list.

If an element of the internal \_zipped\_parameters array matches ALL labels provided, removes it from the internal zipped\_parameters method. If no such element is in \_zipped\_parameters, does nothing.

### Parameters

**zip\_label** (*str*) - The string label corresponding the key to be deleted in the \_zipped\_parameters attribute.

#### Notes

**Note:** This function should always be used rather than modifying the \_zipped\_parameters attribute directly.

### **Examples**

```
>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)
>>> s.add_coupling(states=(0,1), detuning=det, rabi_frequency=1, label=
    "probe")
>>> s.add_coupling(states=(1,2), detuning=det, rabi_frequency=1)
>>> s.zip_parameters("probe_detuning", "(1,2)_detuning", zip_label="demo1")
>>> print(s._zipped_parameters) #NOT modifying directly
>>> s.unzip_parameters("demo1")
>>> print(s._zipped_parameters) #NOT modifying directly
{'demo1': ['(1,2)_detuning', 'probe_detuning']}
{}
```

If the labels provided are not a match, a message is printed and nothing is altered.

```
>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)
>>> s.add_coupling(states=(0,1), detuning=det, rabi_frequency=1, label=
    "probe")
>>> s.add_coupling(states=(1,2), detuning=det, rabi_frequency=1)
>>> s.zip_parameters("probe_detuning", "(1,2)_detuning")
>>> print(s._zipped_parameters) #NOT modifying directly
>>> s.unzip_parameters('blip_0')
>>> print(s._zipped_parameters) #NOT modifying directly
{'zip_0': ['(1,2)_detuning', 'probe_detuning']}
No label matching blip_0, no action taken
{'zip_0': ['(1,2)_detuning', 'probe_detuning']}
```

**variable\_parameters** (*apply\_mesh: bool* = *False*)  $\rightarrow$  List[Tuple[Tuple[Union[int, str], Union[int, str]], str, ndarray]]

Property to retrieve the values of parameters that were stored on the graph as arrays.

#### Returns

A list of tuples corresponding to the parameters of the systems that are variable (i.e. stored as an array). They are ordered according to states, then according to variable name. Tuple entries of the list take the form (states, param\_name, value)

```
Return type
```

list of tuples

### **Examples**

```
>>> s = rq.Sensor(3)
>>> vals = np.linspace(-1,2,3)
>>> s.add_coupling(states=(1,2), rabi_frequency=vals, detuning=1)
>>> s.add_coupling(states=(0,1), rabi_frequency=vals, detuning=vals)
>>> for states, key, value in s.variable_parameters():
... print(f"{states}: {key}={value}")
(0, 1): detuning=[-1. 0.5 2. ]
(0, 1): rabi_frequency=[-1. 0.5 2. ]
(1, 2): rabi_frequency=[-1. 0.5 2. ]
```

The order is important; in the unzipped case, it will sort as though all state labels were cast to strings, meaning integers will always be treated as first.

```
>>> s = rq.Sensor([None, 'e1', 'e2'])
>>> det1 = np.linspace(-1, 1, 3)
>>> det2 = np.linspace(-1, 1, 5)
>>> blue = {"states":(0,'e1'), "rabi_frequency":1, "detuning":det1}
>>> red = {"states":('e1','e2'), "rabi_frequency":3, "detuning":det2}
>>> s.add_couplings(blue, red)
>>> for states, key, value in s.variable_parameters():
... print(f"{states}: {key}={value}")
>>> print(f"Axis Labels: {s.axis_labels()}")
('g', 1): detuning=[-1. 0. 1.]
(1, 2): detuning=[-1. -0.5 0. 0.5 1. ]
Axis Labels: ["('g',1)_detuning", '(1,2)_detuning']
```

zip\_parameters (\*parameters: str, zip\_label: Optional[str] = None)

Define 2 scannable parameters as "zipped" so they are scanned in parallel.

Zipped parameters will share an axis when quantities relevant to the equations of motion, such as the gamma\_matrix and hamiltonian are generated. Note that calling this function does not affect internal quanties directly, but adds their labels together in the internal self.\_zipped\_parameters dict, and they are zipped at calculation time for hamiltonian and decoherence\_matrix.

#### **Parameters**

**parameters** (*str*) - Parameter labels to scan together. Parameter labels are strings of the form "<coupling\_label>\_<parameter\_name>", such as "(0, 1)\_detuning". Must be at least 2 labels to zip. Note that couplings are specified in the *add\_coupling()* function. If unspecified in this function, the pair of states in the coupling cast to a string will be used.

### zip\_label

[optional, str] String label shorthand for the zipped parameters. The label for the axis of these parameters in *axis\_labels()*. Does not affect functionality of the Sensor. If unspecified, the label used will be "zip\_" + <number>.

#### Raises

- **ValueError** If fewer than 2 labels are provided.
- ValueError If any of the 2 labels are the same.
- ValueError If any elements of labels are not labels of couplings in the sensor.
- ValueError If any of the parameters specified by labels are already zipped.
- **ValueError** If any of the parameters specified are not list-like.
- **ValueError** If all list-like parameters are not the same length.

### Notes

**Note:** This function should be called last after all Sensor couplings and dephasings have been added. Changing a coupling that has already been zipped removes it from the self.zipped\_parameters list.

**Note:** Modifying the Sensor.zipped\_parameters attribute directly can break some functionality and should be avoided. Use this function or *unzip\_parameters ()* instead.

**Note:** When defining the zip strings for states labelled with strings, be sure to additional ' or " characters on either side of the labels, as demonstrated in the second example below.

## **Examples**

Make sure to add the appropriate additional string markings when the states are strings.

# 6.1.7 rydiqule.sensor\_solution

Bunch-like object use to store aspects of a solution when calling rydiule.solve() Adds essential keys with "None" entries

### Classes

| Solution(**kwargs) | Manual implementation of a bunch object which fuc-         |
|--------------------|--|
|                    | tions as a dictionary with the ability to access elements. |

### rydiqule.sensor\_solution.Solution

class rydiqule.sensor\_solution.Solution(\*\*kwargs)

Bases: dict

Manual implementation of a bunch object which fuctions as a dictionary with the ability to access elements.

For now, little additional funcitonality exists on top of this, but some may be added in the future.

\_\_init\_\_(\*\*kwargs)

# Methods

| init(**kwargs)                        |  |
|---------------------------------------|--|
| clear()                               |  |
| сору()                                |  |
| deepcopy()                            |  |
| <pre>fromkeys([value])</pre>          | Create a new dictionary with keys from iterable and values set to value.           |
| get(key[, default])                   | Return the value for key if key is in the dictionary, else default.                |
| get_OD()                              | Calculates the optical depth from the solution.                                    |
| get_phase_shift()                     | Extract the phase shift from a solution.   |
| get_solution_element(idx)             | Return a slice of an n_dimensional matrix of solu-                                 |
|                                       | tions of shape $(,n^2-1)$ , where n is the basis size                              |
|                                       | of the quantum system.   |
| get_susceptibility()                  | Return the atomic susceptibility on the probe tran-<br>sition.                     |
| get_transmission_coef()               | Extract the transmission term from a solution.                                     |
| items()                               |  |
| keys()                                |  |
| pop(k[,d])                            | If the key is not found, return the default if given; otherwise, raise a KeyError. |
| popitem()                             | Remove and return a (key, value) pair as a 2-tuple.                                |
| rho_ij(i, j)                          | Gets the i,j element(s) of the density matrix solu-                                |
|                                       | tions.   |
| <pre>setdefault(key[, default])</pre> | Insert key with a value of default if key is not in the                            |
|                                       | dictionary.  |
| update([E,]**F)                       | If E is present and has a .keys() method, then does:                               |
|                                       | for k in E: $D[k] = E[k]$ If E is present and lacks a                              |
|                                       | .keys() method, then does: for k, v in E: $D[k] = v$                               |
|                                       | In either case, this is followed by: for k in F: $D[k] = F[k]$                     |
| values()                              |  |

### Attributes

| beam_area       | Cross-sectional area of the probing beam, in square   |
|-----------------|---|
|                 | meters.   |
| cell_length     | Optical path length of the medium, in meters.         |
| eta             | Eta constant from the Cell.                           |
| kappa           | Kappa constant from the Cell.                         |
| probe_freq      | Probing transition frequency, in rad/s.               |
| probe_rabi      | Probe Rabi frequency, in Mrad/s.                      |
| probe_tuple     | Coupling edge corresponding to probing field.         |
| rho             | Solutions returned by the solver.                     |
| couplings       | Dictionary of the couplings.                          |
| axis_labels     | Labels for the axes of scanned parameters.            |
| axis_values     | Value arrays corresponding to each axis.              |
| rq_version      | Version of rydiqule that created the Solution.        |
| dm_basis        | The list of density matrix elements in the order they |
|                 | appear in the solution.                               |
| doppler_classes | Doppler classes used to perform the doppler aver-     |
|                 | age.  |
| t               | Times the solution is returned at, when using the     |
|                 | time solver.  |
| init_cond       | Initial conditions, when using the time solver.       |

#### \_beam\_area: Optional[float]

Cross-sectional area of the probing beam, in square meters. Not generally defined when using a Sensor.

# \_cell\_length: Optional[float]

Optical path length of the medium, in meters. Not generally defined when using a Sensor.

### \_eta: Optional[float]

Eta constant from the Cell. Not generally defined when using a Sensor.

### Туре

float, optional

### \_kappa: Optional[float]

Kappa constant from the Cell. Not generally defined when using a Sensor.

#### Type

float, optional

### \_probe\_freq: Optional[float]

Probing transition frequency, in rad/s. Not generally defined when using a Sensor.

### \_probe\_rabi: Optional[Union[float, ndarray]]

Probe Rabi frequency, in Mrad/s. Not generally defined when using a Sensor.

# \_probe\_tuple: Optional[Tuple[Union[int, str], Union[int, str]]]

Coupling edge corresponding to probing field. Not generally defined when using a Sensor.

### axis\_labels: list[str]

Labels for the axes of scanned parameters. If doppler averaging but not summing, doppler dimensions are prepended.

Type

list of str

### axis\_values: list

Value arrays corresponding to each axis. If doppler averaging but not summing, doppler classes in internal units are added.

Туре

list

#### property beam\_area: float

Cross-sectional area of the probing beam, in square meters. Not generally defined when using a Sensor.

### property cell\_length: float

Optical path length of the medium, in meters. Not generally defined when using a Sensor.

**clear** ()  $\rightarrow$  None. Remove all items from D.

**copy** ( )  $\rightarrow$  a shallow copy of D

### couplings: dict

Dictionary of the couplings.

Туре

dict

### deepcopy()

### dm\_basis: ndarray

The list of density matrix elements in the order they appear in the solution. See Sensor.basis() for details.

Туре

list of str

### doppler\_classes: Optional[ndarray]

Doppler classes used to perform the doppler average. Will be None if doppler averaging was not used.

#### Type

numpy.ndarray, optional

### property eta: float

Eta constant from the Cell. Not generally defined when using a Sensor.

### fromkeys(value=None,/)

Create a new dictionary with keys from iterable and values set to value.

#### get (key, default=None, /)

Return the value for key if key is in the dictionary, else default.

### get\_OD() $\rightarrow$ Union[float, ndarray]

Calculates the optical depth from the solution. This equation comes from Steck's Quantum Optics Notes Eq. 6.74.

Assumes the optically-thin approximation is valid. If a calculated OD for a solution exceeds 1, this approximation is likely invalid.

#### Returns

**OD** – Optical depth of the sample

### **Return type**

float or numpy.ndarray

### Warns

**UserWarning** – If any OD exceeds 1, which indicates the optically-thin approximation is likely invalid.

### **Examples**

```
>>> c = rq.Cell('Rb85', *rq.D2_states('Rb85'), cell_length = 0.01)
>>> c.add_coupling(states=(0,1), rabi_frequency=1, detuning=1)
>>> sols = rq.solve_steady_state(c)
>>> print(sols.rho.shape)
>>> OD = sols.get_OD()
>>> print(OD)
(3,)
29.642013239786518
~/src/Rydiqule/src/rydiqule/sensor_solutions.py:103: UserWarning:
At least one solution has optical depth greater than 1.
Integrated results are likely invalid.
```

### $\texttt{get\_phase\_shift()} \rightarrow \texttt{Union[float, ndarray]}$

Extract the phase shift from a solution.

Assumes the optically-thin approximation is valid.

#### Returns

Probe phase in radians.

#### **Return type**

float or numpy.ndarray

### **Examples**

```
>>> c = rq.Cell('Rb85', *rq.D2_states('Rb85'), cell_length = .00001)
>>> c.add_coupling(states=(0,1), rabi_frequency=1, detuning=1)
>>> sols = rq.solve_steady_state(c)
>>> print(sols.rho.shape)
>>> phase_shift = sols.get_phase_shift()
>>> print(phase_shift)
(3,)
80.52949114644437
```

#### get\_solution\_element (*idx: int*) $\rightarrow$ Union[float, ndarray]

Return a slice of an n\_dimensional matrix of solutions of shape  $(...,n^2-1)$ , where n is the basis size of the quantum system.

### Parameters

idx (int) – Solution index to slice.

### Returns

Slice of solutions corresponding to index idx. For example, if sols has shape  $(..., n^2-1)$ , sol\_slice will have shape (...).

### **Return type**

float or numpy.ndarray

#### Raises

**IndexError** – If idx in not within the shape determined by basis size.

### **Examples**

```
>>> c = rq.Cell('Rb85', *rq.D2_states('Rb85'))
>>> c.add_coupling(states=(0,1), rabi_frequency=1, detuning=1)
>>> sols = rq.solve_steady_state(c)
>>> print(sols.rho.shape)
>>> rho_01_im = sols.get_solution_element(0)
>>> print(rho_01_im)
(3,)
0.0013139903428765695
```

get\_susceptibility() → Union[complex, ndarray]

Return the atomic susceptibility on the probe transition.

Experimental parameters must be defined manually for a Sensor.

#### Returns

Susceptibility of the density matrix solution.

#### Return type

complex or numpy.ndarray

### **Examples**

```
>>> c = rq.Cell('Rb85', *rq.D2_states('Rb85'), cell_length = 0.0001)
>>> c.add_coupling(states=(0,1), rabi_frequency=1, detuning=1)
>>> sols = rq.solve_steady_state(c)
>>> print(sols.rho.shape)
>>> sus = sols.get_susceptibility()
>>> print(sus)
(3,)
(1.9046090082907774e-05+0.0003680924230367812j)
```

### $\texttt{get\_transmission\_coef()} \rightarrow \texttt{Union[float, ndarray]}$

Extract the transmission term from a solution.

Assumes the optically-thin approximation is valid.

### Returns

Numerical value of the probe absorption in fractional units (P\_out/P\_in).

### **Return type**

float or numpy.ndarray

# **Examples**

```
>>> c = rq.Cell('Rb85', *rq.D2_states('Rb85'), cell_length = 0.0001)
>>> c.add_coupling(states=(0,1), rabi_frequency=0.1, detuning=0)
>>> sols = rq.solve_steady_state(c)
>>> print(sols.rho.shape)
>>> t = sols.get_transmission_coef()
>>> print(t)
(3,)
0.7425903081191148
```

### init\_cond: ndarray

Initial conditions, when using the time solver. Undefined otherwise.

Type

numpy.ndarray

**items** ()  $\rightarrow$  a set-like object providing a view on D's items

```
property kappa: float
```

Kappa constant from the Cell. Not generally defined when using a Sensor.

keys ( )  $\rightarrow$  a set-like object providing a view on D's keys

```
pop (k[, d]) \rightarrow v, remove specified key and return the corresponding value.
```

If the key is not found, return the default if given; otherwise, raise a KeyError.

### popitem()

Remove and return a (key, value) pair as a 2-tuple.

Pairs are returned in LIFO (last-in, first-out) order. Raises KeyError if the dict is empty.

### property probe\_freq: float

Probing transition frequency, in rad/s. Not generally defined when using a Sensor.

```
property probe_rabi: Union[complex, ndarray]
```

Probe Rabi frequency, in Mrad/s. Not generally defined when using a Sensor.

### property probe\_tuple: Tuple[Union[int, str], Union[int, str]]

Coupling edge corresponding to probing field. Not generally defined when using a Sensor.

### rho: ndarray

Solutions returned by the solver.

Туре

numpy.ndarray

**rho\_ij** (*i*: *int*, *j*: *int*)  $\rightarrow$  Union[complex, ndarray]

Gets the i,j element(s) of the density matrix solutions.

See get\_rho\_ij() for details.

#### Parameters

- i (int) density matrix element i
- j (*int*) density matrix element j

#### Returns

[i, j] elment(s) of the density matrix

### **Return type**

complex or numpy.ndarray

### rq\_version: str

Version of rydiqule that created the Solution.

Type

# setdefault (key, default=None, /)

Insert key with a value of default if key is not in the dictionary.

Return the value for key if key is in the dictionary, else default.

### t: ndarray

Times the solution is returned at, when using the time solver. Undefined otherwise.

Туре

numpy.ndarray

**update** ([E], \*\*F)  $\rightarrow$  None. Update D from dict/iterable E and F.

If E is present and has a .keys() method, then does: for k in E: D[k] = E[k] If E is present and lacks a .keys() method, then does: for k, v in E: D[k] = v In either case, this is followed by: for k in F: D[k] = F[k]

**values** ()  $\rightarrow$  an object providing a view on D's values

# 6.1.8 rydiqule.sensor\_utils

Utilities used by the Sensor classes.

# **Functions**

| <pre>draw_diagram(sensor[, include_dephasing])</pre>        | Draw a matplotlib plot that shows the energy level di-   |
|---|--|
|   | agram, couplings, and dephasing paths.                   |
| <pre>generate_eom(hamiltonian, gamma_matrix[,])</pre>       | Create the optical bloch equations for a hamiltonian and |
|   | decoherence matrix using the Lindblad master equa-       |
|   | tion.  |
| <pre>get_basis_transform(basis_size)</pre>                  | Function that defines the basis transformation matrix u  |
|   | and its inverse u_i, between the real and complex basis. |
| get_rho_ij(sols, i, j)                                      | For a given density matrix solution, retrieve a specific |
|   | element of the density matrix.                           |
| get_rho_populations(sols)                                   | For a given density matrix solution, return the diagonal |
|   | populations.   |
| <pre>make_real(equations, constant[, ground_removed])</pre> | Converts equations of motion from complex basis to       |
|   | real basis.  |
| remove_ground(equations)                                    | Remove the ground state from the equations of motion     |
|   | using population conservation.                           |
| <pre>scale_dipole(dipole)</pre>                             | Scale a dipole matrix from units of a0*e to Mrad/s       |
|   | when multiplied by a field in V/m.                       |

#### rydiqule.sensor\_utils.draw\_diagram

rydiqule.sensor\_utils.draw\_diagram(sensor: Sensor, include\_dephasing: bool = True)  $\rightarrow$  LD

Draw a matplotlib plot that shows the energy level diagram, couplings, and dephasing paths.

To show the plot, call plt.show(). If in a jupyter notebook, this is handled automatically.

Diagram has horizontal lines for the energy levels (spacing not to scale). Integer labels refer to the internal indexing for each state. If sensor is of type Cell, will also add text labels to each state of the quantum numbers.

Solid arrows between states are couplings defined with a non-zero Rabi frequency. Dashed arrows between states are couplings defined with a dipole moment.

Wiggly arrows between states denote a dephasing pathway. Opacity represents strength of dephasing relative to the largest specified dephasing, where fully opaque is the largest dephasing.

Parameters

- **sensor** (*Sensor*) Sensor object to diagram.
- **include\_dephasing** (*bool*, *optional*) Whether to plot dephasing paths. Default is True.

#### Returns

Diagram handle

#### **Return type**

leveldiagram.LD

### rydiqule.sensor\_utils.generate\_eom

```
rydiqule.sensor_utils.generate_eom (hamiltonian: ndarray, gamma_matrix: ndarray, remove_ground_state: bool = True, real_eom: bool = True)

→ Tuple[ndarray, ndarray]
```

Create the optical bloch equations for a hamiltonian and decoherence matrix using the Lindblad master equation.

### **Parameters**

- hamiltonian (*numpy.ndarray*) Complex array representing the Hamiltonian matrix of the system, the matrix should be of shape (\*1, n, n), where n is the basis size and l is the shape of the stack of hamiltonians. For example, if the hamiltonian varies in 2 parameters l might be (10, 10).
- gamma\_matrix (*numpy.ndarray*) Complex array representing the decoherence matrix of the system, the matrix should be of size (n, n), where n is the basis size.
- **remove\_ground\_state** (*bool*, *optional*) Remove the ground state from the equations of motion using population conservation. Setting to False is intended for internal use only and is not officially supported. See *remove\_ground()* for details.
- **real\_eom** (*bool*, *optional*) Transform the equations of motion from the complex basis to the real basis. Setting to False is intended for internal use only and is not officially supported Seee make\_real() for details.

#### Returns

- equations (*numpy.ndarray*) The array representing the Optical Bloch Equations (OBEs) of the system. The shape will be (\*1, n^2-1, n^2-1) if remove\_ground\_state is True and (\*1, n^2, n^2) otherwise. The datatype will be np.float64 if real\_eom is True and np.complex128 otherwise.
- const (*numpy.ndarray*) Array of which defines the constant term in the linear OBEs. The shape will be (\*1, n^2-1) if remove\_ground\_state is True and (\*1, n^2) otherwise. The datatype will be np.float64 if real\_eom is True and np. complex128 otherwise.

#### Raises

**ValueError** – If the shapes of gamma\_matrix and hamiltonian are not matching: or not square in the last 2 dimensions

### Examples

```
>>> ham = np.diag([1,-1])
>>> gamma = np.array([[.1, 0],[.1,0]])
>>> print(ham.shape)
>>> eom, const = rq.generate_eom(ham, gamma)
>>> print(eom)
>>> print(const.shape)
(2, 2)
[[-0.1 2. 0.]
[-2. -0.1 0.]
[ 0. 0. -0.1]]
(3,)
```

This also works with a "stack" of multiple hamiltonians:

```
>>> ham_base = np.diag([1,-1])
>>> ham_full = np.array([ham_base for _ in range(10)])
>>> gamma = np.array([[.1, 0],[.1,0]])
>>> print(ham_full.shape)
>>> eom, const = rq.generate_eom(ham_full, gamma)
>>> print(const.shape)
>>> print(const.shape)
(10, 2, 2)
(10, 3, 3)
(10, 3)
```

### rydiqule.sensor\_utils.get\_basis\_transform

```
rydiqule.sensor_utils.get_basis_transform (basis_size: int) → Tuple[ndarray, ndarray]
```

Function that defines the basis transformation matrix u and its inverse u\_i, between the real and complex basis.

This matrix u implements that the  $\rho[j,i] \to Re(\rho[j,i])$  and  $\rho[i,j] \to Im(\rho[j,i])$ .

The transformation is not quite unitary, due to the asymmetry of the factors of 1/2.

```
Parameters
basis_size (int) – Size of the basis to generate transformations for.
```

Returns

- **u** (*numpy.ndarray*) Forward transformation matrix.
- **u\_inv** (*numpy.ndarray*) Inverse transformation matrix.

#### Raises

ValueError - If basis\_size does not match current basis.

### rydiqule.sensor\_utils.get\_rho\_ij

```
rydiqule.sensor_utils.get_rho_ij (sols: Union[ndarray, Solution], i: int, j: int) → Union[complex, ndarray]
```

For a given density matrix solution, retrieve a specific element of the density matrix.

Assumes the ground state of the solution is eliminated (as per *remove\_ground()*), and assumes Rydiqule's nominal state ordering of the Density Vector (per *make\_real()*).

### Parameters

- **sols** (numpy.ndarray or *Solution*) Solutions to extract the matrix element for. Can be either the solution object returned by the solve or an N-D array representing density vectors, with ground state removed, and written in the totally real equations.
- i (int) density matrix index i
- j (*int*) density matrix index j

#### Returns

Array of rho\_ij values. Will be of type float when i=j. Will be of type complex128 when i!=j.

#### **Return type**

numpy.ndarray

### **Examples**

```
>>> sols = np.arange(180).reshape((4,5,3,3))
>>> print(sols.shape)
>>> rho_01 = rq.get_rho_ij(sols, 0,1)
>>> print(rho_01.shape)
>>> print(rho_01[0,0])
(4, 5, 3, 3)
(4, 5, 3)
[0.-1.j 3.-4.j 6.-7.j]
```

### rydiqule.sensor\_utils.get\_rho\_populations

```
rydiqule.sensor_utils.get_rho_populations (sols: Union[ndarray, Solution]) \rightarrow ndarray
```

For a given density matrix solution, return the diagonal populations.

Note that rydiqule's convention for removing the ground state forces population conservation, ie the sum of these populations will be 1.

#### Parameters

**sols** (numpy.ndarray or *Solution*) – Solutions to extract the matrix element for. Can be either the solution object returned by the solve or an N-D array representing density vectors, with ground state removed, and written in the totally real equations.

#### Returns

Populations of the density matrices. Will have same shape as input solutions, with the last dimension reduced to the basis size.

#### **Return type**

numpy.ndarray

#### rydiqule.sensor\_utils.make\_real

```
rydiqule.sensor_utils.make_real (equations: ndarray, constant: ndarray, ground_removed: bool = 
True) → Tuple[ndarray, ndarray]
```

Converts equations of motion from complex basis to real basis.

Changes the density vector equation for  $p_{ij}$  into the  $Re[p_{ij}]$  equation and changing the density vector equation for  $p_{ji}$  into the equation for  $Im[p_{ij}]$ .

#### Parameters

- equations (numpy.ndarray) Complex equations of motion.
- **constant** (*numpy.ndarray*) RHS of the equations of motion.
- ground\_removed (bool, optional) Indicates if equations has had the ground state removed. Default is True.

### Returns

- real\_eqns (numpy.ndarray) EOMs in real basis.
- real\_const (numpy.ndarray) RHS of EOMs in real basis.

### rydiqule.sensor\_utils.remove\_ground

rydiqule.sensor\_utils.**remove\_ground**(*equations: ndarray*) → Tuple[ndarray, ndarray]

Remove the ground state from the equations of motion using population conservation.

Population conservation enforces

$$\rho_{(0,0)} = 1 - \sum_{i=1}^{n-1} \rho_{(i,i)}$$

We use this equation to remove the EOM for rho\_00 and enforce population conservation in the steady state.

### Parameters

**equations** (numpy.ndarray) – array of shape  $(n^2, n^2)$  representing the equations of motion of the system, where n is the number of basis states.

#### Returns

The modified equations of shape (n^2-1, n^2-1)

#### **Return type**

numpy.ndarray

### rydiqule.sensor\_utils.scale\_dipole

```
rydiqule.sensor_utils.scale_dipole(dipole: Union[float, ndarray]) \rightarrow Union[float, ndarray]
```

Scale a dipole matrix from units of a0\*e to Mrad/s when multiplied by a field in V/m.

### Parameters

**dipole** (*float* or *numpy.ndarray*) – Array of dipole moments in units of a0\*e. These are the default units used by ARC.

### Returns

Scaled array in units of (Mrad/s)/(V/m)

#### **Return type**

numpy.ndarray

# 6.1.9 rydiqule.slicing

### Modules

| rydiqule.slicing.slicing | A handful of tools that solvers use to interface with slic- |
|--------------------------|---|
|                          | ing matrix stacks   |

### rydiqule.slicing.slicing

A handful of tools that solvers use to interface with slicing matrix stacks

# Functions

| <pre>compute_grid(stack_shape, n_slices)</pre>          | Calculate the bin edges to break a given stack shape into |
|---|---|
|   | at least a certain number of pieces                       |
| <pre>get_slice_num(n, stack_shape, doppler_shape,</pre> | Estimates the memory required for the desired steady      |
| )   | state solve.  |
| <pre>get_slice_num_t(n, stack_shape,[, debug])</pre>    | Estimates the memory required for the desired time        |
|   | solve.  |
| <pre>matrix_slice(*matrices[, edges, n_slices])</pre>   | Generator that returns parts of a stack of matrices.      |
| <pre>memory_size(shape, item_size)</pre>                | Calculate the memory size, in bytes of an array with the  |
|   | given size and shape.                                     |

### rydiqule.slicing.slicing.compute\_grid

rydiqule.slicing.slicing.compute\_grid(stack\_shape: Tuple[int, ...], n\_slices: int)

Calculate the bin edges to break a given stack shape into at least a certain number of pieces

Works by iterating first over a number of slices per axis (N=1,2,3), then over each in the stack shape, splitting the axis into N slices, and comparing the total number of slices to the number specified. In a sense, the algorithm factors a number greater than or equal to n\_slices, then breaks the stack along each axis according to this factorization. If the axis lengths do not break evenly into the appropriate number of pieces, the bin edges are truncated to an integer. This means that the slices are not guaranteed to be  $(1/n_slices)$ , but they will be close enough for most cases.

### Parameters

- **stack\_shape** (*tuple of int*) The shape of the stack to be sliced. Does not include Hamiltonian or matrix equation dimensions, so for a hamiltonian stack of shape (\*1, n, n), stack\_shape will be \*1.
- **n\_slices** (*int*) The number of slices into which to break the hamiltonian. Lower bound on the number of slices there will actually be.

#### Returns

The list of bin edges axis by axis. Can be passed to  $matrix\_slice()$  as the edges argument.

#### **Return type**

list(np.ndarray)

# **Examples**

```
>>> stack_shape=(10,10)
>>> print(compute_grid(stack_shape, 4))
[array([ 0, 5, 10]), array([ 0, 5, 10])]
>>> print(compute_grid(stack_shape, 6))
[array([ 0, 3, 6, 10]), array([ 0, 5, 10])]
```

# rydiqule.slicing.slicing.get\_slice\_num

```
rydiqule.slicing.slicing.get_slice_num (n: int, stack_shape: Tuple[int, ...], doppler_shape:

Tuple[int, ...], sum_doppler: bool, weight_doppler: bool,

n_slices: Optional[int] = None, debug: bool = False) →

Tuple[int, Tuple[int, ...]]
```

Estimates the memory required for the desired steady state solve.

Estimates are fairly accurate, but not guaranteed. Goal is to err on allowing edge case solves to proceed.

### Parameters

- n (int) Size of the system basis
- **stack\_shape** (*tuple of int*) Tuple of sizes for the hamiltonian stack to be solved
- **doppler\_shape** (*tuple of int*) Tuple of sizes for the doppler axes. Pass an empty tuple if no doppler averaging.
- **sum\_doppler** (bool) Whether solution will be summing the doppler average
- weight\_doppler (bool) Whether the solution will apply weights to the doppler averaging
- **n\_slices** (*int*, *default=1*) Manually override the minimum number of hamiltonian slices to use.
- **debug** (*bool*, *default=False*) Print debug information about the memory calculations.

### Returns

- n\_ham\_slices (int) Number of slices to use when solving the stacked hamiltonian
- **out\_sol\_shape** (*tuple of int*) Shape of the resulting solution for this calculation.

### Raises

- **MemoryError** If there isn't enough memory to solve the system:
- MemoryError If sum\_doppler=False and full solution does not fit in memory.:

### rydiqule.slicing.slicing.get\_slice\_num\_t

```
rydiqule.slicing.slicing.get_slice_num_t (n: int, stack_shape: Tuple[int, ...], doppler_shape:

Tuple[int, ...], time_points: int, sum_doppler: bool,

weight_doppler: bool, n_slices: Optional[int], debug:

bool = False) → Tuple[int, Tuple[int, ...]]
```

Estimates the memory required for the desired time solve.

Note that the time solver used (scipy.solve\_ivp) is an adaptive solver, so the internal number of time steps used is problem dependent and not controlled by the requested number of time points. Generally, the number of points is proportional to the highest frequency in the problem and the length of the time to solve. To estimate a lower bound on the memory needed to time solve, we use a fudge factor of 4 on the requested time points. This is unlikely to be accurate even in a general case.

### Parameters

- **n** (*int*) Size of the system basis
- **stack\_shape** (*tuple of int*) Tuple of sizes for the hamiltonian stack to be solved
- **doppler\_shape** (*tuple of int*) Tuple of sizes for the doppler axes. Pass an empty tuple if no doppler averaging.

- time\_points (*int*) Number of time steps requested from the time solver. This sets the output solution shape. An internal fudge factor of 4 is applied for memory estimation purposes.
- **sum\_doppler** (bool) Whether solution will be summing the doppler average
- weight\_doppler (bool) Whether the solution will apply weights to the doppler averaging
- **n\_slices** (*int*, *default=1*) Manually override the minimum number of hamiltonian slices to use.
- **debug** (*bool*, *default=False*) Print debug information about the memory calculations.

### Returns

- n\_ham\_slices (int) Number of slices to use when solving the stacked hamiltonian
- out\_sol\_shape (tuple of int) Shape of the resulting solution for this calculation.

### Raises

MemoryError - If sum\_doppler=False and full solution does not fit in memory.:

#### Warns

UserWarning (If there is unlikely to be enough memory to solve the system.)

### rydiqule.slicing.slicing.matrix\_slice

rydiqule.slicing.slicing.matrix\_slice (\*matrices: ndarray, edges: Optional[Iterable] = None, n\_slices: Optional[int] = None) → Iterator[Tuple[Tuple[slice, ...], Unpack[Tuple[np.ndarray, ...]]]]

Generator that returns parts of a stack of matrices.

Given a stack of n by n matrices, produces a generator which returns the given matrices in the specified number of smaller stacks. For example, given a stack of matrices of shape (10, 10, 4, 4) with 4 slices, generates 4 stacks of shape (5, 4, 4). Due to the nature of the slicing, the number of slices might be slightly greater that the number specified. Output matrices will be broadcastable by numpy's broadcasting rules. Input arrays are interpreted as a stack, with the last 2 dimensions staying intact.

#### Parameters

- matrices (*np.ndarray*) matrix stacks to be sliced. All matrices must be of shapes that can be broadcast by numpy's broadcasting rules, with the additional restriction that all matrices must have the same number of dimensions, even if some dimensions are of size 1. For example, matrices of sizes (10, 1, 4, 4) and (1, 20, 4, 4) can be sliced together.
- edges (*iterable*, *optional*) The values along each axis that define the edges of bins on an n-dimensional grid. For example, to slice a grid of hamiltonians with stack\_shape (10, 10) into 4 pieces, edges could be defined as [0, 5, 10] for each of the 2 stack axes.
- **n\_slices** (*int*, *optional*) The number of slices into which to break the matrix stack. Ignored if the edges parameter is not None. Must be specified as an integer value if edges is None, ignored otherwise. Defaults to None.

#### Yields

- tuple of slices slicing for each corresponding matrix
- *numpy.ndarray* Slice of hamiltonian stack

### **Examples**

```
>>> import numpy as np
>>> import rydiqule as rq
>>> M1 = np.ones((1,20,4,4))
>>> M2 = np.ones((20,1,4,4))
>>> M3 = np.ones((20,20,4,4))
```

```
>>> axis0_edges = np.array([0,10,20])
>>> axis1_edges = np.array([0,10,20])
```

>>> for idx,m1,m2, m3 in rq.matrix\_slice(M1, M2, M3, edges=[axis0\_edges, axis1\_ →edges]):
>>> print(m1.shape, m2.shape, m3.shape)

(1, 10, 4, 4) (10, 1, 4, 4) (10, 10, 4, 4) (1, 10, 4, 4) (10, 1, 4, 4) (10, 10, 4, 4) (1, 10, 4, 4) (10, 1, 4, 4) (10, 1, 4, 4) (10, 1, 4, 4) (10, 10, 4) (10, 10, 4)

# rydiqule.slicing.slicing.memory\_size

rydiqule.slicing.slicing.memory\_size (*shape: Tuple[int, ...], item\_size: int*) → int

Calculate the memory size, in bytes of an array with the given size and shape. Does not calculate the actual array, just theoretical size since this function is intended to be used before attempting allocate an array that is too large.

### Parameters

- **shape** (*list-like*) Shape of the array in question.
- item\_size (*int*) Size of an array element in bytes.

### Returns

Expected memory size of array in bytes

# Return type int

# 6.1.10 rydiqule.solvers

Steady-state solvers of the Optical Bloch Equations.

# **Functions**

| <pre>solve_steady_state(sensor[, doppler,])</pre> | Finds the steady state solution for a system character- |
|---|---|
|   | ized by a sensor.                                       |
| <pre>steady_state_solve_stack(eom, const)</pre>   | Helper function which returns the solution to the given |
|   | equations of motion                                     |

### rydiqule.solvers.solve\_steady\_state

rydiqule.solvers.solve\_steady\_state(sensor: Sensor, doppler: bool = False,

 $doppler\_mesh\_method: Optional[Union[UniformMethod, IsoPopMethod, SplitMethod, DirectMethod]] = None,$  $sum\_doppler: bool = True, weight\_doppler: bool = True,$  $n\_slices: Optional[int] = None) \rightarrow Solution$ 

Finds the steady state solution for a system characterized by a sensor.

If insuffucent system memory is available to solve the system in a single call, system is broken into "slices" of manageable memory footprint which are solved indivudually. This slicing behavior does not affect the result. Can be performed with or without doppler averging.

#### Parameters

- **sensor** (*Sensor*) The sensor for which the solution will be calculated.
- **doppler** (*bool*, *optional*) Whether to calculate the solution for a doppler-broadened gas. If True, only uses dopper brodening defined by kvec parameters for couplings in the sensoe, so setting this True without kvec definitions will have no effect. Default is False.
- (dict (doppler\_mesh\_method) If not None, should be a dictionary of meshing parameters to be passed to doppler\_classes(). See doppler\_classes() for more information on supported methods and arguments. If None, uses the default doppler meshing. Default is `None.
- **optional)** If not None, should be a dictionary of meshing parameters to be passed to *doppler\_classes()*. See *doppler\_classes()* for more information on supported methods and arguments. If None, uses the default doppler meshing. Default is `None.
- **sum\_doppler** (bool) Whether to average over doppler classes after the solve is complete. Setting to False will not perform the sum, allowing viewing of the weighted results of the solve for each doppler class. In this case, an axis will be prepended to the solution for each axis along which doppler broadening is computed. Ignored if doppler=False. Default is True.
- weight\_doppler (bool) Whether to apply weights to doppler solution to perform averaging. If False, will not apply weights or perform a doppler\_average, regardless of the value of sum\_doppler. Changing from default intended only for internal use. Ignored if doppler=False or sum\_doppler=False. Default is True.
- **n\_slices** (*int or None, optional*) How many sets of equations to break the full equations into. The actual number of slices will be the largest between this value and the minumum number of slices to solve the system without a memory error. If None, uses the minimum number of slices to solve the system without a memory error. Detailed information about slicing behavior can be found in *matrix\_slice()*. Default is None.

### Notes

**Note:** If decoherence values are not sufficiently populated in the sensor, the resulting equations may be singular, resulting in an error in numpy.linalg. This error is not caught for flexibility, but is likely the culprit for numpy.linalg errors encountered in steady-state solves.

**Note:** The solution produced by this function will be expressed using rydiqule's convention of converting a density matrix into the real basis and removing the ground state to improve numerical stability.

Note: If the sensor contains couplings with time\_dependence, this solver will add those couplings at their t = 0 value to the steady-state hamiltonian to solve.

#### Returns

A bunch-type object contining information about the solution. Presently, only attribute "rho" is added to the solution, corresponding to the density matrix of the steady state solution. Will include solutions to all parameter value combinations if array-like parameters are specified.

Return type

Solution

### **Examples**

A basic solve for a 3-level system would have a "density matrix" solution of size 8 (3^2-1)

```
>>> s = rq.Sensor(3)
>>> s.add_coupling((0,1), detuning = 1, rabi_freqency=1)
>>> s.add_coupling((1,2), detuning = 2, rabi_freqency=2)
>>> s.add_transit_broadening(0.1)
>>> sol = rq.solve_steady_state(s)
>>> print(type(sol))
>>> print(type(sol.rho))
>>> print(sol.rho.shape)
<class 'rydiqule.sensor_solution.Solution'>
<class 'numpy.ndarray'>
(8,)
```

Defining an array-like parameter will automatically calculate the density matrix solution for every value. Here we use 11 values, resulting in 11 density matrices. The axis\_labels attribute of the solution can clarify which axes are which.

```
>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)
>>> s.add_coupling((0,1), detuning = det, rabi_freqency=1)
>>> s.add_coupling((1,2), detuning = 2, rabi_freqency=2)
>>> s.add_transit_broadening(0.1)
>>> sol = rq.solve_steady_state(s)
>>> print(sol.rho.shape)
>>> print(sol.axis_labels)
(11, 8)
['(0,1)_detuning']
```

```
>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)
>>> s.add_coupling((0,1), detuning = det, rabi_freqency=1)
>>> s.add_coupling((1,2), detuning = det, rabi_freqency=2)
>>> s.add_transit_broadening(0.1)
>>> sol = rq.solve_steady_state(s)
>>> print(sol.rho.shape)
>>> print(sol.axis_labels)
(11, 11, 8)
['(0,1)_detuning', '(1,2)_detuning']
```

If the solve uses doppler broadening, but not averaging for doppler is specified, there will be a solution axis corresponding to doppler classes.

>>> s = rq.Sensor(3)
>>> det = np.linspace(-1,1,11)

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```
>>> s.add_coupling((0,1), detuning = det, rabi_freqency=1)
>>> s.add_coupling((1,2), detuning = 2, rabi_freqency=2, kvec=(1,0,0))
>>> s.add_transit_broadening(0.1)
>>> sol = rq.solve_steady_state(s, doppler=True, sum_doppler=False)
>>> print(sol.rho.shape)
>>> print(sol.axis_labels)
(561, 11, 8)
['doppler_0', '(0,1)_detuning']
```

### rydiqule.solvers.steady\_state\_solve\_stack

```
rydiqule.solvers.steady_state_solve_stack (eom: ndarray, const: ndarray) → ndarray
```

Helper function which returns the solution to the given equations of motion

Solves an equation of the form  $\dot{x} = Ax + b$ , or a set of such equations arranged into stacks. Essentially just wraps numpy.linalg.solve(), but included as its own function for modularity if another solver is found to be worth investigating.

#### **Parameters**

- **eom** (*numpy.ndarray*) An square array of shape (\*1, n, n) representing the differential equations to be solved. The matrix (or matrices) A in the above formula.
- **const** (*numpy.ndarray*) An array or shape (\*1, n) representing the constant in the matrix form of the differential equation. The constant b in the above formula. Stack shape \*1 must be consistent with that in the eom argument

#### Returns

A 1xn array representing the steady-state solution of the differential equation

#### **Return type**

numpy.ndarray

# 6.1.11 rydiqule.stack\_solvers

### **Modules**

```
rydiqule.stack_solvers.cyrk_solver
rydiqule.stack_solvers.
nbkode_solver
rydiqule.stack_solvers.nbrk_solver
rydiqule.stack_solvers.scipy_solver
```

# rydiqule.stack\_solvers.cyrk\_solver

### **Functions**

| <pre>cyrk_solve(eoms_base, const_base,)</pre> | Solve a set of Optical Bloch Equations (OBEs)        |
|---|--|
|   | with rydiqule's time solving convention using CyRK's |
|   | cyrk_ode.  |

#### rydiqule.stack\_solvers.cyrk\_solver.cyrk\_solve

```
rydiqule.stack_solvers.cyrk_solver.cyrk_solve (eoms_base: ndarray, const_base: ndarray,
eom_time_r: ndarray, const_r: ndarray,
eom_time_i: ndarray, const_i: ndarray,
time_inputs: Sequence[Callable[[float],
complex]], t_eval: ndarray, init_cond:
ndarray, **kwargs) → ndarray
```

Solve a set of Optical Bloch Equations (OBEs) with rydiqule's time solving convention using CyRK's cyrk\_ode.

Uses matrix components of the equations of motion provided by the methods of a Sensor(). Designed to be used as a wrapped function within  $solve_time()$ . Builds and solves equations of motion according rydiqule's time solving conventions. Sets up and solves dx/dt = A(t)x + b(t)

#### **Parameters**

- **eoms\_base** (*numpy.ndarray*) The matrix of shape (\*1, n, n) representing the non time-varying portion of the matrix A in the equations of motion.
- **const\_base** (*numpy.ndarray*) The array of shape (\*1, n) representing the non time-varying portion of the vector b in the equations of motion.
- eoms\_time\_r (numpy.ndarraynumpy) The matrix of shape (n\_t, \*1, n, n) representing the real time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **const\_r** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the real time-varying portion of the vector b, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **eoms\_time\_i** (*numpy.ndarray*) The matrix of shape (n\_t, \*1, n, n) representing the imaginary time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- **const\_i** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the imaginary time-varying portion of the vector b, where n\_t is the length of time\_in-puts. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- time\_inputs (list (callable)) List of callable functions of length n\_t. The functions should take a single floating point as an input representing the time in microseconds, and return a real or complex floating point value represent an electric field in V/m at that time. Return type of each function must be the same for all inputs t.
- **t\_eval** (*numpy.ndarray*) Array of times to sample the integration at. This array must have dtype of float64.
- init\_cond (*numpy.ndarray*) Matrix of shape (\*1, n) representing the initial state of the system.
- **\*\*kwargs** (*dict*:) Additional keyword arguments passed to the cyrk\_ode.

#### Returns

The matrix solution of shape  $(*l, n, n_t)$  representing the density matrix of the system at each time t.

#### **Return type**

numpy.ndarray

#### Raises

**OverflowError** – If system size exceeds cyrk backend limit of 65535 equations.: If we

see this error a lot, consider getting CyRK project to increase it by changing type of  $y\_size$  from unisgned short.

### rydiqule.stack\_solvers.nbkode\_solver

### **Functions**

| nbkode_solve(eoms_base, const_base,) | Solve a set of Optical Bloch Equations (OBEs) using    |
|--------------------------------------|--|
|                                      | rydiqule's time solving convention using numbakit-ode. |

#### rydiqule.stack\_solvers.nbkode\_solver.nbkode\_solve

rydiqule.stack\_solvers.nbkode\_solver.**nbkode\_solve** (eoms\_base: ndarray, const\_base: ndarray, eom\_time\_r: ndarray, const\_r: ndarray, eom\_time\_i: ndarray, const\_i: ndarray, time\_inputs: Sequence[Callable[[float], complex]], t\_eval: ndarray, init\_cond: ndarray, \*\*kwargs) → ndarray

Solve a set of Optical Bloch Equations (OBEs) using rydiqule's time solving convention using numbakit-ode.

Uses matrix components of the equations of motion provided by the methods of a Sensor(). Designed to be used as a wrapped function within  $solve_time()$ . Builds and solves equations of motion according rydiqule's time solving conventions. Sets up and solves dx/dt = A(t)x + b(t)

### Parameters

- **eoms\_base** (*numpy.ndarray*) The matrix of shape (\*1, n, n) representing the non time-varying portion of the matrix A in the equations of motion.
- **const** (*numpy.ndarray*) The array of shape (\*1, n) representing the non time-varying portion of the vector b in the equations of motion.
- eoms\_time\_r (numpy.ndarraynumpy) The matrix of shape (n\_t, \*1, n, n) representing the real time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **const\_r** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the real time-varying portion of the vector b, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **eoms\_time\_i** (*numpy.ndarray*) The matrix of shape (n\_t, \*1, n, n) representing the imaginary time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- **const\_i** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the imaginary time-varying portion of the vector b, where n\_t is the length of time\_in-puts. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- time\_inputs (list (callable)) List of callable functions of length n\_t. The functions should take a single floating point as an input representing the time in microseconds, and return a real or complex floating point value represent an electric field in V/m at that time. Return type of each function must be the same for all inputs t.
- **t\_eval** (*numpy.ndarray*) Array of times to sample the integration at. This array must have dtype of float64.

- init\_cond ((numpy.ndarray)) Matrix of shape (\*1, n) representing the initial state of the system.
- **\*\*kwargs** (*dict*) Additional keyword arguments passed to the nbkode solver constructor.

### Returns

The matrix solution of shape  $(*l, n, n_t)$  representing the density matrix of the system at each time t.

### **Return type**

numpy.ndarray

### rydiqule.stack\_solvers.nbrk\_solver

### Functions

| nbrk_solve(eoms_base, const_base,) | Solve a set of Optical Bloch Equations (OBEs)        |
|------------------------------------|--|
|                                    | with rydiqule's time solving convention using CyRK's |
|                                    | nbrk_ode.  |
|                                    |  |

### rydiqule.stack\_solvers.nbrk\_solver.nbrk\_solve

rydiqule.stack\_solvers.nbrk\_solver.**nbrk\_solve** (eoms\_base: ndarray, const\_base: ndarray, eom\_time\_r: ndarray, const\_r: ndarray, eom\_time\_i: ndarray, const\_i: ndarray, time\_inputs: Sequence[Callable[[float], complex]], t\_eval: ndarray, init\_cond: ndarray, \*\*kwargs) → ndarray

Solve a set of Optical Bloch Equations (OBEs) with rydiqule's time solving convention using CyRK's  $nbrk_ode$ .

Uses matrix components of the equations of motion provided by the methods of a Sensor(). Designed to be used as a wrapped function within  $solve_time()$ . Builds and solves equations of motion according rydiqule's time solving conventions. Sets up and solves dx/dt = A(t)x + b(t)

### Parameters

- **eoms\_base** (*numpy.ndarray*) The matrix of shape (\*1, n, n) representing the non time-varying portion of the matrix A in the equations of motion.
- **const** (*numpy.ndarray*) The array of shape (\*1, n) representing the non time-varying portion of the vector b in the equations of motion.
- eoms\_time\_r (numpy.ndarraynumpy) The matrix of shape (n\_t, \*l, n, n) representing the real time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **const\_r** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the real time-varying portion of the vector b, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **eoms\_time\_i** (*numpy.ndarray*) The matrix of shape (n\_t, \*l, n, n) representing the imaginary time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- **const\_i** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the imaginary time-varying portion of the vector b, where n\_t is the length of time\_in-puts. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- time\_inputs (list (callable)) List of callable functions of length n\_t. The functions should take a single floating point as an input representing the time in microseconds, and return a real or complex floating point value represent an electric field in V/m at that time. Return type of each function must be the same for all inputs t.
- t\_eval (*numpy.ndarray*) Array of times to sample the integration at. This array must have dtype of float64.
- init\_cond ((numpy.ndarray)) Matrix of shape (\*1, n) representing the initial state of the system.
- **\*\*kwargs** (*dict*) Additional keyword arguments passed to nbrk\_ode.

#### Returns

The matrix solution of shape  $(*l, n, n_t)$  representing the density matrix of the system at each time t.

### **Return type**

numpy.ndarray

### rydiqule.stack\_solvers.scipy\_solver

## **Functions**

| <pre>scipy_solve(eoms_base, const, eom_time_r,)</pre> | Solve a set of Optical Bloch Equations (OBEs)         |
|---|---|
|   | with rydiqule's time solving convention using scipy's |
|   | solve_ivp.  |

#### rydiqule.stack\_solvers.scipy\_solver.scipy\_solve

rydiqule.stack\_solvers.scipy\_solver.scipy\_solve (eoms\_base: ndarray, const: ndarray, eom\_time\_r: ndarray, const\_r: ndarray, eom\_time\_i: ndarray, const\_i: ndarray, time\_inputs: Sequence[Callable[[float], complex]], t\_eval: ndarray, init\_cond: ndarray, eqns: Literal['loop', 'comp'] = 'loop', \*\*kwargs) → ndarray

Solve a set of Optical Bloch Equations (OBEs) with rydiqule's time solving convention using scipy's solve\_ivp.

Uses matrix components of the equations of motion provided by the methods of a Sensor (). Designed to be used as a wrapped function within  $solve_time()$ . Builds and solves equations of motion according rydiqule's time solving conventions. Sets up and solves dx/dt = A(t)x + b(t)

#### Parameters

- **eoms\_base** (*numpy.ndarray*) The matrix of shape (\*1, n, n) representing the non time-varying portion of the matrix A in the equations of motion.
- **const** (*numpy.ndarray*) The array of shape (\*1, n) representing the non time-varying portion of the vector b in the equations of motion.
- eoms\_time\_r (*numpy.ndarraynumpy*) The matrix of shape (n\_t, \*1, n, n) representing the real time-varying portion of the matrix A, where n\_t is the length of

time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.

- **const\_r** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the real time-varying portion of the vector b, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the real part of the ith entry in time\_inputs.
- **eoms\_time\_i** (*numpy.ndarray*) The matrix of shape (n\_t, \*1, n, n) representing the imaginary time-varying portion of the matrix A, where n\_t is the length of time\_inputs. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- **const\_i** (*numpy.nd\_array*) The matrix of shape (n\_t, \*1, n) representing the imaginary time-varying portion of the vector b, where n\_t is the length of time\_in-puts. The ith slice along the first axis should be multiplied by the imaginary part of the ith entry in time\_inputs.
- time\_inputs (list (callable)) List of callable functions of length n\_t. The functions should take a single floating point as an input representing the time in microseconds, and return a real or complex floating point value represent an electric field in V/m at that time.
- **t\_eval** (*numpy.ndarray*) Array of times to sample the integration at.
- init\_cond ((numpy.ndarray)) Matrix of shape (\*1, n) representing the initial state of the system.
- eqns ({"loop", "comp"}) Function used of generating equations of motion. One of "loop" or "comp", corresponding to defining time-dependent equations of motion as a loop over time-dependent components or with a list comprehension. List comprehensions are preferred for longer solves and loops are preferred for shorter solves.
- **\*\*kwargs** (*dict*) Additional keyword arguments passed to the nbkode solver constructor.

### Returns

The matrix solution of shape  $(*l, n, n_t)$  representing the density matrix of the system at each time t.

#### **Return type**

numpy.ndarray

## 6.1.12 rydiqule.timesolvers

Solvers for time domain analysis with an arbitrary RF field

### **Functions**

| <pre>generate_eom_time(hamiltonians_time)</pre>     | Generates the Optical Bloch Equations for just the rf  |
|---|--|
|   | terms.   |
| <pre>solve_eom_stack(eoms_base, const,)</pre>       | Solve a stack of equations of motion with shape $(*1,$ |
|   | n, n) in the time domain.                              |
| <pre>solve_time(sensor, end_time, num_pts[,])</pre> | Solves the response of the optical sensor in the time  |
|   | domain given the its time-dependent inputs             |

### rydiqule.timesolvers.generate\_eom\_time

```
\label{eq:complexity} rydiqule.timesolvers.generate_eom_time(\textit{hamiltonians\_time: ndarray}) \rightarrow Tuple[ndarray, ndarray]
```

Generates the Optical Bloch Equations for just the rf terms. Uses the convention of the hamiltonian\_rf return of the get\_time\_hamiltonian function. The equations of motion returned are assumed to be used in conjunction with an electric field.

### Parameters

**hamiltonians\_time** (numpy.ndarray) – A matrix of shape (basis\_size, basis\_size), where the off-diagonal terms (i,j) are the dipole matrix elements in e a\_b of the transition coupling state i to state j.

### Returns

- **numpy.ndarray** (*Part of the Optical Bloch Equations corresponding to time\_dependent couplings.*) To produce equations to solve, these values must be multiplied by an electric field in V/m.
- **numpy.ndarray** (*Constant term of the time-dependent portion of the equations*) of motion. Same units as the equations themselves.

### rydiqule.timesolvers.solve\_eom\_stack

rydiqule.timesolvers.**solve\_eom\_stack** (*eoms\_base: ndarray, const: ndarray, eom\_time\_r: ndarray, const\_r: ndarray, eom\_time\_i: ndarray, const\_i: ndarray, time\_inputs: List[Callable[[float], complex]], t\_eval: ndarray, init\_cond: ndarray, solver, \*\*kwargs*) → ndarray

Solve a stack of equations of motion with shape (\*1, n, n) in the time domain.

Companion function to *solve\_time()*, but can be invoked on its for equations already formatted.

### Parameters

- **eoms\_base** (*numpy.ndarray*) Array of shape (\*1, n, n) representing the part of equations of motion of the system which do not respond to external fields.
- **const** (*numpy.ndarray*) **constant** term of shape (n,) added in differential equations. Typically generated by generate\_eom().
- eoms\_time\_r (list[numpy.ndarray]) list of arrays of shape (basis\_size^2-1, basis\_size^2-1) representing the parts of the OBEs with a real-valued time-dependence. In the solver, this array will be multiplied by a time-dependent rabi frequency. Typically a matrix of mostly zeros, with non-zero terms corresponding to a particular time-dependent coupling
- **const\_r** (*numpy.ndarray*) Constant term of shape (n,) added in a real time-dependent portion of differential equations. Typically generated by gener-ate\_eom\_time().
- **eoms\_time\_i** (*numpy.ndarray*) list of arrays of shape (basis\_size^2-1, basis\_size^2-1) representing the parts of the OBEs with an imaginary-valued time-dependence. In the solver, this array will be multiplied by a time-dependent rabi frequency.
- **const\_i** (*numpy.ndarray*) constant term of shape (n,) added in an imaginary time-dependent portion of differential equations. Typically generated by generate\_eom\_time().
- **t\_eval** (*numpy.ndarray*)-1-D array of times, in microseconds, at which to evaluate the solution. Does not affect evaluations in the solve.

- **time\_inputs** (*list[function float->float]*) List of functions which represent the rabi frequency of a field as a function of time. list length should be identical to the length of obes\_time. In the solver, the *i* th time input will be evaluated at time *t* and multiplied by the *i* th entry of obes\_time.
- **tuple(float)** (*time\_range*) Pair of values represent the start and end time, in microseconds, of the simulation.
- **init\_cond** (numpy.ndarray or None, optional) Density matrix representing the initial state of the system. If specified, the shape should be either (n) in the case of a single initial condition for all parameter values, or should be of shape (\*1, n) matching the output shape of a steady state solve if the initial condition may be different for different combinations of parameters. If None, will solve the problem in the steady state with all time-dependent fields "off" and use the solution as the initial condition for the time behavior. Other possible manual options might include a matrix populated by zeros representing the entire population in the ground state. Defaults to None.

### Returns

Flattened solution array corresponding to time points.

#### **Return type**

numpy.ndarray

### rydiqule.timesolvers.solve\_time

```
rydiqule.timesolvers.solve_time (sensor: Sensor, end_time: float, num_pts: int, init_cond:

Optional[ndarray] = None, doppler: bool = False,

doppler_mesh_method: Optional[Union[UniformMethod,

IsoPopMethod, SplitMethod, DirectMethod]] = None,

sum_doppler: bool = True, weight_doppler: bool = True, n_slices:

Optional[int] = None, solver: Union[Callable, Literal['scipy',

'nbkode', 'cyrk', 'nbrk']] = 'scipy', **kwargs) → Solution
```

Solves the response of the optical sensor in the time domain given the its time-dependent inputs

If insuffucent system memory is available to solve the system all at once, system is broken into "slices" of manageable memory footprint which are solved indivudually. This slicing behavior does not affect the result. All couplings that include a "time\_dependence" argument will be solved in the time domain.

A number of solver backends work with rydiqule, but the default "scipy" ivp solver is the is recommended backend in almost all cases, as it is the most fully-featured and documented. Advanced users have the ablity to define their own solver backends by creating a function that follows the call signature for rydiqule timesolver backends. Additional arguments to the solver backend can be supplied with \*\*kwargs.

### Parameters

- **sensor** (*Sensor*) The sensor object representing the atomic/laser arrangement of the system.
- end\_time (float) Amount of time, in microseconds, for which to simulate the system
- **num\_pts** (*int*) The number of points along the range (0, end\_time) for which the solution is evaluated. This does not affect the number of function evaluations during the solve, rather the spacing of the points in the reported solution.
- **init\_cond** (numpy.ndarray or None, optional) Density matrix representing the initial state of the system. If specified, the shape should be either (n) in the case of a single initial condition for all parameter values, or should be of shape (\*1, n) matching the output shape of a steady state solve if the initial condition may be different for different combinations of parameters. If None, will solve the problem in the steady state with all time-dependent fields at their t = 0 value and use the solution as the initial condition. Other possible manual options might include a matrix populated by zeros representing the entire population in the ground state. Defaults to None.

- **doppler** (*bool*, *optional*) Whether to account for doppler shift among moving atoms in the gas. If True, the solver will implicitly define a velocity distribution for particles in the cell, solve the problem for each velocity class, and return a weighted average of the results. Note that solving in this manner carries a substantial performance penalty, as each doppler velocity class is solved as its own problem. If solved with doppler, only axis specified by a "kvec"' argument in one of the sensor couplings will be average over. The time solver currently supports doppler averaging in any number of spatial dimensions, up to the limit of 3 imposed by the macroscopic physical world. Defaults to `False.
- **doppler\_mesh\_method** (*dict*, *optional*) Dictionary that controls the doppler meshing method. Exact details of this are found in the documentation of doppler\_classes(). Ignored if doppler=False. Default is None.
- **sum\_doppler** (*bool*, *optional*) Whether to average over doppler classes after the solve is complete. Setting to false will not perform the sum, allowing viewing of the weighted results of the solve for each doppler class. Ignored if doppler=False. Default is True.
- weight\_doppler (bool) Whether to apply weights to doppler solution to perform averaging. If False, will not apply weights or perform a doppler\_average, regardless of the value of sum\_doppler. Changing from default intended only for internal use. Ignored if doppler=False or sum\_doppler=False. Default is True.
- **n\_slices** (*int* or *None*, *optional*) How many sets of equations to break the full equations into. The actual number of slices will be the largest between this value and the minumum number of slices to solve the system without a memory error. If None, solver uses the minimum number of slices required to solve without a memory Error. Defaults to None.
- **solver** ({"scipy", "nbkode", "cyrk", "nbrk"} or callable) The backend solver used to solve the ivp generated by the sensor. All string values correspond to backend solvers built in to rydiqule. Valid string values are:
  - "scipy": Solves equations with scipy.integrate.solve\_ivp(). The default, most stable, and well-supported option.
  - "nbkode": Solves equations with the jit-compiled Runge-Kutta-45 solver in numbakit-ode. May be faster for very long time solves with many timesteps.
  - "cyrk": Solves jit-compiled equations with a cython compiled RK solver from CyRK. Due to some jit compilation, only faster for moderate length problems (ie problems with a moderate number of required time steps).
  - "nbrk": Solves equations with the jit-compiled RK solver from CyRK. Due to extensive jit compilation, only faster for very long solves (ie problems with a large number of required time steps).

Additionally, can be specified with a callable that matches rydiqule's time-solver convention, enabling using a custom solver backend.

**Note:** Unless otherwise noted, backends other than scipy are considered experimental. Issues with their use are considered features not fully implemented rather than bugs.

• **\*\*kwargs** (Additional keyword arguments passed to the backend solver.)-See documentation of the relevant solver (i.e. scipy.integrate. solve\_ivp()) for details and supported arguments.

#### Returns

A bunch-type object contining information about the solution. Timesolver specific attributes are t and init\_cond, corresponding respectively to the times at which the solution is sampled and the initial conditions used for the solve.

Return type Solution

CHAPTER SEVEN

# **DEVELOPER DOCUMENTATION**

These pages contain documentation relevant to the development of rydiqule. If you with to work on the source code of rydiqule, details relating to policies and tools can be found here.

## 7.1 Unit Tests

Rydiqule comes bundled with a suite of unit tests that confirm basic functionality of the various components and checks for robustness to erroneous or unexpected arguments. We strive to follow the testing methodology and practices employed by numpy. We agree with the stipulation made there, that

"Long experience has shown that by far the best time to write the tests is before you write or change the code - this is test-driven development"

## 7.1.1 pytest

Rydiqule takes advantage of the pytest testing framework to run unit and integration tests of the code base. The full test suite is run from the project base directory with the command

```
pytest tests/
```

This command will run all tests in the tests/ subdirectory. These tests cover a wide range of functionality as well as a number of representative integrations that demonstrate how the code can be used to generate end results.

### Marks

The tests are marked based on the type of test that is being performed, and pytest can be told to only run certain tests. For example, this command will only run tests relating to the steady state solving functionality:

```
pytest -m steady_state
```

You can also exclude a specific group of tests. For example, this command will exlcude tests marked as slow.

```
pytest -m "not slow"
```

Marks specifications can be combined using standard boolean keywords as well. The following will run all the time tests that are not slow.

pytest -m "time and not slow"

The available marks can be listed using pytest --markers. The markers we use are

| Marker       | Description   |
|--------------|---|
| slow         | Marks a test as taking a long time to run   |
| high_memory  | Marks a test needing a lot of RAM   |
| steady_state | Marks a test as using the steady-state solver   |
| time         | Marks a test as using the time solver   |
| doppler      | Marks a test that incorporates Doppler averaging.   |
| experiments  | Marks a test that represents a full experiment.   |
| util         | Marks a test of the ancillary utilties.   |
| structure    | Marks a test of the definition of the atomic system.  |
| dev          | Used to temporarily mark a single test that is being developed so it can run independently. |

Table 7.1: Markers

## Coverage

If you install the pytest-cov plugin, you can check code coverage of the tests by modifying the command to read.

```
pytest --cov=rydiqule tests/
```

### **Durations**

If you want to see which tests take the longest to complete, you can use the --durations=n flag to give the n longest time tests:

pytest --durations=3 tests/

Settings the durations flag to 0 will cause pytest to report the time taken for all tests run.

# 7.2 Type Hinting

Rydiqule employs the optional type hinting capabilities of python. These type annotations are not checked or enforced at runtime by python itself. Rather, they provide hints to fellow programmers and users about the types of function arguments, return types, and class variables.

We use the mypy static type checking library to read these hints and catch type errors within the code base. To run this check locally, install the mypy python package and run the following command from the package root directory.

туру

This command will automatically read configuration options set in the mypy.ini file. Further optional flags can be passed to the command to override or add optional behaviors. Initial run of the mypy takes some time, however subsequent runs take advantage of local caching to increase analysis speed. Using the mypy daemon mode can further increase analysis speed if necessary.

An html report of the mypy coverage can be generated using the following command.

mypy --html-report .mypy\_report

This command will store the html pages in the specified directory .mypy\_report. Note that this command takes a long time to run every time, as it cannot use the cache.

# 7.3 Linting

We use the ruff linting package to help enforce code style and consistent readability. It can be run locally from the project root folder by calling the command ruff check .. It pulls options for running the command from the ruff.toml configuration file.

If you intend to work on the rydiqule codebase, it is good practice to incorporate automatic linting within your code editor.

Linting can be disabled for a single line by using the # noqa tag at the end of the line. Specific error codes can be specified by # noqa: E501, which ignores only line length errors.

# 7.4 Building the Documentation

The Rydiqule documentation can be built locally from the source repository using sphinx. To do so, you will need to install the sphinx and sphinx-rtd-theme packages.

## 7.4.1 html

An html webpage version of the documentation formatted in the read-the-docs style can be made by running the following command from the docs/ subdirectory.

make html

The output will be located in the docs/build/html/ subdirectory. The home page is index.html. The html documentation has the best formatting by default and is the easiest to use.

## 7.4.2 latexpdf

A pdf version of the documentation can be built using

```
make latexpdf
```

The output will be located in docs/build/latex and is called rydiqule.pdf. Note that building the pdf requires perl and a functioning latex installation with the latexmk package. You will also require the GNU FreeFont collection. On Windows, these can be installed manually at the system level or via the MikTeX package gnu-freefont. This build also requires a great many other latex packages in addition to latexmk. It is easiest to install these packages on the fly as needed, if your latex distribution supports that.

Given the difficulty of building this type of documentation, we attempt to include an updated pdf with each relase. It is locaed in the docsbuildlatex directory.

## 7.4.3 epub

There is also the ability to build the documentation in the EPUB format, if desired.



%matplotlib inline

%load\_ext autoreload
%autoreload 2

import numpy as np
import matplotlib.pyplot as plt
from scipy.spatial.transform import Rotation as R

import rydiqule as rq
from rydiqule.sensor\_utils import get\_rho\_ij

# **3-PHOTON RYDBERG EIT**

We demonstrate three photon coherent excitations using the system studied in Taicharoen et. al. PRA 063427 (2019). This is a rubidium vapor with a  $5S_{1/2} \rightarrow 5P_{3/2} \rightarrow 5D_{5/2} \rightarrow 28F_{7/2}$  excitation pathway, with corresponding optical fields of 780 nm, 776 nm, and 1260 nm. These fields are labelled probe, dressing, and coupling, respectively.

Here we demonstrate using rydiqule to solve this system under three conditions:

- 1) Cold atoms
- 2) Warm atoms, colinear optical beams
- 3) Warm atoms, doppler-free angles

Because there are three optical fields, the basic coherent feature observed, on resonance, is expected to the absorptive (rather than transmissive like EIT). Going to warm atoms, this feature broadens significantly, and other coherent features can arise at non-zero detunings of the fields. Going to a Doppler-free excitation in warm atoms, we find that a transmissive feature is observed on resonance. This feature is significantly narrower than those observed in the colinear case.

## 8.1 Doppler-free, 3 photon excitation

With all three fields resonant, we expect to see Electromagnetically-Induced-Absorption (EIA) instead of EIT.

```
detunings = np.linspace(-20,20,41)
probe = {'states':(0,1), 'rabi_frequency':2*np.pi*0.1,'detuning':2*np.pi*0}
dress = {'states':(1,2), 'rabi_frequency':2*np.pi*2, 'detuning':2*np.pi*detunings}
basis_size = 4
gam = np.zeros((basis_size,basis_size),dtype=np.float64)
gam[1,0] = 6
gam[2,1] = 0.66
gam[3,2] = 10e-3
gamma_matrix = 2*np.pi*gam
sensor = rq.Sensor(basis_size)
sensor.set_gamma_matrix(gamma_matrix)
```

```
dress['detuning'] = 2*np.pi*0
sensor.add_couplings(dress)
sols = rq.solve_steady_state(sensor)
```

```
fig, ax = plt.subplots()
ax.plot(detunings, get_rho_ij(sols.rho,1,0).imag)
ax.set_xlabel("Coupling Laser Detuning (MHz)")
ax.set_ylabel(r"Im($\rho_{10}$)")
```



## 8.2 Colinear 3-photon Excitation with Doppler Averaging

We can take our three fields and configure them in the (+,-,-) configuration of Taicharoen (2019). We will need to do Doppler averaging along the colinear axis to get the result. The magnitude of a field's kvector is defined such that it is the magnitude of the Doppler shift associated with the most probable speed of the Maxwell-Boltzmann distribution  $(v_P \equiv \sqrt{2k_BT/m})$ , where  $k_B$  is Boltzmann's constant, T is the gas temperature, and m is the atomic mass). It should have units of Mrad/s like all other specifies quantities.

The following reproduces Figure 2b from Taicharoen et. al. PRA 063427 (2019). Note that having all fields resonant results in an EIA feature, but it now much broader than the Doppler-free case above. If the dressing field is detuning, EIT features are observed.

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```
sensor.add_decoherence((2,1), 2*np.pi*0.66)
sensor.add_decoherence((3,2), 2*np.pi*10e-3)
```

sensor.add\_couplings(probe,couple)

```
dress['detuning'] = 2*np.pi*0
sensor.add_couplings(dress)
sols0 = rq.solve_steady_state(sensor,doppler=True)
```

```
dress['detuning'] = 2*np.pi*20
sensor.add_couplings(dress)
solsp20 = rq.solve_steady_state(sensor,doppler=True)
```

```
dress['detuning'] = -2*np.pi*20
sensor.add_couplings(dress)
solsm20 = rq.solve_steady_state(sensor,doppler=True)
```

```
fig, ax = plt.subplots(figsize=(8,6))
ax.plot(detunings, get_rho_ij(sols0.rho,1,0).imag, label="$\\Delta_d= 0$ MHz")
ax.plot(detunings, get_rho_ij(solsp20.rho,1,0).imag, label="$\\Delta_d= +20$ MHz")
ax.plot(detunings, get_rho_ij(solsm20.rho,1,0).imag, label="$\\Delta_d= -20$ MHz")
ax.set_xlabel("Coupling Laser Detuning (MHz)")
ax.set_ylabel(r"Im($\rho_{10}$)")
ax.legend()
```

```
<matplotlib.legend.Legend at 0x21861422640>
```



# 8.3 Doppler-Free Angles

We can take the same co-propagating system, and instead change the angles of the three beams such that  $k_p + k_d + k_c \approx 0$ .

We now need to do Doppler averaging in two orthogonal dimensions. Rydiqule automatically detects how many non-zero dimensions are present in the field kvectors and averages over the appropriate number of spatial dimensions.

```
detunings = np.linspace(-20, 20, 21)
kp = 2*np.pi/780e-3*np.array([1,0,0])
kd = 2*np.pi/776e-3*np.array([-1,0,0])
kc = 2*np.pi/1260e-3*np.array([-1,0,0])
vP = 242.387 \# m/s
# rotate to doppler free angles
rd = R.from_euler('z', -35.964, degrees=True)
rc = R.from_euler('z', 72.4718, degrees=True)
kdDF = rd.apply(kd)
kcDF = rc.apply(kc)
probe = {'states':(0,1), 'rabi_frequency':2*np.pi*10, 'kvec':vP*kp, 'detuning':0}
dress = {'states':(1,2), 'rabi_frequency':2*np.pi*25, 'kvec':vP*kdDF}
couple = {'states':(2,3), 'rabi_frequency':2*np.pi*18, 'detuning':2*np.

→pi*detunings, 'kvec':vP*kcDF}

n = 4
sensor = rq.Sensor(n)
sensor.add_decoherence((1,0), 2*np.pi*6)
sensor.add_decoherence((2,1), 2*np.pi*0.66)
sensor.add_decoherence((3,2), 2*np.pi*10e-3)
sensor.add_couplings(probe,couple)
```

print('Residual fractional kvector sum due to round-off errors')
print((kp+kdDF+kcDF)/np.sqrt(kp.dot(kp)))

```
Residual fractional kvector sum due to round-off errors [-1.41309045e-08 -4.99652620e-07 0.00000000e+00]
```

```
dress['detuning'] = 2*np.pi*0
sensor.add_couplings(dress)
solsODF = rq.solve_steady_state(sensor,doppler=True)
```

```
fig, ax = plt.subplots()
ax.plot(detunings, get_rho_ij(sols0DF.rho,1,0).imag)
ax.set_xlabel("Coupling Laser Detuning (MHz)")
ax.set_ylabel(r"Im($\rho_{10}$)")
```

```
Text(0, 0.5, 'Im($\rho_{10}$)')
```



We observe a significantly narrower feature than in the collinear case, and it is now EIT instead of EIA.

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# **CALCULATING SNR**

Rydiqule contains the function rydiqule.get\_snr() function that will take a Sensor or Cell and calculate the expected SNR for one axis of the solve. Below we demonstrate the use of this function to numerically confirm the analytic results of Meyer et. al. PRA 104, 043103 (2021) Eqs. 12 & 13:

$$\begin{split} \Omega_p^{(\text{opt})} &\approx \sqrt{\Gamma(2\gamma + \Gamma_r + \Gamma_c)} \\ \Omega_c^{(\text{opt})} &\approx \sqrt{2} \Omega_p^{(\text{opt})} \end{split}$$

These show the optical probe and coupling Rabi frequencies for resolving Rydberg state shifts in a 2-color Rydberg EIT measurement, in an optically-thin with no Doppler broadening.

```
import numpy as np
import rydiqule as rq
import matplotlib.pyplot as plt
%load_ext autoreload
%autoreload 2
```

The autoreload extension **is** already loaded. To reload it, use: %reload\_ext autoreload

Manually define representative kappa and eta constants for a Rb85 sensor. These are necessary to find the SNR in experimental units and must be supplied by the user when calculating using a Sensor. If using a Cell, these constants are automatically calculated and do not need to be passed to get\_snr.

The definition of these numerical factors is found in Meyer et. al. PRA 104, 043103 (2021) Eqs. 5 & 7.

$$\kappa = \frac{\omega_p n \mu^2}{2c\epsilon_0 \hbar}$$
$$\eta = \sqrt{\frac{\omega \mu^2}{2c\epsilon_0 \hbar A}}$$

kappa = 28974.8787
eta = 0.00135882
probe\_freq = 2.416e9

# 9.1 1D Optimum

Here we demonstrate calculating the SNR for resolving a phase shift due to an RF Rydberg coupling vs probe Rabi frequency. We have chosen a far-detuned RF coupling to ensure Stark shifts are linear.

```
##Set up a simplified Rb Sensor
basis_size = 4
Rb_sensor = rq.Sensor(basis_size)
Rb_sensor.set_experiment_values(probe_freq = probe_freq,probe_tuple = (0,1),
                              kappa = kappa, eta = eta, cell_length = .000001)
red_rabi = np.linspace(0.1,6,100)
blue_rabi = np.linspace(0.1,4,101)
blue_rabi_1 = 1
my_step = np.array([1, 1.1])
probe = {'states': (0,1), 'rabi_frequency': red_rabi, 'detuning': 0, 'label':

→ 'probe' }

couple = {'states': (1,2), 'rabi_frequency':blue_rabi_1, 'detuning': 0, 'label':
\leftrightarrow 'couple'}
rf = {'states': (2,3), 'rabi_frequency': my_step, 'detuning':20, 'label': 'rf'}
Rb_sensor.add_couplings(probe,couple, rf)
#simplify the gamma matrix to match predictions
gam = np.zeros((basis_size, basis_size))
gam[2, 0] = 0.1
gam[3, 0] = 0.01
gam[1, 0] = 6.0
Rb_sensor.set_gamma_matrix(gam)
```

To calculate the SNR vs a specific parameter, that parameter must be list-like with at least two elements. So calculated vs RF Rabi frequency, we have specified two Rabi frequency values very close to each other to measure the local linear sensitivity. More values can be added to this list to see if sensitivity changes for larger changes in the parameter, which indicates nonlinear response.

```
rq.draw_diagram(Rb_sensor)
```

```
<rydiqule.energy_diagram.ED at 0x1da48b14b20>
```



We call get\_snr with the Sensor to calculate with, the label of the swept parameter to calculate SNR against, the tuple of the probing transition to get measurable parameters from, which quadrature the probing field is being detected in, and the kappa and eta numerical factors.

Using Sensor.axis\_labels() we can identify which axis rydique has used for the swept parameters. This allows us to correctly index out the appropriate solutions for analysis. In particular, we need to index the sensitivity axis to get the sensitivity at the second RF Rabi frequency in the list (relative to the first).

```
#print the axis labels
Rb_sensor.axis_labels()
```

```
['probe_rabi_frequency', 'rf_rabi_frequency']
```

```
snrs_final = snrs[:,1]
param_mesh_final=np.array(param_mesh)[:,:,1]
```

We can plot the SNR as a function of probe rabi frequency. The vertical line represents the analytic optimum value for the probe Rabi frequency.

```
fix, ax = plt.subplots(figsize = (2,2))
ax.plot(param_mesh_final[0], snrs_final)
ax.set_xlabel("Red Rabi Freq [Mrad/s]")
ax.set_ylabel("SNR in 1 sec.")
ax.set_title('RF LO = 1 Mrad/s \n RF Signal = 0.1 Mrad/s')
ax.axvline(blue_rabi_1/np.sqrt(2),0,3, color = 'k')
```

```
<matplotlib.lines.Line2D at 0x1da4ba95fd0>
```



# 9.2 2D Optimum - Fnd Optimized $\Omega_p$ and $\Omega_c$ for best SNR

We can also calculate the SNR versus many different axis. Here we calculate versus both the probe and coupling Rabi frequencies.

Rb\_sensor.add\_couplings(probe,couple, rf)

```
Rb_sensor.axis_labels()
```

['probe\_rabi\_frequency', 'couple\_rabi\_frequency', 'rf\_rabi\_frequency']

```
snrs_final = snrs[:,:,1]
param_mesh_final=np.array(param_mesh)[:,:,:,1]
```

```
Predicted optimum probe Rabi frequency: 0.775 Mrad/s
Predicted optimum coupling Rabi frequency: 1.095 Mrad/s
```

We plot the SNR versus both Rabi frequencies using a contour plot. We have overlaid the analytic predictions for the optimal SNR. Compare Figure 5(a) of Meyer et. al.

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# **RF HETERODYNE WITH DOPPLER EXAMPLE**

This notebook demonstrates two-tone detection using a Rydberg sensor in the time domain with Doppler averaging. An RF local oscillator (LO) and signal (sig) are imposed on the Rydberg sensor. This is useful for RF phase detection, and can be used to linearize the detection, as shown below. The main results of this example showing how different levels of Doppler averaging affect the beat signal size of the sensor.

```
import datetime
from numba import vectorize, float64
##***LAST UPDATE***##
now = datetime.datetime.now()
print(now)
```

```
2023-10-11 10:52:41.251854
```

# 10.1 Imports

```
import numpy as np
import rydiqule as rq
import matplotlib.pyplot as plt
```

```
%load_ext autoreload
%autoreload 2
```

# **10.2 Define the Sensors**

```
state1 = RbSensor_time.states_list()[2]
state2 = RbSensor_time.states_list()[3]
print("1: ", state1)
print("2: ", state1)
dipoleMoment = RbSensor_time.atom.getDipoleMatrixElement(*state1,*state2, 0)
field = rf_rabi/rq.scale_dipole(dipoleMoment)
print("applied field, V/m:", field) #V/m
print("Rabi frequency, Mrad/s: ", field*rq.scale_dipole(dipoleMoment))
```

```
1: [150, 2, 2.5, 0.5]
2: [150, 2, 2.5, 0.5]
applied field, V/m: 0.08558532725336343
Rabi frequency, Mrad/s: 100.0
```

```
def sig_and_LO( delta, beta):
    def fun(t):
        return (1+beta*np.sin(delta*t))
    return fun
```

658.5872652398125

## 10.3 Observe a heterodyne beat between the Signal and LO.

## 10.3.1 Define the RF LO and signal

```
sampleNum = 200
endTime = 10 # microseconds
rf = sig_and_LO( 5, .1)
```

## 10.3.2 Solve without Doppler averaging

Observe the beat between signal and LO fields.

RbSensor\_time.add\_couplings(blue\_laser, red\_laser, rf)

```
%%time
#Solve Without any doppler broadening
time_sol = rq.solve_time(RbSensor_time, endTime, sampleNum, atol=1e-6, rtol=1e-6)
```

```
CPU times: total: 172 ms
Wall time: 191 ms
```



C:UsersDavidsrcRydiqulesrcrydiqulesensor\_solution.py:223: UserWarning: At-→least one solution has optical depth greater than 1. Integrated results-→are likely invalid.

warnings.warn(('At least one solution has optical depth '

```
fig, ax = plt.subplots()
ax.plot(time_sol.t, transmission)
ax.set_xlabel("time (us)")
ax.set_ylabel('transmission')
ax.set_title("Doppler-Free Solution")
```

Text(0.5, 1.0, 'Doppler-Free Solution')



## 10.3.3 Solve with Doppler averaging

Doppler averaged results require larger Rabi frequencies to observe similar sized signals.

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```
RbSensor_time.add_couplings(blue_laser, red_laser, rf)
```

```
CPU times: total: 3min 11s
Wall time: 1min 38s
```

```
transmission_doppler = time_sol_doppler.get_transmission_coef()
```

```
fig, ax = plt.subplots()
ax.plot(time_sol_doppler.t, transmission_doppler)
ax.set_xlabel("time (us)")
ax.set_ylabel('transmission')
ax.set_title("Doppler Solution")
```

Text(0.5, 1.0, 'Doppler Solution')



## 10.3.4 Solve with smaller Doppler Width

We can artificially reduce the amount of Doppler broadening. In this case, the default meshing of the velocity classes should be overridden to avoid excessive calculations.

RbSensor\_time.add\_couplings(blue\_laser, red\_laser, rf)

CPU times: total: 1.03 s Wall time: 518 ms

transmission\_doppler\_narrow = time\_sol\_doppler\_narrow.get\_transmission\_coef()

C:UsersDavidsrcRydiqulesrcrydiqulesensor\_solution.py:223: UserWarning: At→ →least one solution has optical depth greater than 1. Integrated results→ →are likely invalid. warnings.warn(('At least one solution has optical depth '

```
fig, ax = plt.subplots()
ax.plot(time_sol_doppler_narrow.t, transmission_doppler_narrow)
ax.set_xlabel("time (us)")
ax.set_ylabel('transmission')
ax.set_title("Small Doppler Solution")
```

Text(0.5, 1.0, 'Small Doppler Solution')



## 10.3.5 Compare the size of the beat signals

Here we ignore the starting transient, and normalize the beat signal. As the Doppler broadening is increased, the size of the beat is reduced (for the same optical depth).

```
def normalize_trace(trace,expand=1e2):
    ave = trace[100:].mean()
    return (trace - ave)/ave*expand
```

<matplotlib.legend.Legend at 0x2cf4a780490>



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# **RF HETERODYNE EXAMPLE**

For a more thorough introduction to the core functionality of rydiqule, it may be helpful to look at the Introduction\_to\_Rydiqule.ipynb notebook before this one.

This notebook demonstrates two-tone detection using a Rydberg sensor in the time domain. An RF local oscillator (LO) and signal (sig) are imposed on the Rydberg sensor. This is useful for RF phase detection, and can be used to linearize the detection, as shown below. The main results of this example are:

- 1. we show that the time solver and steady-state solver approximately agree.
- 2. we plot an example of a time response due to RF heterodyne.
- 3. we find the optimum detuning of the Rydberg laser for RF heterodyne, for a given value of LO power.
- 4. we plot the linear dynamic of the RF heterodyning scheme, and show that it is limited by the LO power on the high end. The result is limited by the solver tolerance on the low end.

```
import datetime
##***LAST UPDATE***##
now = datetime.datetime.now()
print(now)
```

```
2023-10-10 16:29:39.706585
```

## 11.1 Imports

```
import numpy as np
import rydiqule as rq
import matplotlib.pyplot as plt
from tqdm import tqdm
```

```
%load_ext autoreload
%autoreload 2
```

# 11.2 Comparing the steady-state and time solver results

This example uses a Cell object, which inherits Sensor. The Cell's purpose is to attach the bare pyhiscs calculations of a Sensor to a real physical atom (Rubidium-85) by default. This allows for specification of quantum numbers for states, meaning rydiqule can calculate things like transition frequencies (using ARC Rydberg) without needing to specify them in the object creation. The details will be discussed further down.

NOTE: The time solver runs more slowly for large transition frequencies, since it makes no rotating wave approximation. Therefore, it is advisable to debug calculations using a transition with a low frequency (ie, very large N). Once calculations are debugged and running well, they can be re-run with the appropriate n-level. Further, ARC calculates dipole moments for the chosen transition. For large n, this calculation is slow, due to the large amount of structure in the atomic wavefunction. However, ARC caches the results, so it only runs slowly the first time. It will likely take several minutes to calculate the add\_states function, the first time, but then will run quickly.

## 11.2.1 The steady-state Cell

## **Define Transitions**

Transitions are defined as dictionaries in a Cell in the same way as they are in a bas Sensor. For the steady-state case, nothing changes. For this example, will observer the response of the system over a series of 200 blue laser detunings.

### Solve the steady state system

We solve a Cell in exactly the same way we solve a Sensor object.

```
ss_solution = rq.solve_steady_state(RbSensor_ss)
print(ss_solution.rho.shape)
```

(200, 15)

## 11.2.2 The time solver Cell

We want to use the same decoherence values

## **Define Couplings**

```
[n,l,j,m] = RbSensor_ss.states_list()[2]
[n2, 12, j2, m2] = RbSensor_ss.states_list()[3]
rf_freq = RbSensor_ss.atom.getTransitionFrequency(n2,l2,j2,n,l,j)*1E-6
def rf_carrier(t):
    return np.cos(2*np.pi*rf_freq*t)#extra factor of 2 to account for no RWA.
```

RbSensor\_time.add\_couplings(red\_laser, blue\_laser, rf\_transition)

## Defining the rf field

The time\_dependence arguments expected to be a python function of a single variable (time in  $\mu s$ ) that returns the field at that time. To match our steady state solution, which had a detuning of 0, we will explicitly define a single-tone field as a function of time that is resonant with our rf transition.

## Solve in the time domain

Internally, the time solver will loop over all detuning values and output the full result. You can use the verbose flag to print its progress to stdout

```
%%time
end_time = 10 #microseconds
sample_num = 10
time_solution = rq.solve_time(RbSensor_time, end_time, sample_num, atol=1e-6,_
ortol=1e-6)
```

```
CPU times: total: 9.98 s
Wall time: 15.7 s
```

RbSensor\_time.couplings.edges[2,3]

```
{'rabi_frequency': 25,
  'transition_frequency': 4138.025828450375,
  'phase': 0,
  'kvec': (0, 0, 0),
  'time_dependence': <function __main__.rf_carrier(t)>,
  'dipole_moment': 14533.336151288706,
  'label': '(2,3)'}
```

## 11.2.3 Comparing results

Now, with results for both steady state and time simulations, we can compare them and see that they match. Note that because the time solution has an extra dimension, we only get the last ([:, -1]) element, since this is effectively the steady-state solution (assuming transient behavior has been damped out by 10  $\mu$ s). Here we also use a function to get the transmission coefficient from the solution quickly by extracting the proper density matrix elements.

```
time_solution.get_transmission_coef().shape
```

(20, 10)

#Modify to include convenience functions and get physical parameters.



## 11.3 Observe a heterodyne beat between the Signal and LO.

The goal of this section is to see the beating behavior in time between the signal and rf local oscillator. This will help see exactly how to observe behavior in the time domain with rydiqule. It will look a lot like other time solves, but we will look at the solution in a different way.

## 11.3.1 Define the RF LO and signal

Just like before, we need a function of time to input into the time solver. This time, instead of just an rf carrier signal, we will define a function that adds a local oscillator of frequency  $\omega_0$  with an "incoming" rf signal of frequency  $\omega_0 + \delta$ . We will also define the time function as the return of another function, which will allow us to make changes to the function quickly if we want to experiment a little.

```
def sig_and_LO(omega_0, delta, beta):
    def fun(t):
        return np.sin(omega_0*t)+beta*np.sin((omega_0+delta)*t)
        return fun
```

```
omega_0 = 2*np.pi*rf_freq
delta = 5
beta = 0.05
```

## 11.3.2 The Sensor

We will use the same RbSensor\_time sensor as before, but change the blue laser to be just a single value. This highlights an important aspect of Sensor. At present, it does not support multiple fields coupling the same pair of levels, but will override an old one with a new one when add\_coupling() is called.

## 11.3.3 Inital conditions

If the init\_cond argument is not supplied to rq.solve\_time, it will calculate the initial condition based on the steady-state solution of the supplied sensor **without** any of the time-dependant fields. Since we define our incoming field and LO in a single function, we will likely end up with a sizeable transient if we use this approach. This is now a great opportunity to demonstrate how to supply an initial condition manually. We calculate our initial condition using the solution to the **steady-state** sensor we defined above. Hopefully, this allows us to see the beat oscillation around the steady-state solution without a large transient from introducing our LO and rf field at the same time.

Solving is done the same way as before, this time solving for 250 points in 10 microseconds

```
RbSensor_ss.add_couplings(blue_laser)
sol_init = rq.solve_steady_state(RbSensor_ss)
sample_num=250
end_time = 10
time_sol_beat = rq.solve_time(RbSensor_time, end_time, sample_num, init_cond=sol_
init.rho)
print(time_sol_beat.rho.shape)
```

(250, 15)

## 11.3.4 Plotting the beat

We now use the get\_transmission\_coef() function again to extract the transmission from the (250, 15)-shaped solution to get a 250 element array we can plot against time. We can see that the system quickly settles into the expected beat frequency of 1 MHZ

```
fig, ax = plt.subplots()
transmission = time_sol_beat.rho[:,3]
ax.plot(time_sol_beat.t, time_sol_beat.get_transmission_coef())
ax.set_xlabel("time (us)");
ax.set_ylabel('transmission');
```



We do have a bit of transient behavior at the start, but we can clearly see the beat expected bead frequency of 5Mrad/s  $\approx$  800kHz.

# 11.4 RF Heterodyne in the Rotating Wave Approximation

We move to a rotating frame by specifying an rf detuning, and writing the coupling in the complex rotating frame. This transformation will greatly speed up the time integration.

```
def sig_LO_RWA(det, beta):
    def fun(t):
        return 1+beta*np.exp(1j*det*t)
    return fun
red_laser = {'states':(0,1), 'rabi_frequency':2*np.pi*0.6, 'detuning':0}
```

```
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```
(continued from previous page)

sol\_init = rq.solve\_steady\_state(RbSensor\_ss)

```
sample_num=250
end_time = 10
time_sol_beat = rq.solve_time(RbSensor_time, end_time, sample_num)
```

```
fig, ax = plt.subplots()
ax.plot(time_sol_beat.t, time_sol_beat.get_transmission_coef())
ax.set_xlabel("time (us)");
ax.set_ylabel('transmission');
```



# 11.5 Find the optimum laser detuning with LO

We again use the same sensor to look at the sensitivity of the sensor as a function of blue laser detuning.

#### 11.5.1 Set up and solve Sensor

susceptibility = time\_sol.rho[:,100:,3]
print(susceptibility.shape)
ptp\_result = np.ptp(susceptibility, axis=-1)

(75, 200)

### 11.5.2 Plotting responsivity versus LO detuning

```
fig, ax = plt.subplots()
ax.plot(detuning_list, ptp_result,'o-')
ax.set_ylabel("responsivity (a.u)")
ax.set_xlabel("Rydberg laser detuning (Mrad/s)")
```

Text(0.5, 0, 'Rydberg laser detuning (Mrad/s)')



This plot shows that, for maximum responsivity, the Rydberg (or probe) laser must be tuned to the side of an Autler-Townes peak, for maximum sensitivity

## 11.6 Test the Linear Dynamic Range

Example testing the linear dynamic range in Heterodyne

#### 11.6.1 Setting the laser parameters

We will set the blue laser detuning to -8 MRad/s, which was roughly the optimal value from the plot above

```
blue_laser = {'states':(1,2), 'rabi_frequency':6.0, 'detuning': -8}
RbSensor_time.add_couplings(blue_laser)
```

#### 11.6.2 Solve parameters

With the detuning set, we can set up everything we need for our scan, namely the solver parameters and list of amplitudes.

```
num_Amps = 50
amp_list = np.logspace(-6,0.2,num_Amps)
sample_num = 300
end_time = 3
```

#### 11.6.3 Running the loop

Now all that is left is get the value we want at each amplitude using a good old python for loop. This could be done with something like a map() function depending on your comfort level with python, but we will be explicit here.

100

→%| →50/50 [00:01<00:00, 48.75it/s]

### 11.6.4 Plotting the dynamic range

```
fig, ax = plt.subplots()
ax.plot(amp_list, pk_to_pk_result,'o-')
ax.set_ylabel("responsivity (a.u)")
ax.set_xlabel("Probe relative amplitude")
ax.set_xscale('log')
ax.set_yscale('log')
```



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# **PYTHON MODULE INDEX**

#### r

rydiqule, 51 rydiqule.atom\_utils,51 rydiqule.cell,54 rydiqule.doppler\_utils,82 rydiqule.experiments,92 rydiqule.rydiqule\_utils,94 rydiqule.sensor,95 rydiqule.sensor\_solution, 119 rydiqule.sensor\_utils,126 rydiqule.slicing, 130 rydiqule.slicing.slicing, 130 rydiqule.solvers,134 rydiqule.stack\_solvers,137 rydiqule.stack\_solvers.cyrk\_solver, 137 rydiqule.stack\_solvers.nbkode\_solver, 139 rydiqule.stack\_solvers.nbrk\_solver, 140 rydiqule.stack\_solvers.scipy\_solver, 141 rydiqule.timesolvers, 142

## INDEX

#### Symbols

\_init\_\_\_() (rydiqule.cell.Cell method), 54 (rydiqule.doppler\_utils.DirectMethod \_init\_\_() method), 86 (rydiqule.doppler\_utils.IsoPopMethod \_init\_ \_() method), 88 (rydiqule.doppler\_utils.SplitMethod \_init\_\_() method), 89 \_init\_\_() (rydiqule.doppler\_utils.UniformMethod method), 91 \_init\_\_() (rydiqule.sensor.Sensor method), 96 (rydiqule.sensor\_solution.Solution \_init\_\_() method), 119 \_add\_coupling() (rydiqule.cell.Cell method), 56 \_add\_coupling() (rydiqule.sensor.Sensor method), 98 \_add\_decay\_to\_graph() (rydiqule.cell.Cell method), 57 \_add\_state() (rydiqule.cell.Cell method), 57 \_add\_states() (rydiqule.cell.Cell method), 57 \_beam\_area (rydiqule.sensor\_solution.Solution attribute), 121 \_cell\_length (rydiqule.sensor\_solution.Solution attribute), 121 \_collapse\_mesh() (rydiqule.cell.Cell method), 57 \_collapse\_mesh() (rydiqule.sensor.Sensor method), 98 (rydiqule.cell.Cell \_coupling\_with\_label() method), 57 \_coupling\_with\_label() (rydiqule.sensor.Sensor method), 98 \_eta (rydiqule.sensor\_solution.Solution attribute), 121 \_kappa (rydiqule.sensor\_solution.Solution attribute), 121\_probe\_freq (rydiqule.sensor\_solution.Solution attribute), 121 \_probe\_rabi (rydiqule.sensor\_solution.Solution attribute), 121 \_probe\_tuple (rydiqule.sensor\_solution.Solution attribute), 121 \_remove\_edge\_data() (rydiqule.cell.Cell method), 57 (rydiqule.sensor.Sensor \_remove\_edge\_data() method), 98 \_stack\_shape() (rydiqule.cell.Cell method), 58 \_stack\_shape() (rydiqule.sensor.Sensor method),

#### 99

- \_states\_valid() (rydiqule.cell.Cell method), 58 \_states\_valid() (rydiqule.sensor.Sensor method), 99
- \_validate\_qnums() (rydiqule.cell.Cell method), 58

#### A

- about () (in module rydiqule\_rydiqule\_utils), 94
- add\_coupling() (rydiqule.cell.Cell method), 58
- add\_couplings() (rydiqule.cell.Cell method), 61
- add\_decoherence() (rydiqule.cell.Cell method), 61
  add\_decoherence() (rydiqule.sensor.Sensor
- method), 101
  add\_energy\_shift() (rydiqule.cell.Cell method),
- 62
- add\_energy\_shift() (rydiqule.sensor.Sensor method), 102
- add\_energy\_shifts() (rydiqule.sensor.Sensor method), 102
- add\_self\_broadening() (rydiqule.cell.Cell method), 62
- add\_self\_broadening() (rydiqule.sensor.Sensor method), 102
- add\_states() (rydiqule.cell.Cell method), 63
- add\_transit\_broadening() (rydiqule.sensor.Sensor method), 103
- apply\_doppler\_weights() (in module rydiqule.doppler\_utils), 82
- ATOMS (*in module rydiqule.atom\_utils*), 52
- axis\_labels (rydiqule.sensor\_solution.Solution attribute), 121
- axis\_labels() (rydiqule.cell.Cell method), 64
- axis\_values (rydiqule.sensor\_solution.Solution attribute), 121

#### В

- BASE\_EDGE\_KEYS (in module rydiqule.sensor), 95
- BASE\_SCANNABLE\_KEYS (in module rydiqule.sensor), 95
- basis\_size (rydiqule.cell.Cell property), 65
- basis\_size (rydiqule.sensor.Sensor property), 105
- beam\_area (*rydiqule.cell.Cell attribute*), 65
- beam\_area (rydiqule.sensor.Sensor attribute), 105
- beam\_area (rydiqule.sensor\_solution.Solution property), 122

# С

- calc\_eta() (in module rydiqule.atom\_utils), 53
- calc\_kappa() (in module rydiqule.atom\_utils), 53
  Cell (class in rydiqule.cell), 54
- cell\_length (rydiqule.cell.Cell attribute), 65
- cell\_length (rydiqule.sensor.Sensor attribute), 105
- cell\_length(rydiqule.sensor\_solution.Solution property), 122
- clear() (rydiqule.doppler\_utils.DirectMethod method), 87

- compute\_grid() (in module rydiqule.slicing.slicing),
  131
- copy() (rydiqule.doppler\_utils.DirectMethod method), 87
- copy() (rydiqule.doppler\_utils.IsoPopMethod method), 88
- copy() (rydiqule.doppler\_utils.SplitMethod method), 90
- copy() (rydiqule.doppler\_utils.UniformMethod method), 91
- copy() (rydiqule.sensor\_solution.Solution method), 122
- couplings (rydiqule.sensor\_solution.Solution attribute), 122
- couplings\_with() (rydiqule.cell.Cell method), 65
- couplings\_with() (rydiqule.sensor.Sensor method), 105
- cyrk\_solve() (in module rydiqule.stack\_solvers.cyrk\_solver), 138

# D

- D1\_states() (in module rydiqule.atom\_utils), 52
- D2\_states() (in module rydiqule.atom\_utils), 53
- decoherence\_matrix() (rydiqule.cell.Cell
   method), 66
- deepcopy() (rydiqule.sensor\_solution.Solution method), 122

- DirectMethod (class in rydiqule.doppler\_utils), 86
- dm\_basis (rydiqule.sensor\_solution.Solution attribute),
  122
- dm\_basis() (rydiqule.cell.Cell method), 66
- dm\_basis() (rydiqule.sensor.Sensor method), 107
- doppler\_classes (rydiqule.sensor\_solution.Solution attribute), 122
- doppler\_classes() (in module rydiqule.doppler\_utils), 83
- doppler\_velocities (rydiqule.doppler\_utils.DirectMethod attribute), 87

#### Е

- eta (rydiqule.cell.Cell property), 67
- eta (rydiqule.sensor.Sensor attribute), 107
- eta (rydiqule.sensor\_solution.Solution property), 122

#### F

### G

- gaussian3d() (in module rydiqule.doppler\_utils), 85
  generate\_doppler\_shift\_eom() (in module
- rydiqule.doppler\_utils), 85
  generate\_eom() (in module rydiqule.sensor\_utils),
  127
- generate\_eom\_time() (in module rydiqule.timesolvers), 143

- get () (rydiqule.doppler\_utils.SplitMethod method), 90
- get () (rydiqule.doppler\_utils.UniformMethod method), 91
- get () (rydiqule.sensor\_solution.Solution method), 122
- get\_basis\_transform() (in module rydiqule.sensor\_utils), 128
- get\_cell\_hfs\_coefficient() (rydiqule.cell.Cell method), 67

- get\_cell\_tansition\_frequency() (rydiqule.cell.Cell method), 68 get\_coupling\_rabi() (rydiqule.cell.Cell method), 68 get\_coupling\_rabi() (rydiqule.sensor.Sensor *method*), 107 get\_couplings() (rydiqule.cell.Cell method), 68 get\_couplings() (rydiqule.sensor.Sensor method), 107 get\_doppler\_equations() (in module rydiqule.doppler\_utils), 85 get\_doppler\_shifts() (rydiqule.cell.Cell method), 69 get\_doppler\_shifts() (rydiqule.sensor.Sensor *method*), 108 get\_hamiltonian() (rydiqule.cell.Cell method), 69 (rydiqule.sensor.Sensor get\_hamiltonian() method), 108 get\_hamiltonian\_diagonal() (rydiqule.cell.Cell method), 70 get\_hamiltonian\_diagonal() (rydiqule.sensor.Sensor method), 109 get\_OD() (in module rydiqule.experiments), 92 get\_OD() (rydiqule.sensor\_solution.Solution method), 122 get\_parameter\_mesh() (rydiqule.cell.Cell method), 70 get\_parameter\_mesh() (rydiqule.sensor.Sensor method), 109 get\_phase\_shift() (in module rydiqule.experiments), 92 get\_phase\_shift() (rydiqule.sensor\_solution.So*lution method*), 123 get\_qnums() (rydiqule.cell.Cell method), 71 get\_rho\_ij() (in module rydiqule.sensor\_utils), 128 get\_rho\_populations() (in module rydiqule.sensor\_utils), 129 (rydiqule.cell.Cell get\_rotating\_frames() method), 71 get\_rotating\_frames() (rydiqule.sensor.Sensor *method*), 110 get\_slice\_num() (in module rydiqule.slicing.slicing), 132 get\_slice\_num\_t() (in module rydiqule.slicing.slicing), 132 get\_snr() (in module rydiqule.experiments), 93 get\_solution\_element() (in module rydiqule.experiments), 94 get\_solution\_element() (rydiqule.sensor\_solution.Solution method), 123
- get\_state\_num() (rydiqule.cell.Cell method), 71
- get\_susceptibility() (in module rydiqule.experiments), 94
- get\_susceptibility() (rydiqule.sensor\_solution.Solution method), 124
- get\_time\_couplings() (rydiqule.cell.Cell method), 72
- get\_time\_couplings() (rydiqule.sensor.Sensor

method), 110

- get\_time\_dependence() (rydiqule.cell.Cell *method*), 73
- get\_time\_dependence() (rydiqule.sensor.Sensor *method*), 111
- get\_time\_hamiltonians() (rydiqule.cell.Cell *method*), 73
- get\_time\_hamiltonians() (rydiqule.sensor.Sensor method), 112
- get\_transition\_frequencies() (rydiqule.cell.Cell method), 74
- get\_transition\_frequencies() (rydiqule.sensor.Sensor method), 113
- get\_transmission\_coef() (in module rydiqule.experiments), 94
- get\_transmission\_coef() (rydigule.sensor\_solution.Solution method), 124
- get\_value\_dictionary() (rydiqule.cell.Cell method), 74
- get\_value\_dictionary() (rydiqule.sensor.Sensor method), 113

- init\_cond (rydiqule.sensor\_solution.Solution attribute), 124
- IsoPopMethod (class in rydiqule.doppler\_utils), 88
- (rydiqule.doppler\_utils.DirectMethod items() method), 87
- items() (rydiqule.doppler\_utils.IsoPopMethod method), 88
- items() (rydiqule.doppler\_utils.SplitMethod method), 90
- (rydiqule.doppler\_utils.UniformMethod items() method), 91
- items() (rydiqule.sensor\_solution.Solution method), 124

## Κ

- kappa (rydiqule.cell.Cell property), 75
- kappa (rydiqule.sensor.Sensor attribute), 113
- kappa (rydiqule.sensor\_solution.Solution property), 125
- keys() (rydiqule.doppler\_utils.DirectMethod method), 87
- keys() (rydiqule.doppler\_utils.IsoPopMethod method), 88
- (rydiqule.doppler utils.SplitMethod method), keys() 90
- (rydiqule.doppler\_utils.UniformMethod keys() method), 91
- (rydiqule.sensor\_solution.Solution method), keys() 125

level\_ordering() (rydiqule.cell.Cell method), 75

#### Μ

make\_real() (in module rydigule.sensor\_utils), 129

matrix\_slice() (in module rydiqule.slicing.slicing), pop() (rydiqule.sensor\_solution.Solution method), 125 133 (rydiqule.doppler\_utils.DirectMethod popitem() memory\_size() (in module rydiqule.slicing.slicing), method), 87 134 (rydiqule.doppler\_utils.IsoPopMethod popitem() method (rydiqule.doppler\_utils.DirectMethod attribute), method), 89 87 (rydiqule.doppler\_utils.SplitMethod popitem() (rydiqule.doppler\_utils.IsoPopMethod method atmethod), 90 popitem() (rydiqule.doppler\_utils.UniformMethod tribute), 89 method (rydiqule.doppler\_utils.SplitMethod attribute), method), 92 90 (rydiqule.sensor\_solution.Solution popitem() method (rydiqule.doppler\_utils.UniformMethod atmethod), 125 probe\_freq (rydiqule.cell.Cell property), 76 tribute), 91 module probe\_freq (rydiqule.sensor.Sensor attribute), 113 rydiqule, 51 probe\_freq (rydiqule.sensor\_solution.Solution proprydiqule.atom\_utils, 51 erty), 125 rydiqule.cell,54 probe\_rabi (rydiqule.sensor\_solution.Solution proprydiqule.doppler\_utils,82 erty), 125 rydiqule.experiments, 92 probe\_tuple (rydiqule.cell.Cell attribute), 76 rydiqule.rydiqule\_utils,94 probe\_tuple (rydiqule.sensor.Sensor attribute), 114 rydiqule.sensor,95 probe\_tuple (rydiqule.sensor\_solution.Solution proprydiqule.sensor\_solution, 119 erty), 125 rydiqule.sensor\_utils, 126 R rydiqule.slicing, 130 rydiqule.slicing.slicing, 130 rydiqule.solvers,134 130 rydiqule.stack\_solvers,137 rydiqule.stack\_solvers.cyrk\_solver, rho\_ij() (rydiqule.sensor\_solution.Solution method), 137 125rydiqule.stack\_solvers.nbkode\_solverg version 139 attribute), 125 rydiqule.stack\_solvers.nbrk\_solver, rydiqule 140 module, 51 rydiqule.stack\_solvers.scipy\_solver,rydiqule.atom\_utils 141 module, 51 rydiqule.timesolvers, 142

## Ν

| n_coherent (rydiqule.doppler_utils.SplitMethod at-             |
|--|
| tribute), 90   |
| n_doppler (rydiqule.doppler_utils.SplitMethod at-              |
| tribute), 90   |
| n_isopop (rydiqule.doppler_utils.IsoPopMethod                  |
| attribute), 89   |
| n_uniform (rydiqule.doppler_utils.UniformMethod at-            |
| tribute), 91   |
| nbkode_solve() (in module ry-                                  |
| diqule.stack_solvers.nbkode_solver), 139                       |
| nbrk_solve() (in module ry-                                    |
| diqule.stack_solvers.nbrk_solver), 140                         |
| -  |
| P  |
| <pre>pop() (rydiqule.doppler_utils.DirectMethod method),</pre> |
| <pre>pop() (rydiqule.doppler_utils.IsoPopMethod method),</pre> |
|  |

- pop() (rydiqule.doppler\_utils.SplitMethod method), 90
  pop() (rydiqule.doppler\_utils.UniformMethod method),
- 91
- remove\_ground() (in module rydiqule.sensor\_utils), rho (rydiqule.sensor\_solution.Solution attribute), 125 (rydiqule.sensor\_solution.Solution rydiqule.cell module, 54 rydiqule.doppler\_utils module, 82 rydiqule.experiments module, 92 rydiqule.rydiqule\_utils module, 94 rydiqule.sensor module,95 rydiqule.sensor\_solution module, 119 rydigule.sensor utils module, 126 rydiqule.slicing module, 130 rydiqule.slicing.slicing
- module,130 rydiqule.solvers
- module, 134
- rydiqule.stack\_solvers
- module,137
- rydiqule.stack\_solvers.cyrk\_solver module,137

rydiqule.stack\_solvers.nbkode\_solver module, 139 rydiqule.stack\_solvers.nbrk\_solver module, 140 rydiqule.stack\_solvers.scipy\_solver module, 141 rydiqule.timesolvers module, 142

# S

scale\_dipole() (in module rydiqule.sensor\_utils),
130

- scipy\_solve() (in module rydiqule.stack\_solvers.scipy\_solver), 141
- Sensor (class in rydiqule.sensor), 96

set\_experiment\_values() (rydiqule.cell.Cell
 method), 76

set\_experiment\_values() (rydiqule.sensor.Sensor method), 114

set\_gamma\_matrix() (rydiqule.sensor.Sensor method), 114

setdefault() (rydiqule.doppler\_utils.Uniform-Method method), 92

Solution (class in rydiqule.sensor\_solution), 119

solve\_eom\_stack() (in module rydiqule.timesolvers), 143

- solve\_steady\_state() (in module rydiqule.solvers), 135
- solve\_time() (in module rydiqule.timesolvers), 144
- spatial\_dim() (rydiqule.cell.Cell method), 77

- SplitMethod (class in rydiqule.doppler\_utils), 89
- states (rydiqule.cell.Cell property), 77
- states (rydiqule.sensor.Sensor property), 115
- states\_list() (rydiqule.cell.Cell method), 78
- states\_with\_label() (rydiqule.sensor.Sensor method), 115
- steady\_state\_solve\_stack() (in module rydiqule.solvers), 137

## Т

t (rydiqule.sensor\_solution.Solution attribute), 125

## U

UniformMethod (class in rydiqule.doppler\_utils), 91

- unzip\_parameters() (rydiqule.cell.Cell method),
  79
- unzip\_parameters() (rydiqule.sensor.Sensor method), 116
- update() (rydiqule.doppler\_utils.DirectMethod method), 87
- update() (rydiqule.doppler\_utils.IsoPopMethod method), 89
- update() (rydiqule.doppler\_utils.SplitMethod method), 90
- update() (rydiqule.sensor\_solution.Solution method), 125

### V

## W

- width\_coherent (rydiqule.doppler\_utils.Split-Method attribute), 90
- width\_doppler (rydiqule.doppler\_utils.Uniform-Method attribute), 92

### Ζ